DEMO MANUAL DC2192B

LTC6806 isoSPI Fuel Cell Monitor

DESCRIPTION

Demonstration circuit 2192B is a fuel cell monitor featuring the LTC[®]6806, a 36-channel fuel cell monitor. Multiple boards can be linked through a 2-wire isolated serial interface (isoSPI[™]) to monitor a long series of cells in a stack. The DC2192B demo circuit also features reversible isoSPI enabling a redundant communication path. The PCB, components and DuraClik connectors are optimized for low EMI susceptibility and emissions.

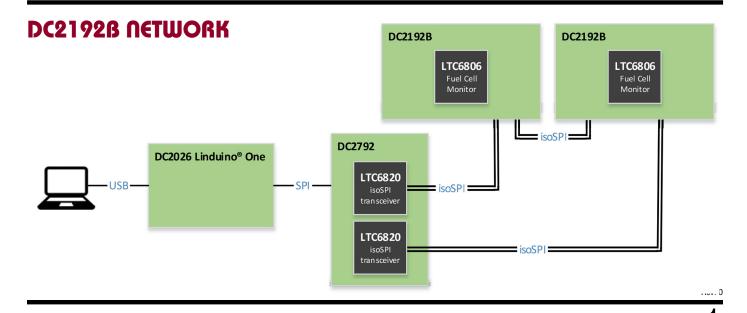
The DC2192B can communicate to a PC by connecting a DC2792B dual master isoSPI together with DC2026 Linduino[®] One. The DC2026 must be loaded with the appropriate program (called a **sketch**) to control the battery stack monitor IC and receive data through a USB serial port. The DC2026C provides a standard SPI interface which can be translated to isoSPI and then connected to a DC2192B isoSPI port (J3/J4 connector). The DC2792B provides two SPI-isoSPI channels for reversible operation.

Design files for this circuit board are available.

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PERFORMANCE SUMMARY Specifications are at $T_A = 25^{\circ}C$

PARAMETER	MIN	ТҮР	MAX	UNITS
V^+ Supply Voltage (Relative to V ⁻) where TME Specifications are Met	4.75	5.0	5.5	V
Input Voltage Range, C25 – C36 to V ⁻	-5.0		140	V
Input Voltage Range, C14 – C24 to V ⁻	-5.0		95	V
Input Voltage Range, C0 – C13 to V ⁻	-5.0		60	V
V _{REF1} 1st Reference Voltage, No Load	2.700	3.058	3.300	V
V _{REF2} 2nd Reference Voltage, 1mA Load to V ⁻	2.200	2.500	2.700	V
V _{BIAS} I _{BIAS} Voltage, READY/ACTIVE State	1.9	2.0	2.1	V
CPIN Input Measurement Range with HIRNG = 0	-2.5		2.5	V
CPIN Input Measurement Range with HIRNG = 1	-5.0		5.0	V
Cell Count			36	



HARDWARE SETUP

Mating Connector for J1

The mating female receptacle connector DB-37 female, (see Figure 2) is not included to mate with the J1 male plug connector DB-37 male (see Figure 1). The connector must be purchased separately from an electronics component supplier such as Digikey or Mouser Electronics.

Recommended DB-37 Female or Equivalent to Mate with DC2192B J1 DB-37 Male

For PCB-to-PCB Connection

- TE Connectivity 5747847-4 Female D-Sub-to-PCB (DB-37 Female)
 - Female Receptacle Board-to-Board Connector
 - Receptacle Assembly, Size 4, 37 Position
 - Right Angle, Front Metal Shell, 0.318 Series
 - 0.026" Diameter Posts, Board Locks, Amplimite HD-20

For PCB-to-Wire connection:

- TE Connectivity 205167-1 Female D-Sub-to-Cable (DB-37 female)
 - Female Receptacle Cable-to-Cable Connector
 - Receptacle Assembly, Size 4, 37 Position
 - Series 109, Amplimite HD-20

Wiring J1 Connector

The DC2192B demo board connector pinout is critical. Correct wiring must be followed to avoid the risk of damaging the demo board.

When connected to a fuel cell stack, power for the DC2192B is provided by an external power supply. Before plugging the DB-37 female connector (not included) onto DC2192B J1 DB-37 male connector, first carefully wire the fuel cell connections or resistors onto the DB-37 female connector. These connections provide input stimulus for the fuel cell monitor IC. Refer to the DC2192B 36 Resistor Connection section.

Fuel cell voltages are wired to J1 starting from position 19 (most negative potential of the group). Please refer to the appropriate demo board J1 connector pinout in Table 1.

Alternatively, resistors can be used to simulate fuel cell-voltages. 100Ω 1W or equivalent resistors are recommended because 100Ω (or lower values) typically will not induce measurement errors and the 1W (or greater rating) will keep the resistor temperatures low preventing power dissipation damage.

DC2192B 36 Resistor Connection

Carefully connect thirty-six (36) 100Ω resistors onto the DB-37 female receptacle connector between each CPIN input from position 19 to position 1 as shown in Table 1, Figure 2 and Figure 3. Provide a stack-equivalent power supply connection to position 1 (positive) and position 19 (negative). The power supply may be adjusted to provide the desired nominal fuel cell voltage (e.g. 25.2V will be 0.7V per cell).

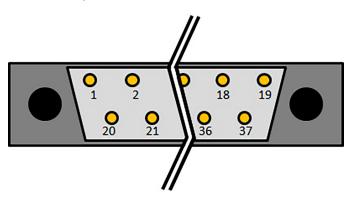


Figure 1. DC2192B J1 D-SUB37 (DB-37) Front Male Pin View

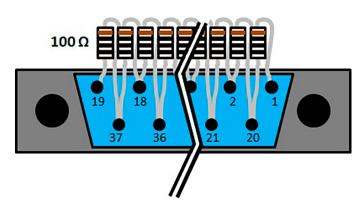


Figure 2. Resistor Divider String Connection D-SUB37 Front Female Receptacles/Sockets View—Shown for Connection Clarity—Actual Physical Connection by PCB or Wire will Be Different

HARDWARE SETUP

Table 1. J1 Pinout

J1 PIN	CPIN INPUT	J1 PIN	CPIN INPUT
19	C0/GND	10	C18
37	C1	28	C19
18	C2	9	C20
36	C3	27	C21
17	C4	8	C22
35	C5	26	C23
16	C6	7	C24
34	C7	25	C25
15	C8	6	C26
33	C9	24	C27
14	C10	5	C28
32	C11	23	C29
13	C12	4	C30
31	C13	22	C31
12	C14	3	C32
30	C15	21	C33
11	C16	2	C34
29	C17	20	C35
		1	C36

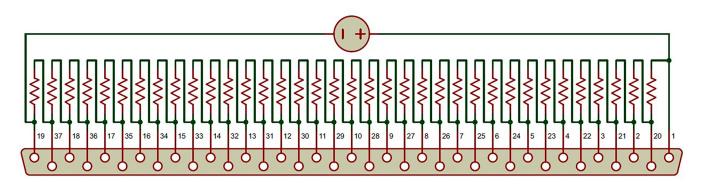


Figure 3. Resistor Divider String Connection D-SUB37 (DB-37) Female Receptacles Schematic of Figure 2. Includes the Power Supply Connection

Rev. 0

isoSPI is the only communication option to DC2192B. Due to the custom EMI optimized isoSPI cable with DuraClik connectors, it is highly recommended to use DC2792B Dual Master isoSPI demo board or equivalent for easy plug-and-play operation. The DC2792B Dual Master isoSPI demo board can be connected as a typical single-ended isoSPI bus master or to both ends of a reversible configuration with two isoSPI bus masters. Refer to DC2792B demo manual for usage details.

DC2792B to DC2192B Typical isoSPI Connection

A typical isoSPI connection begins with the isoSPI master connected to the first (or **bottom**) DC2192B. Additional DC2192B boards can be daisy-chained onto the isoSPI bus. Communication begins from the first (or **bottom**) DC2192B then to the next **upper** DC2192B and, finally, to the last (or **top**) DC2192B.

Figure 4 shows the following connections for two boards on a stack interfaced to a PC.

- 1. Connect a USB cable from the PC USB port to the DC2026 J5 connector.
- 2. Connect DC2026 to DC2792B Dual Master isoSPI demo board.
- a. Connect a 14-pin ribbon cable from the DC2026 J1 header to the DC2792B J1 header.
- 3. Connect DC2792B to DC2192B in isoSPI mode. This DC2192B is the first (or **bottom**) board of the stack.
 - a. Connect a 2-wire twisted-pair patch cable from the DC2792B J2 MAIN DuraClik connector to the **bot-tom** DC2192B J3 isoSPI A DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

b. Connect an external 3.3V – 15V power supply to the **bottom** DC2192B VEXT⁺ E2 and VEXT⁻ E1 turrets.

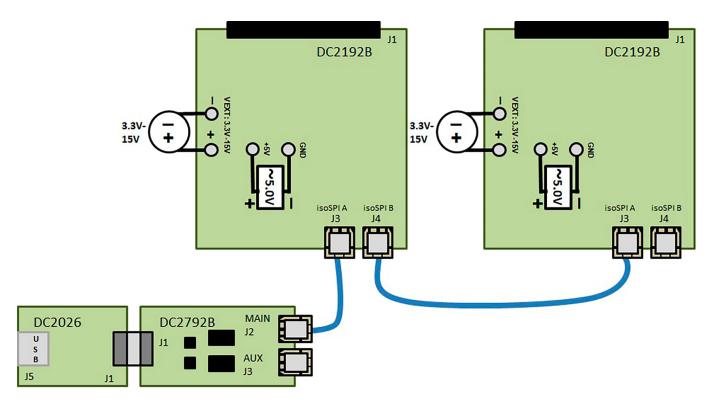


Figure 4. DC2792B Typical isoSPI Connection to the Bottom DC2192B in a Two-Board DC2192B Stack

- 4. Connect or daisy-chain the DC2192B to another DC2192B in isoSPI mode. This DC2192B is the last (or top) board of a two-board stack. More DC2192B **upper** boards can be daisy-chained together in the same manner.
 - a. Connect a 2-wire twisted-pair patch cable from the bottom DC2192B J4 isoSPI B DuraClik connector to the next upper or top DC2192B J3 isoSPI A DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

b. Connect an external 3.3V – 15V power supply to the next upper or top DC2192B VEXT+ E2 and VEXT⁻ E1 turrets.

- 5. **CAUTION!** The fuel cell voltage must be connected correctly to prevent damage to the DC2192B. Refer to Table 1 and Figure 2 then confirm that the fuel cell voltage connections to the DB-37 female matches the DC2192B J1 pinout.
 - a. Plug the DB-37 female receptacle connector onto the J1 fuel cell voltage DB-37 male plug connector.
- 6. Refer to Software Setup section of this demo manual to properly setup the PC with the Arduino IDE software to allow communication to the DC2192B boards.

DC2792B to DC2192B Reverse isoSPI Connection

A reverse isoSPI connection begins with the isoSPI Master connected to the last (or top) DC2192B. Additional DC2192B boards can be daisy-chained onto the isoSPI bus. Communication begins from the last (or **top**) DC2192B then to the next lower DC2192B and, finally, to the first (or bottom) DC2192B.

Figure 5 shows the following connections for two boards on a stack interfaced to a PC.

1. Connect a USB cable from the PC USB port to the DC2026 J5 connector.

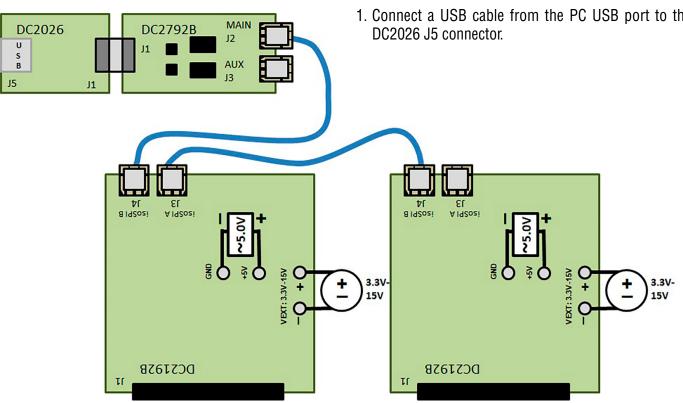


Figure 5. DC2792B Reverse isoSPI Connection to the Top DC2192B in a Two-Board DC2192B Stack

- 2. Connect DC2026 to DC2792B Dual Master isoSPI demo board.
 - a. Connect a 14-pin ribbon cable from the DC2026 J1 header to the DC2792B J1 header.
- 3. Connect DC2792B to DC2192B in isoSPI mode. This DC2192B is the last (or **top**) board of a two-board stack.
 - a. Connect a 2-wire twisted-pair patch cable from the DC2792B J2 MAIN DuraClik connector to the **top** DC2192B J4 isoSPI B DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

- b. Connect an external 3.3V 15V power supply to the **top** DC2192B VEXT⁺ E2 and VEXT⁻ E1 turrets.
- Connect or daisy-chain the DC2192B to another DC2192B in isoSPI mode. This DC2192B is the first (or bottom) board of a two-board stack. More DC2192B lower boards can be daisy-chained together in the same manner.
 - a. Connect a 2-wire twisted-pair patch cable from the **top** DC2192B J3 isoSPI A DuraClik connector to the next **lower** or **bottom** DC2192B J4 isoSPI B DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

- b. Connect an external 3.3V 15V power supply to the next **lower** or **bottom** DC2192B VEXT⁺ E2 and VEXT⁻ E1 turrets.
- CAUTION! The fuel cell voltage must be connected correctly to prevent damage to the DC2192B. Refer to Table 1 and Figure 2 then confirm that the fuel cell voltage connections to the DB-37 female matches the DC2192B J1 pinout.

- a. Plug the DB-37 female receptacle connector onto the J1 fuel cell voltage DB-37 male plug connector.
- Refer to the Software Setup section of this demo manual to properly setup the PC with the Arduino IDE software to allow communication to the DC2192B boards.

DC2792B TO DC2192B Redundant isoSPI Connection

A redundant isoSPI connection begins with the primary (or **main**) isoSPI Master connected to the first (or **bottom**) DC2192B and has a backup auxiliary (or **aux**) isoSPI Master connected to the last (or **top**) DC2192B. Additional DC2192B boards can be daisy-chained between the two isoSPI masters on the isoSPI bus. Primary (or **main**) communication begins from the first (or **bottom**) DC2192B then to the next **upper** DC2192B and, finally, to the last (or **top**) DC2192B. The backup auxiliary (or **aux**) communication begins in the reverse direction to provide coverage when a possible isoSPI daisy-chain break occurs.

Figure 6 shows the following connections for two boards on a stack interfaced to a PC.

- 1. Connect a USB cable from the PC USB port to the DC2026 J5 connector.
- 2. Connect DC2026 to DC2792B Dual Master isoSPI demo board.
 - a. Connect a 14-pin ribbon cable from the DC2026 J1 header to the DC2792B J1 header.
- 3. Connect DC2792B primary (or **main**) isoSPI master to the first (or **bottom**) DC2192B board of the stack.
 - a. Connect a 2-wire twisted-pair patch cable from the DC2792B J2 MAIN DuraClik connector to the **bot-tom** DC2192B J3 isoSPI A DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

b. Connect an external 3.3V – 15V power supply to the **bottom** DC2192B VEXT⁺ E2 and VEXT⁻ E1 turrets.

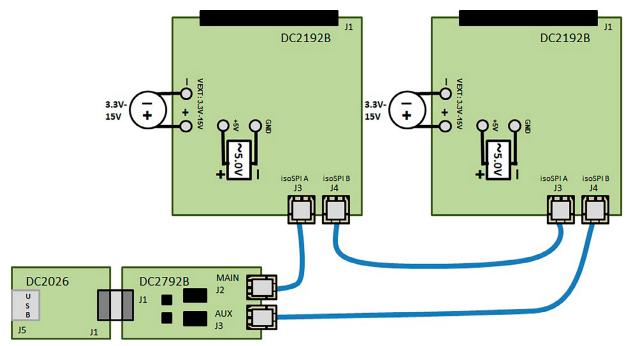


Figure 6. DC2792B Redundant isoSPI Connections to the Bottom and Top DC2192B in a Two-Board DC2192B Stack

- Connect or daisy-chain the DC2192B to another DC2192B in isoSPI mode. This DC2192B is the last (or top) board of a two-board stack. More DC2192B upper boards can be daisy-chained together in the same manner.
 - a. Connect a 2-wire twisted-pair patch cable from the **bottom** DC2192B J4 isoSPI B DuraClik connector to the next **upper** or **top** DC2192B J3 isoSPI A DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

c. Connect an external 3.3V – 15V power supply to the **upper** or **top** DC2192B VEXT⁺ E2 and VEXT⁻ E1 turrets.

- 5. Connect the DC2792B auxiliary (or **aux**) isoSPI Master to the last (or **top**) DC2192B board of the stack.
 - a. Connect a 2-wire twisted-pair patch cable from the DC2792B J3 AUX DuraClik connector to the **top** DC2192B J4 isoSPI B DuraClik connector.

CAUTION! The 2-wire twisted-pair patch cable with the DuraClik end plugs have 1mm thick center locking tabs on the wiring side that must be pressed down to release from the DuraClik receptacles. Failure to do so may damage the cable and prevent board-to-board isoSPI communication.

- CAUTION! The fuel cell voltage must be connected correctly to not damage the DC2192B. Refer to Table 1 and Figure 2, then confirm that the fuel cell voltage connections to the DB-37 female matches the DC2192B J1 pinout.
 - a. Plug the DB-37 female receptacle connector onto the J1 fuel cell voltage DB-37 male plug connector.
- 7. Refer to the Software Setup section of this demo manual to properly setup the PC with the Arduino IDE software to allow communication to the DC2192B boards.

The DC2192B can be controlled by the DC2026 Linduino One board together with DC2792B Dual isoSPI Master or equivalent isoSPI transceiver. The DC2026 is part of the Arduino compatible Linduino platform that provides example code that will demonstrate how to control the multicell battery stack monitor ICs. Compared to most Arduino compatible microcontroller boards, the DC2026 offers conveniences such as an isolated USB connection to the PC, built-in SPI MISO line pull-up to properly interface with the battery stack monitor IC opendrain SDO, and an easy ribbon cable connection for SPI communication through the DC2792B 14-pin QuikEval[™] J1 connector.

Arduino IDE Setup

- 1. Download then install the Arduino IDE onto the PC. Detailed instructions can be found under the quick start tab.
- Set the Arduino IDE to open BMS Sketchbooks. From within the Arduino IDE, click on File menu select Preferences. Then under Sketchbook location: select Browse and locate the path to the extracted LTSketchbook.zip file that was downloaded (see Figure 7).
- 3. Close then re-open the Arduino IDE to enable the use of the Sketchbook Location that was previously set.

🥺 sketch_july11a Arduino 1.8.1			-	- 🗆 ×	
File Edit Sketch Tools Help	Preferences	×			
	Settings Network			P	
sketch_july11a	Sketchbook location:				
<pre>sketch_july11a 1 void setup() { 2 // put your setup code here, 3 4 } 5 6 void loop() { 7 // put your main code here, t 8 9 }</pre>	Sketchbook location: C:EXAMPLE\LTSketchbook Editor language: System Default (requires restart of Arduino) Editor font size: 13 Interface scale: Automatic 100 % (requires restart of Arduino) Show verbose output during: complation upload Compler warnings: None Compler warnings: None Compler warnings: None Compler warnings: Code Folding Verify code after upload Use external editor C Check for updates on startup Vupdate sketch files to new extension on save (.pde -> .ino) Save when verifying or uploading Additonal Boards Manager URLs: More preferences can be edited directly in the file C:\Users\EGonzale\AppData\Local\Arduino 15\preferences.txt (edit only when Arduino is not running)	Browse			^
					~
	0	K Cancel			
1			Arduino/Gen	uino Uno on COM6	Γ

Figure 7. Sketchbook Location Path

- 4. Select the correct COM port to allow communication to DC2026 through USB. Under the **Tools** menu, select **Port** → Select the highest number **COMxx**. There may be more than one option—DC2026 is usually the highest COM port number. The PC screenshot (Figure 8) used in this example shows the DC2026 connected to COM6.
- Select the correct Arduino compatible microcontroller board. Under the Tools menu, select Board → Arduino/Genuino Uno with the "•" black dot symbol (see Figure 9).

ile Edit Sketch To	ols Help			
sketch_jul11a	Auto Format Archive Sketch Fix Encoding & Reload	Ctrl+T		
1 void setup 2 // put y 3	Serial Monitor Serial Plotter	Ctrl+Shift+N Ctrl+Shift+L	'	
4 } 5 6 void loop(WiFi101 Firmware Updater Board: "Arduino/Genuino U	no"	•	
7 // put y	Port: "COM6"			Serial ports
8 9 }	Get Board Info		 Image: A start of the start of	COM6
	Programmer: "AVRISP mkII" Burn Bootloader		F	

Figure 8. Selecting the Correct COM

e Edit Sketch To	ols Help		
sketch_jul11a	Auto Format Ctrl+T Archive Sketch Fix Encoding & Reload		
1 void setup 2 // put y 3	Serial Monitor Ctrl+S Serial Plotter Ctrl+S		
4 }	WiFi101 Firmware Updater		
6 void loop(Board: "Arduino/Genuino Uno"	,	Boards Manager
7 // put y 8 9 }	Port: "COM6" Get Board Info	1	Arduino AVR Boards Arduino Yún
	Programmer: "AVRISP mkII"		Arduino/Genuino Uno
Burn Bootloader			Arduino Duemilanove or Diecimila

Figure 9. Selecting the Compatible Microcontroller Board

- 6. Open one of the programs or sketches associated with the DC2192. In this example LTC6806 sketch will be opened. Under the File menu, select Sketchbook → Part Number → 6000 → 6806 → DC2192 (see Figure 10).
- Upload the DC2192 sketch onto the DC2026 by clicking on the Upload button on the top left corner. When this process is completed there will be a Done uploading message on the bottom left corner (see Figure 11).

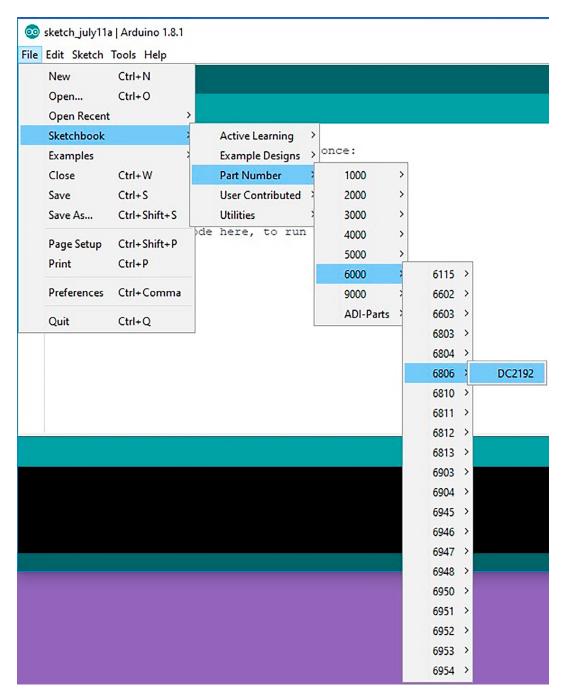


Figure 10. Selecting the LTC6806 Sketch

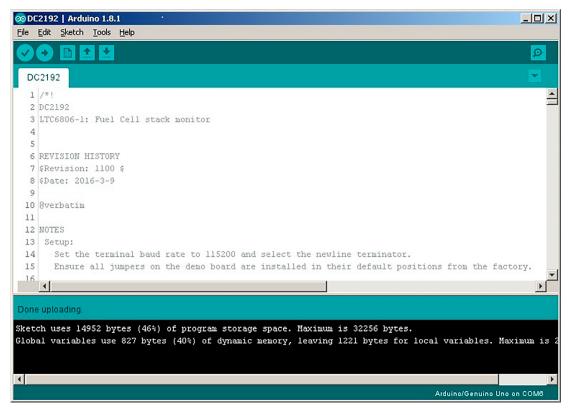


Figure 11. Uploading DC2192 Sketch

 Open the Arduino Serial Monitor tool (Figure 12). Click on the Serial Monitor button on the top right corner then the Serial Monitor window will open and show on the top left corner the COMxx used.

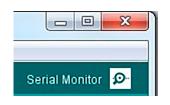


Figure 12. Arduino Serial Monitor Tool

- Configure the Serial Monitor to allow communication to the DC2026 through USB. On the bottom of the Serial Monitor window, set the following starting from bottom left to bottom right:
 - a. Click on the Autoscroll checkbox to select it.
 - b. Select Both NL & CR on the left dropdown menu.
 - c. Select 115200 baud on the right dropdown menu.
 - d. As shown in Figure 13, when configured correctly the DC2192 sketch menu will appear.

😳 COM6	
	Send
Please enter LTC6806 Command	
Write Configuration: 1	Change Written Configuration: 10
Read Configuration: 2	Run Open Wire Test: 11
Start Cell Voltage Conversion: 3	Start CVST: 12
Read Cell Voltages: 4	Print Cells Hex: 13
Start Aux Voltage Conversion: 5	Set UV OV Thresholds: 14
Read Aux Voltages: 6	Start Continuous Monitor Mode: 15
Start Stat Voltage Conversion: 7	Print menu: 'm'
Read Stat Register Data: 8	I
loop cell voltages: 9	1
Please enter command:	1
]	
Autoscroll	Both NL & CR 💌 115200 baud 💌

Figure 13. DC2192 Sketch Menu

APPENDIX A: THE SKETCHBOOK CONTENTS

The LTSketchbook will generally contain the following folders: Libraries, Part Number, Utilities and Documentation.

Libraries Directory contains a subdirectory for each IC in the sketchbook. Each subdirectory contains a *.cpp* and *.h* files. These files contain all the constant definitions and low-level IC command implementations. Porting to a different microcontroller requires changes to some library files.

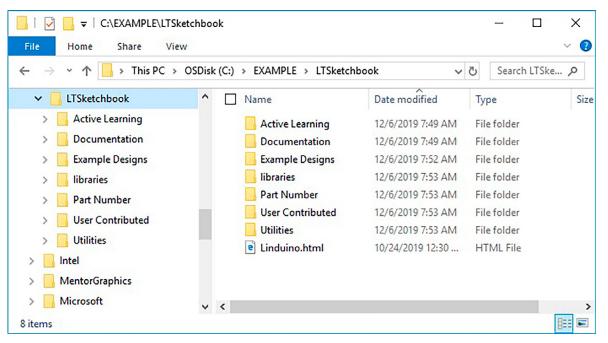
Part Number Directory contains example control programs for each IC. Inside the Part Number folder, each BMS IC has a sketch(*.ino*) file that implements a control program to evaluate the functionality of the IC. This sketch allows the user to control the IC through a serial terminal and make all primary measurements. This sketch also allows for evaluation of self-test and discharge features of the IC. Generally, the name of a sketch relates to the IC's demo board. For example, the sketch for LTC6804 is *DC1942.ino*, for LTC6811 it is *DC2259.ino*, and for LTC6806 it is *DC2192.ino*.

Utilities Directory contains support programs, including a program that emulates the standard Analog Devices DC590 isolated USB to serial controller.

Documentation Directory: contains *html* documentation for the provided code base. Documentation for all of the BMS ICs can be accessed by opening the *Linduino*. *html* file, as found in the main sketchbook directory (see Figure 14) and in the documentation directory.

What is A Sketch

A **sketch** is simply another word for a microcontroller/ Linduino program. The term is generally only used when referring to Arduino-based programs, as sketches have several abstractions that remove some of the complexity of a standard microcontroller (MCU) program. All sketches contains two primary functions, the setup() and the *loop()* function. These are in fact the only functions that are mandatory in a sketch and are almost always implemented in some form in a typical MCU program. The setup() function is run once at power on or after the MCU is reset. The setup() function generally is used to initialize the MCU peripheral circuits and to initialize all of the control variables. The *loop()* function is similar to a *main()* function that has implemented an infinite loop inside a standard C program. The code within the *loop()* function is typically where the primary program code is placed. The code within the *loop()* function will repeat infinitely.





APPENDIX A: THE SKETCHBOOK CONTENTS

Sketch Modifications

Sketches can be modified to a set of applications specific requirements. All sketches are written such that the most common modifications can be made by changing the variables listed in the /**Setup Variables* */table at the top of the sketch. For reference, example modifications to a DC2259 (LTC6811) sketch are shown below. These modifications are applicable to most of the available BMS ICs in the sketchbook.

Common modifications can be made by changing the *Setup Variables*. The most common application changes are listed below. After the variables are changed, the sketch will need to be recompiled and uploaded to the Linduino.

 To change the number of ICs in the isoSPI network, change the TOTAL_IC variable. A number between 1 and 4 should be entered. In an application that has 2 devices in the network the modified line will look like:

const uint8_t TOTAL_IC = 2;

2. Often an application may need to sample data at a rate faster than the default 500ms (2Hz). To modify the loop/sample rate the MEASUREMENT_LOOP_TIME variable should be changed. The loop time must be entered in milliseconds and should be a number larger than 20mS. To change the loop rate to roughly 10 measurements a second the loop rate should be changed to 100mS. The modified line will look like:

```
const uint16 t MEASUREMENT LOOP TIME = 100;
```

 It is possible to modify which measurements fall within the loop during the Loop Measurements command. The following list are the measurements that can be looped:

```
const uint8_t MEASURE_CELL = ENABLED;
// This is ENABLED or DISABLED
const uint8_t MEASURE_AUX = DISABLED;
// This is ENABLED or DISABLED
const uint8_t MEASURE_STAT = DISABLED;
//This is ENABLED or DISABLED
```

By default, only a cell measurement is done, as noted by MEASURE_CELL = ENABLED. What measurements are made can be changed by setting what the measure field is equal to. To measure cells and the status register but not the AUX register, the variables would be setup as shown below.

const uint8_t MEASURE_CELL = ENABLED; // This is ENABLED or DISABLED const uint8_t MEASURE_AUX = DISABLED; // This is ENABLED or DISABLED const uint8_t MEASURE_STAT = ENABLED; //This is ENABLED or DISABLED

4. ADC conversion settings can also be modified in the Setup Variables section. The default setup is to run the ADC in Normal mode, which has a 7kHz filter code; in this mode the ADC_OPT bit is disabled. Typical choice for which cell to convert is ALL. Full ADC conversion programming requires setting ADC_OPT, ADC_ CONVERSION_MODE, CELL_CH_TO_CONVERT, AUX_ CH_TO_CONVERT, and STAT_CH_TO_CONVERT. These variables are programmed with constants listed in the LTC68xy_daisy.h file. For simplicity they are also listed below.

```
MD_422HZ_1KHZ
MD_27KHZ_14KHZ
MD_7KHZ_3KHZ
MD_26HZ_2KHZ
ADC_OPT_ENABLED
ADC_OPT_DISABLED
CELL_CH_ALL
CELL_CH_1and7
CELL_CH_2and8
CELL_CH_3and9
CELL_CH_4and10
CELL_CH_5and11
CELL_CH_6and12
```

APPENDIX A: THE SKETCHBOOK CONTENTS

To set the ADC to have a 1kHz filter corner the ADC_ OPT and ADC_CONVERSION_MODE variables would be changed to:

ADC_OPT = ADC_OPT_ENABLED;

ADC CONVERSION MODE = MD 422HZ 1KHZ;

To convert only cells 2 and 8,

CELL CH TO CONVERT = CELL CH 2and8;

5. In another example, the user may wish to change the undervoltage and overvoltage thresholds. Each number is based on an LSB of 100μV.

//Under Voltage and Over Voltage Thresholds

```
const uint16_t OV_THRESHOLD = 41000;
```

// Over voltage threshold ADC Code.
// LSB = 0.0001

const uint16 t UV THRESHOLD = 30000;

// Under voltage threshold ADC Code.
// LSB = 0.0001



ESD Caution

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

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