

# **AMR2501**

# High Accuracy, Low Noise Linear Magnetic Sensor

## Description

The AMR2501 linear sensor utilizes a push-pull Wheatstone bridge composed of four highly sensitive AMR sensor elements. The Wheatstone bridge effectively compensates the sensor's temperature drift to achieve outstanding temperature stability with minimal noise. AMR2501 is available in the DFN16L package.

## Features and Benefits

- Anisotropic magnetoresistance (AMR) technology
- Low noise density: 100 pT/√Hz@1 Hz
- Wide range supply voltages
- Low saturation field
- Excellent temperature stability
- Low hysteresis



DFN16L (5 mm × 6 mm × 0.75 mm)

# Applications

- Weak magnetic field sensing
- Current sensor
- Position sensor
- Magnetometer

# Selection Guide

Part Number	Linear Range	Sensitivity	Set/reset Coil Resistance	Offset Coil Resistance	Noise Density	Package	Packing Form
AMR2501D-A	±1 Gs	2.5 mV/V/Gs	2 Ω	3 Ω	100 pT/√Hz	DFN16L	Tape & Reel
AMR2501D-B	±1 Gs	2.5 mV/V/Gs	2 Ω	40 Ω	100 pT/√Hz	DFN16L	Tape & Reel





# Catalogue

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## 1. Functional Block Diagram



Figure 1. Block Diagram

# 3. Pin Configuration



Figure 3. Pin Configuration (DFN16L)

# 2. Sensing Direction



Figure 2. Sensing Direction (DFN16L)

Pin Number	Name	Function		
1	N/A	Not connected		
2	N/A	Not connected		
3	N/A	Not connected		
4	S/R-	Set/reset input -		
5	V <sub>OUT</sub> -	Output -		
6	V <sub>CC2</sub>	Supply voltage		
7	N/A	Not connected		
8	Offset-	Offset voltage -		
9	GND	Ground		
10	N/A	Not connected		
11	V <sub>CC1</sub>	Supply voltage		
12	V <sub>OUT</sub> +	Output +		
13	N/A	Not connected		
14	S/R+	Set/reset input +		
15	Offset+	Offset voltage +		
16 N/A		Not connected		





# 4. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit	
Supply Voltage	V <sub>cc</sub>	-	12	V	
ESD Performance (HBM)	V <sub>ESD</sub>	-	4	kV	
Operating Ambient Temperature	T <sub>A</sub>	-55	150	°C	
Storage Ambient Temperature	T <sub>STG</sub>	-55	175	°C	
Soldering Temperature	Ti	-	260	°C	
Magnetic Field	В	-	10000	Gs	

# 5. Electrical Specifications

 $V_{\text{CC}}$  = 5.0 V,  $T_{\text{A}}$  = 25 °C,  $I_{\text{S/R}}$  = 2.5 A, differential output unless otherwise specified

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Symbol	Conditior	Min.	Тур.	Max.	Unit	
V <sub>cc</sub>	Bridge voltage, referer	1.8	5	12	V	
R <sub>B</sub>	I = 10 mA	500	700	1100	Ω	
B <sub>SAT</sub>	Full scale (FS)		-2	-	2	Gs
NONL	Fit in: ±1 Gs		-	0.2	0.5	0/ 50
	Fit in: ±2 Gs			1.2	2	%FS
HYS	2 sweeps, acros	s ±2 Gs	-	0.02	0.1	%FS
B <sub>repeat</sub>	2 sweeps, across ±2 Gs		-	0.05	0.1	%FS
V <sub>OFFSET</sub>	V <sub>OFFSET</sub> = (V <sub>OUT</sub> +) - ( V <sub>OUT</sub> -), B = 0 Gs, after set pulse		-10	±2	+10	mV/V
SEN	-		1.8	2.5	3.5	mV/V/Gs
V <sub>noise</sub>	At 1 Hz		-	20	-	nV/√Hz
B <sub>noise</sub>	At 1 Hz		-	100	-	pT/√Hz
RES	Bandwidth = 10 Hz		-	20	-	μGs
BW	Magnetic signal (lower limit = DC)		-	5	-	MHz
R <sub>OFFCOIL</sub>	Measured from OFFSET+ to OFFSET-	AMR2501D-A	-	3	-	Ω
		AMR2501D-B	-	40	-	
BOFFCOIL	Field applied in sensitive direction	AMR2501D-A	45	51	60	mA/Gs
		AMR2501D-B	9	10	12	
R <sub>s/R</sub>	Measured between S/R+ and S/R-		1.5	2	2.5	Ω
I <sub>S/R</sub>	2 µs current pulse		1	2.5	3.5	Α
B <sub>disturb</sub>	Sensitivity starts to degrade, restore by S/R pulse		-	3	-	Gs
TCS	T <sub>A</sub> = -40 °C to 125 °C		-	-3000	-	PPM/°C
тсо	$T_A$ = -40 °C to 125 °C, w/o set/reset		-	300	-	PPM/°C
	$T_A$ = -40 °C to 125 °C, w/ set/reset		-	10	-	
TCR	T <sub>A</sub> = -40 °C to 1	-	2500	-	PPM/°C	
X <sub>B</sub>	Cross field = 1 Gs		-	±0.5	-	%FS
	V <sub>CC</sub> R <sub>B</sub> B <sub>SAT</sub> NONL HYS B <sub>repeat</sub> V <sub>OFFSET</sub> SEN V <sub>noise</sub> B <sub>noise</sub> RES BW R <sub>OFFCOIL</sub> B <sub>OFFCOIL</sub> R <sub>S/R</sub> I <sub>S/R</sub> I <sub>S/R</sub> B <sub>disturb</sub> TCS TCO	$\begin{tabular}{ c c c c } \hline V_{CC} & Bridge voltage, reference on the second symplect on$	$\begin{tabular}{ c c c c } \hline V_{CC} & Bridge voltage, referenced to ground \\ \hline R_B & I = 10 mA \\ \hline B_{SAT} & Full scale (FS) \\ \hline NONL & Fit in: \pm 1 Gs \\ \hline NONL & Fit in: \pm 1 Gs \\ \hline HYS & 2 sweeps, across \pm 2 Gs \\ \hline HYS & 2 sweeps, across \pm 2 Gs \\ \hline B_{repeat} & 2 sweeps, across \pm 2 Gs \\ \hline V_{OFFSET} & U_{OFFSET} = (V_{OUT} +) - (V_{OUT} -), \\ B = 0 Gs, after set pulse \\ \hline SEN & - \\ \hline V_{noise} & At 1 Hz \\ \hline RES & Bandwidth = 10 Hz \\ \hline BW & Magnetic signal (low=r limit = DC) \\ \hline R_{OFFCOIL} & Measured from \\ OFFSET + to OFFSET - \\ \hline BW & Magnetic signal (low=r limit = DC) \\ \hline R_{OFFCOIL} & Field applied in \\ \hline sensitive direction & AMR2501D-A \\ \hline AMR2501D-B \\ \hline R_{S/R} & Measured between S/R+ and S/R- \\ \hline I_{S/R} & 2 \ \mu s \ current \ ulse \\ \hline Sensitivity starts to degrade, restore by S/R \ pulse \\ \hline TCS & T_A = -40 \ C \ to \ 125 \ C \\ \hline TCR & T_A = -40 \ C \ to \ 125 \ C \\ \hline \end{tabular}$	$\begin{tabular}{ c c c c } \hline V_{CC} & Bridge voltage, referenced to ground & 1.8 \\ \hline R_B & I = 10 \mbox{ mA} & 500 \\ \hline B_{SAT} & Full scale (FS) & -2 \\ \hline RONL & Fit in: \pm 1 \mbox{ Gs} & -2 \\ \hline Fit in: \pm 1 \mbox{ Gs} & -2 \\ \hline Fit in: \pm 2 \mbox{ Gs} & -2 \\ \hline Fit in: \pm 2 \mbox{ Gs} & -2 \\ \hline HYS & 2 \mbox{ sweeps, across } \pm 2 \mbox{ Gs} & -2 \\ \hline HYS & 2 \mbox{ sweeps, across } \pm 2 \mbox{ Gs} & -2 \\ \hline HYS & 2 \mbox{ sweeps, across } \pm 2 \mbox{ Gs} & -2 \\ \hline R_{oFFSET} & 2 \mbox{ sweeps, across } \pm 2 \mbox{ Gs} & -10 \\ \hline SEN & - & 1.8 \\ \hline V_{oFFSET} & B \mbox{ Gs, after set pulse} & -10 \\ \hline SEN & - & 1.8 \\ \hline V_{noise} & At 1 \mbox{ Hz} & - \\ \hline R_{noise} & At 1 \mbox{ Hz} & - \\ \hline R_{oFFCOIL} & Magnetic \mbox{ signal (lower limit = DC)} & - \\ \hline R_{oFFCOIL} & Measured from \\ OFFSET \mbox{ to OFFSET} & AMR2501D-A & - \\ \hline R_{oFFCOIL} & Field \mbox{ applied in sensitive direction} & AMR2501D-A & - \\ \hline R_{oFFCOIL} & Field \mbox{ applied in sensitive direction} & AMR2501D-A & - \\ \hline R_{S/R} & Measured \mbox{ between S/R+ and S/R-} & 1.5 \\ \hline I_{S/R} & 2 \mbox{ µs current pulse} & 1 \\ \hline R_{disturb} & 2 \mbox{ motor by S/R pulse} & - \\ \hline TCS & T_A \mbox{ -40 °C to 125 °C} & - \\ \hline T_A \mbox{ -40 °C to 125 °C}, \ w/ \ set/reset & - \\ \hline TCR & T_A \mbox{ -40 °C to 125 °C} & - \\ \hline \end{array}$	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{tabular}{ c c c c c } \hline V_{CC} & Bridge voltage, referenced to ground & 1.8 & 5 & 12 \\ \hline R_{B} & I = 10 \mbox{ mA} & 500 & 700 & 1100 \\ \hline B_{SAT} & Full scale (FS) & -2 & - & 2 \\ \hline R_{B} & Ift in: \pm 1 \mbox{ GS} & - & 0.2 & 0.5 \\ \hline R_{II} & Ift in: \pm 1 \mbox{ GS} & - & 0.2 & 0.5 \\ \hline R_{II} & Ift in: \pm 2 \mbox{ GS} & - & 0.02 & 0.1 \\ \hline B_{repeal} & 2 \mbox{ sweeps, across } \pm 2 \mbox{ GS} & - & 0.02 & 0.1 \\ \hline B_{repeal} & 2 \mbox{ sweeps, across } \pm 2 \mbox{ GS} & - & 0.05 & 0.1 \\ \hline V_{OFFSET} & 2 \mbox{ Sweeps, across } \pm 2 \mbox{ GS} & - & 0.05 & 0.1 \\ \hline V_{OFFSET} & 2 \mbox{ sweeps, across } \pm 2 \mbox{ GS} & - & 0.05 & 0.1 \\ \hline V_{OFFSET} & B = 0 \mbox{ GS, after set pulse} & -10 & \pm 2 & +10 \\ \hline SEN & - & 1.8 & 2.5 & 3.5 \\ \hline V_{noise} & At 1 \mbox{ Hz} & - & 1.8 & 2.5 & 3.5 \\ \hline V_{noise} & At 1 \mbox{ Hz} & - & 100 & - \\ \hline R_{B} & Bandwidth = 10 \mbox{ Hz} & - & 100 & - \\ \hline R_{B} & Magnetic \mbox{ signal} (low \mbox{ limit = DC}) & - & 5 & - \\ \hline R_{OFFCOIL} & Measured \mbox{ from } OFFSET+ to OFFSET- \\ \hline B_{ofFCOIL} & Field applied \mbox{ in sensitive direction} & AMR2501D-A & - & 3 & - \\ \hline AMR2501D-B & - & 40 & - \\ \hline B_{OFFCOIL} & Field applied \mbox{ sensitive direction} & AMR2501D-A & 45 & 511 & 60 \\ \hline B_{OFFCOIL} & Ift across \mbox{ Haad singenerative } & 1 & 2.5 & 3.5 \\ \hline I_{SIR} & 2 \mbox{ µs current pulse} & 1 & 2.5 & 3.5 \\ \hline I_{SIR} & 2 \mbox{ µs current pulse} & 1 & 2.5 & 3.5 \\ \hline I_{SIR} & 2 \mbox{ µs current pulse} & - & 3 & - \\ \hline TCS & T_A = -40 \ ^{C} \ to \ 125 \ ^{C} \ C \ - & - \ 3000 & - \\ \hline T_A = -40 \ ^{C} \ to \ 125 \ ^{C} \ C \ - & \ 2500 & - \\ \hline \end{array}$





AMR2501

## 6. Typical Output Characteristics

Figure 4 shows the response of the AMR2501 to an applied magnetic field. (Applied field =  $\pm 6$  Gs, analysis field =  $\pm 2$  Gs, and V<sub>cc</sub> = 5 V).



Figure 4. AMR2501 output vs. applied field

#### Typical voltage noise density



Figure 5. AMR2501 voltage noise density vs. frequency

#### Typical magnetic noise density



Figure 6. AMR2501 magnetic noise density vs. frequency





# 7. Application Information

A voltage pulse of 5 V for 2  $\mu$ s in 10 kHz can be select as the set/reset signal. The pulse voltage, pulse width and duty cycle can be adjusted in a certain range. A typical drive circuit is shown in Figure 7.



Figure 7. Set/reset drive circuit of AMR2501

The circuit will generate 5 V set/reset pulses, as illustrated in figure 8.



Figure 8. Set/reset voltage pulses waveform

When set-only or reset-only pulse is applied, the set- and reset- pulse is switchable by reversing the set/reset input.





#### 8. Dimensions

#### DFN16L Package



Figure 9. Package outline of DFN16L (unit: mm)



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