

## Sandwich communication extensions XN06 Part number 88972250



- Standard Modbus RS485 or TCP/IP protocol
- Connects one or several Millenium 3 to a touch screen, a supervision PC or a network gateway
- Exchange of the input/output state and/or of internal values
- Updating date and time of a group of Millenium 3
- Power supply via the controller

Part numbers		
Туре	Description	Supply
88972250 XN06	Modbus RS-485 (slave) communication extension	Via the 24 V DC controller

Specifications

Certifications	CE, UL, CSA, GL
Conformity to standards (with the low voltage directive and EMC directive)	IEC/EN 61131-2 (Open equipment) IEC/EN 61131-2 (Zone B) IEC/EN 61000-6-2, IEC/EN 61000-6-3 (*) IEC/EN 61000-6-4 (*) Except configuration (88 970 1.1 or 88 970 1.2) + (88 970 250 or 88 970 270) + 88 970 241 class A (class B in a metal enclosure)
Earthing	None
Protection rating	In accordance with IEC/EN 60529 : IP40 on front panel IP20 on terminal block
Overvoltage category	3 in accordance with IEC/EN 60664-1
Pollution	Degree : 2 in accordance with IEC/EN 61131-2
Max operating Altitude	Operation : 2000 m Transport : 3,048 m
Mechanical resistance	Immunity to vibrations IEC/EN 60068-2-6, Fc test Immunity to shock IEC/EN 60068-2-27, Fa test
Resistance to electrostatic discharge	Immunity to ESD IEC/EN 61000-4-2, level 3
Resistance to HF interference	Immunity to radiated electrostatic fields IEC/EN 61000-4-3, Immunity to fast transients (burst immunity) IEC/EN 61000-4-4, level 3 Immunity to shock waves IEC/EN 61000-4-5 Radio frequency in common mode IEC/EN 61000-4-6, level 3 Voltage dips and breaks (AC) IEC/EN 61000-4-11 Immunity to damped oscillatory waves IEC/EN 61000-4-12
Conducted and radiated emissions	Class B (*) in accordance with EN 55022, EN 55011 (CISPR22, CISPR11) group 1 (*) Except configuration (88 970 1.1 or 88 970 1.2) + (88 970 250 or 88 970 270) + 88 970 241 class A (class B in metallic cabinet)
Operating temperature	-20 ->+55 °C (+40 °C in a non-ventilated enclosure) in accordance with IEC/EN 60068-2-1 and IEC/EN 60068-2-2
Storage temperature	-40 →+70 °C in accordance with IEC/EN 60068-2-1 and IEC/EN 60068-2-2
Relative humidity	95 % max. (no condensation or dripping water) in accordance with IEC/EN 60068-2-30
Mounting	On symmetrical DIN profile, 35 x 7.5 mm and 35 mm x 15 or panel (2 x 4 mm Ø)
Screw terminals connection capacity	Flexible wire with ferrule = 1 conductor : 0.25 to 2.5 mm <sup>2</sup> (AWG 24AWG 14) 2 conductors 0.25 to 0.75 mm <sup>2</sup> (AWG 24AWG 18) Semi-rigid wire = 1 conductor : 0.2 to 2.5 mm <sup>2</sup> (AWG 25AWG 14) Rigid wire = 1 conductor : 0.2 to 2.5 mm <sup>2</sup> (AWG 25AWG 14) 2 conductors 0.2 to 1.5 mm <sup>2</sup> (AWG 25AWG 16) Tightening torque = 0.5 N.m (4.5 lb-in) (tighten using screwdriver diam. 3.5 mm)

## Characteristics of communication extensions

General characteristics		
Certifications	UL, CSA	UL, CSA
Earthing	Yes, refer to the quick reference guide supplied with the product	Yes, refer to the quick reference guide supplied with the product
Operating temperature	-20 $\rightarrow$ +55 °C (+40 °C in a non-ventilated enclosure) in accordance	$0 \rightarrow +55 \ ^{\circ}\text{C}$ (+40 $\ ^{\circ}\text{C}$ in a non-ventilated enclosure) in accordance
	with IEC/EN 60068-2-1 and IEC/EN 60068-2-2	with IEC/EN 60068-2-1 and IEC/EN 60068-2-2
Cable length	Maximum length of the network : 1000 m (9600 Baud maxi, AWG26)	Maximum length between 2 controllers : 100 m

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## m

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Communication parameters					
88972250	88970270				
Type of link	2 or 4-wire ; RTU or ASCII			-	
Transmission rate (Bauds)	1200, 2400, 4800, 9600, 19200, 28800, 38400, 57600			-	
Parity	None ; even ; odd			-	
Addressing	1 →247			Static or dynamic (BootP server)	
Characteristics of exchanges					
88972250	88970270				
Ladder programming					
Image of smart relay I/O	4		-		
Status	1		-		
Function blocks programming					
Read-words	8			8	
Read/Write	8			8	
Clock words			4		
"Status" words	1			1	
Processing characteristics of CB, CD, XD & XB product types					
LCD display	CD, XD : Display with 4 lines of 18 characters				
Programming method	Function blocks / SCF (Grafcet) or Ladder				
Program size	For CB, CD :				
	4 Ko : 64 macros max.				
	256 blocks max. per macro				
	180 typical blocks				
	For XB, XD : 8 Ko : 64 macro max.				
	256 blocks max. per macro				
	350 typical blocks				
	Or for CB, CD, XB, XD : 120 lines in Ladder				
Program memory	Flash EEPROM				
Removable memory	EEPROM				
Data memory	368 bit/200 words				
Back-up time in the event of power failure	Program and settings in the controller : 10 years				
	Program and settings in the plug-in memory : 10 years Data memory : 10 years				
Cycle time	Function blocks : $6 \rightarrow 90$ ms (typically 20 ms)				
	Ladder : typically 20 ms				
Response time	Input acquisition time : 1 to 2 cycle times				
Clock data retention	10 years (lithium battery) at 25 °C				
Clock drift	Drift < 12 min/year (at 25 °C)				
	6 s/month (at 25 °C with user-definable correction of drit	ft)			
Timer block accuracy	1 % ± 2 cycle times				
Start up time on power up	< 1,2 s				
Characteristics of products with AC power supp	lied				
Supply	24 V AC	100 →240	V AC		
	(889704)	(889703)			
Nominal voltage	24 V AC	100 →240			
Operating limits	-15 % / +20 %	-15 % / +1	0 %		
	or 20.4 VAC→28.8 VAC	or 85 VAC	→264 VAC		
Supply frequency range	50/60 Hz (+4 % / -6 %) or 47→53 Hz/57 < 63 Hz	50/60 Hz (	+4 % / -6 %)	or 47 →53 Hz/57 < 63 Hz	
Immunity from micro power cuts	10 ms (repetition 20 times)	10 ms (rep	etition 20 time	es)	
Max. absorbed power	CB12-CD12-XD10-XB10 : 4 VA		2-XD10-XB10	) : 7 VA	
	CB20-CD20 : 6 VA	CB20-CD2		vien + 12 \/A	
	XD10-XB10 with extension : 7,5 VA	XD10-XB1 XD26-XB2	0 with extens	SION : 12 VA	
	XD26-XB26 : 7.5 VA XD26-XB26 with extension : 10 VA		6 : 12 VA 6 with extens	sion · 17 VA	
Isolation voltage	1780 V AC	1780 V AC			
Inputs	24 V AC		, 100 →240 V	AC	
	(889704)		100 →240 v (889703)		
Input voltage	24 V AC (-15 % / +20 %)		· ,	AC (-15 % / +10 %)	
Input current	4,4 mA @ 20,4 V AC				

	(889704)	(889703)
Input voltage	24 V AC (-15 % / +20 %)	100 →240 V AC (-15 % / +10 %)
Input current	4,4 mA @ 20,4 V AC 5,2 mA @ 24,0 V AC 6,3 mA @ 28,8 V AC	0,24 mA @ 85 V AC 0,75 mA @ 264 V AC
Input impedance	4.6 kΩ	350 kΩ
Logic 1 voltage threshold	≥ 14 V AC	≥ 79 V AC
Making current at logic state 1	>2 mA	>0.17 mA
Logic 0 voltage threshold	≤5 V AC	≤ 20 V AC (≤ 28 V AC : XE10, XR06, XR10, XR14)
Release current at logic state 0	<0.5 mA	<0.5 mA
Response time with LADDER programming	50 ms State 0 →1 (50/60 Hz)	50 ms State 0 < 1 (50/60 Hz)
Response time with function blocks programming	Configurable in increments of 10 ms 50 ms min. up to 255 ms State 0 →1 (50/60 Hz)	Configurable in increments of 10 ms 50 ms min. up to 255 ms State 0 $\rightarrow$ 1 (50/60 Hz)
Maximum counting frequency	In accordance with cycle time (Tc) and input response time (Tr) : 1/ ( (2 x Tc) + Tr)	In accordance with cycle time (Tc) and input response time (Tr) : 1/ ( (2 x Tc) + Tr)
Sensor type	Contact or 3-wire PNP	Contact or 3-wire PNP
Input type	Resistive	Resistive
Isolation between power supply and inputs	None	None
Isolation between inputs	None	None
Protection against polarity inversions	Yes	Yes

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Status indicator	On LCD screen for CD and XD	On LCD screen for CD and XD	
Characteristics of relay outputs common to th	e entire range		
Max. breaking voltage	5 →30 V DC 24 →250 V AC		
Breaking current	CB-CD-XB10-XD10-XR06-XR10 : 8 A XD26-XB26 : 8 x 8 A relays, 2 x 5 A relays XE10 : 4 x 5 A relays XR14 : 4 x 8 A relays, 2 x 5 A relays		
Electrical durability for 500 000 operating cycles	Usage category DC-12 : 24 V, 1.5 A Usage category DC-13 : 24 V (L/R = 10 ms), 0.6 A Usage category AC-12 : 230 V, 1.5 A Usage category AC-15 : 230 V, 0.9 A		
Max. Output Common Current	12A for O8,O9,OA		
Minimum switching capacity	10 mA (at minimum voltage of 12 V)		
Minimum load	12 V, 10 mA		
Maximum rate	Off load : 10 Hz At operating current : 0.1 Hz		
Mechanical life	10,000,000 operations (cycles)		
Voltage for withstanding shocks	In accordance with IEC/EN 60947-1 and IEC/EN 60664-1 : 4 kV		
Off-cycle response time	Make 10 ms Release 5 ms		
Built-in protections	Against short-circuits : None Against overvoltages and overloads : None		
Status indicator	On LCD screen for CD and XD		

tatus indicator	On LCD s	creen for CD

Characteristics of product with DC power supplie	d				
Supply 12 V DC 24 V DC (00070 44 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070148 8 00070000000000000000000000000000000					
	(889705 & 8970814 & 88970840)	(889701 et 889702	.)		
Nominal voltage	12 V DC	24 V DC			
Operating limits	-13 % / +20 % or 10.4 V DC < 14.4 V DC (including ripple)	-20 % / +25 % or 19.2 V DC < 30 V	C (including rinnle)		
Immunity from micro power cuts	$\leq 1 \text{ ms} (\text{repetition 20 times})$	≤ 1 ms (repetition 20			
Max. absorbed power		CB12-CD12-CD20 with solid state outputs - XD10-XB10 with solid state		outputs - XD10-XB10 with solid state outputs : 3 W	
	CB12 with solid state outputs : 1.5 W CD12 : 1.5 W CD20 : 2.5 W	12 : 1.5 W XD10-XB10 With relay outputs : 5 W 20 : 2.5 W CB20-XB26 with solid state outputs : 5 W		W ts : 5 W	
	XD26-XB26 : 3 W XD26-XB26 with extension : 5 W/ XD26 with relay output		uts:6W	uts : 6 W	
	XD26 with solid state outputs : 2.5 W	XD10-XB10 with extension : 8 W XD26-XB26 with extension : 10 W			
Protection against polarity inversions	Yes	Yes			
Digital inputs (I1 to IA and IH to IY)	12 V DC		24 V DC		
			(889701 and 889702)		
Input voltage	12 V DC (-13 % / +20 %)		24 V DC (-2	20 % / +25 %)	
Input current	3,9 mA @ 10,44 V DC		2,6 mA @ 1		
	4,4 mA @ 12,0 V DC		3,2 mA @ 2		
	5,3 mA @ 14,4 VDC		4,0 mA @ 3	30,0 VDC	
Input impedance	2.7 kΩ		7.4 kΩ ≥ 15 V DC		
Logic 1 voltage threshold	≥ 7 V DC				
Making current at logic state 1 Logic 0 voltage threshold	≥2 mA		≥2.2 mA		
Release current at logic state 0	≤ 3 V DC <0.9 mA		≤ 5 V DC		
Response time	$1 \rightarrow 2$ cycle times + 6 ms		<0.75 mA 1 →2 cycle times + 6 ms		
Maximum counting frequency			$I \rightarrow 2$ cycle times + 0 ms I1 & I2 : FBD (Up to 6 k Hz) & Ladder (1 k Hz)		
	I1 & I2 : FBD (Up to 6 k Hz) & Ladder (1 k Hz) I3 to IA & IH to IY : in accordance with cycle time (Tc) and input response time (Tr) : 1/ ( (2 x Tc) + Tr)		Is to IA & IH to IY : in accordance with cycle time (Tc) and input response time (Tr) : $1/((2 \times Tc) + Tr)$		
Sensor type	Contact or 3-wire PNP		Contact or	3-wire PNP	
Conforming to IEC/EN 61131-2	Туре 1		Type 1		
Input type	Resistive		Resistive		
Isolation between power supply and inputs	None		None		
Isolation between inputs	None		None		
Protection against polarity inversions	Yes		Yes		
Status indicator	On LCD screen for CD and XD		On LCD sc	reen for CD and XD	
Analogue or digital inputs (IB to IG)	12 V DC (889705 & 88970814 & 88970840)			24 V DC (889701 and 889702)	
CB12-CD12-XD10-XB10	4 inputs IB →IE		4 inputs IB →IE		
CB20-CD20-XB26-XD26	6 inputs IB →IG			6 inputs IB $\rightarrow$ IG	
Inputs used as analogue inputsonly in FBD					
Measurement range	$(0 \rightarrow 10 \text{ V}) \text{ or } (0 \rightarrow \text{V power supply})$			or $(0 \rightarrow V \text{ power supply})$	
Input impedance	14 kΩ		12 kΩ		
Input voltage	14.4 V DC max		30 V DC max		
Value of LSB	14 mV Common mode	29 mV Common mode		ada	
Input type Resolution	10 bit at maximum input voltage				
Conversion time	Controller cycle time		10 bit at maximum input voltage Controller cycle time		
Accuracy at 25 °C	± 5 %		± 5 %		
Accuracy at 55 °C	± 6.2 %		± 6.2 %		
Repeat accuracy at 55 °C	± 2 %		± 0.2 %		
Isolation between analogue channel and power supply	None		None		
Cable length	10 m maximum, with shielded cable (sensor	not isolated)	10 m maximum, with shielded cable (sensor not isolated)		
Protection against polarity inversions	Yes	,	Yes		
Potentiometer control	2.2 kΩ/0.5 W (recommended)		2.2 k $\Omega$ /0.5 W (recommended)		
	10 kΩ max.		10 kΩ max.		

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Inputs used as digital inputs		www.crouzei.cor
Input voltage	12 V DC (-13 % / +20 %)	24 V DC (-20 % / +25 %)
Input current	0,7 mA @ 10,44 VDC	1,6 mA @ 19,2 VDC
	0.9 mA @ 12.0 VDC	2,0 mA @ 24,0 V DC
	1,0 mA @ 14,4VDC	2,5 mA @ 30,0 VDC
Innutimnedence		
Input impedance	14 κΩ	12 kΩ
Logic 1 voltage threshold	≥7VDC	≥ 15 VDC
Making current at logic state 1	≥0.5 mA	≥1.2 mA
Logic 0 voltage threshold	≤ 3 V DC	≤5VDC
Release current at logic state 0	≤0.2 mA	≤0.5 mA
Response time		
	$1 \rightarrow 2$ cycle times	$1 \rightarrow 2$ cycle times
Maximum counting frequency in FBD	In accordance with cycle time (Tc) and input response time (Tr) :	In accordance with cycle time (Tc) and input response time (Tr) :
	1/ ( (2 x Tc) + Tr)	1/ ( (2 x Tc) + Tr)
Sensor type	Contact or 3-wire PNP	Contact or 3-wire PNP
Conforming to IEC/EN 61131-2	Type 1	Type 1
Input type	Resistive	Resistive
Isolation between power supply and inputs	None	None
Isolation between inputs	None	None
Protection against polarity inversions	Yes	Yes
Status indicator	On LCD screen for CD and XD	On LCD screen for CD and XD
Characteristics of relay outputs common to the entire		
range		
Max. breaking voltage	$5 \rightarrow 30 \text{ V DC}$	
	24 →250 V AC	
Max. Output Common Current	12A (10A UL) for O8,O9,OA	
Breaking current	CB-CD-XD10-XB10-XR06-XR10 : 8 A	
	XD26-XB26 : 8 x 8 A relays, 2 x 5 A relays	
	XE10: 4 x 5 A relays	
	XR14 : 4 x 8 A relays, 2 x 5 A relays	
Electrical durability for 500 000 operating cycles	Usage category DC-12 : 24 V, 1.5 A	
	Usage category DC-13 : 24 V (L/R = 10 ms), 0.6 A	
	Usage category AC-12 : 230 V, 1.5 A	
	Usage category AC-15 : 230 V, 0.9 A	
Minimum switching capacity	10 mA (at minimum voltage of 12 V)	
Minimum load	12 V, 10 mA	
	*	
Maximum rate	Off load : 10 Hz	
	At operating current : 0.1 Hz	
Mechanical life	10,000,000 operations (cycles)	
Voltage for withstanding shocks	In accordance with IEC/EN 60947-1 and IEC/EN 60664-1 : 4 kV	
Off-cycle response time	Make 10 ms	
	Release 5 ms	
D. N. De service alle est		
Built-in protections	Against short-circuits : None	
	Against overvoltages and overloads : None	
Status indicator	On LCD screen for CD and XD	
Digital / PWM solid state output	12 V DC	24 V DC
	(88970814 & 88970840)	(889702)
PWM solid state output*	CB12:04	CD12-XD10-XB10 : O4
	XD26 : O4 →O7	CD20-XD26-XB26 : O4 $\rightarrow$ O7
		CD20-7D20-7D20 : 04
* Only available with "FBD" programming language	* Only available with "FBD" programming language	
Breaking voltage		
	10.4 →30 VDC	19.2 →30 VDC
Nominal voltage	12-24 V DC	19.2 →30 VDC 24 V DC
Nominal voltage Nominal current	12-24 V DC 0.5 A	24 V DC 0.5 A
Nominal voltage Nominal current Max. breaking current	12-24 V DC 0.5 A 0,625 A	24 V DC 0.5 A 0,625 A
Nominal voltage Nominal current Max. breaking current Voltage drop	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1)	24 ∨ DC 0.5 A 0,625 A ≤ 2 ∨ for I = 0.5 A (at state 1)
Nominal voltage Nominal current Max. breaking current	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms	24 ∨ DC 0.5 A 0,625 A ≤ 2 ∨ for I = 0.5 A (at state 1) Make ≤ 1 ms
Nominal voltage Nominal current Max. breaking current Voltage drop	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1)	24 ∨ DC 0.5 A 0,625 A ≤ 2 ∨ for I = 0.5 A (at state 1)
Nominal voltage Nominal current Max. breaking current Voltage drop	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms	24 ∨ DC 0.5 A 0,625 A ≤ 2 ∨ for I = 0.5 A (at state 1) Make ≤ 1 ms
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load
Nominal voltage Nominal current Max. breaking current Voltage drop Response time	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads (*) : Yes	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads (*) : Yes
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency Built-in protections	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the
Nominal voltage Nominal current Max. breaking current Voltage drop Response time Operating frequency Built-in protections	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC	24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against overvoltages (*) : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against overvoltages (*) : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz	24 V DC 0.5 A 0,625 A $\leq$ 2 V for I = 0.5 A (at state 1) Make $\leq$ 1 ms Release $\leq$ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA)
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency	12-24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz	24 V DC 0.5 A 0,625 A $\leq 2$ V for I = 0.5 A (at state 1) Make $\leq 1$ ms Release $\leq 1$ ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency         PWM cyclic ratio         PWM accuracy at 120 Hz	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against inversions of power supply : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) < 5 % (20 % →80 %) load at 10 mA	24 V DC 0.5 A 0,625 A $\leq$ 2 V for I = 0.5 A (at state 1) Make $\leq$ 1 ms Release $\leq$ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against overvoltages (*) : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) $\leq$ 5 % (20 % →80 %) load at 10 mA
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency         PWM cyclic ratio         PWM accuracy at 120 Hz         Max. Breaking current PWM	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) < 5 % (20 % →80 %) load at 10 mA 50 mA	24 V DC 0.5 A 0,625 A $\leq$ 2 V for I = 0.5 A (at state 1) Make $\leq$ 1 ms Release $\leq$ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against overvoltages (*) : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) $\leq$ 5 % (20 % →80 %) load at 10 mA 50 mA
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency         PWM syclic ratio         PWM accuracy at 120 Hz         Max. Breaking current PWM         Max. cable length PWM	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 $\rightarrow$ 100 % (256 steps for CD, XD and 1024 for XA) < 5 % (20 % $\rightarrow$ 80 %) load at 10 mA 50 mA 20 m	24 V DC 0.5 A 0,625 A $\leq$ 2 V for I = 0.5 A (at state 1) Make $\leq$ 1 ms Release $\leq$ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) $< 5 \% (20 \% \rightarrow 80 \%)$ load at 10 mA 50 mA 20 m
Nominal voltage         Nominal current         Max. breaking current         Voltage drop         Response time         Operating frequency         Built-in protections         Min. load         Maximum incandescent load         Galvanic isolation         PWM frequency         PWM cyclic ratio         PWM accuracy at 120 Hz         Max. Breaking current PWM	12-24 V DC 0.5 A 0,625 A ≤ 2 V for I = 0.5 A (at state 1) Make ≤ 1 ms Release ≤ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes Against overloads and short-circuits : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,2 A / 12 V DC 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) < 5 % (20 % →80 %) load at 10 mA 50 mA	24 V DC 0.5 A 0,625 A $\leq$ 2 V for I = 0.5 A (at state 1) Make $\leq$ 1 ms Release $\leq$ 1 ms 1 Maximum on inductive load Against overloads and short-circuits : Yes Against overvoltages (*) : Yes Against overvoltages (*) : Yes (*) In the absence of a volt-free contact between the output of the logic controller and the load 1 mA 0,1 A / 24 V DC No 14.11 Hz 56.45 Hz 112.90 Hz 225.80 Hz 451.59 Hz 1806.37 Hz 0 →100 % (256 steps for CD, XD and 1024 for XA) $\leq$ 5 % (20 % →80 %) load at 10 mA 50 mA

Dimensions (mm) XN05 - XN06

