

SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

Class V, 14-BIT, 400-MSPS ANALOG-TO-DIGITAL CONVERTER

Check for Samples: ADS5474-SP

FEATURES

- 400 MSPS Sample Rate
- 14 Bit Resolution, 10.9 Bits Effective Number of Bits (ENOB)
- 5962R13208:
 - Radiation Hardness Assurance (RHA) up to TID 100 krad (Si)
 - Total Ionizing Dose 100 krad (Si)
 - ELDRS free 100 krad (Si)
 - SEL/SEU characterized
- 1.28 GHz Input Bandwidth
- SFDR = 78 dBc at 230 MHz and 400 MSPS
- SNR = 69.8 dBFS at 230 MHz and 400 MSPS
- 2.2 V_{PP} Differential Input Voltage
- LVDS-Compatible Outputs
- Total Power Dissipation: 2.5 W
- Power Down Mode: 50 mW
- Offset Binary Output Format
- Output Data Transitions on the Rising and Falling Edges of a Half-Rate Output Clock
- On-Chip Analog Buffer, Track-and-Hold, and Reference Circuit

- Available in a 84-Pin Ceramic Nonconductive Tie-Bar Package (HFG)
- Military Temperature Range: –55°C to +125°C T_{case}
- Engineering Evaluation (/EM) Samples are Available (1)
- Pin-Similar and Compatible With 12- and 14-Bit Family: ADS5463-SP and ADS5444-SP

APPLICATIONS

- Test and Measurement Instrumentation
- Software-Defined Radio
- Data Acquisition
- Power Amplifier Linearization
- Communication Instrumentation
- Radar
- (1) These units are intended for engineering evaluation only. They are processed to a non-compliant flow (e.g. No Burn-In, etc.) and are tested to a temperature rating of 25°C only. These units are not suitable for qualification, production, radiation testing or flight use. Parts are not warranted for performance over the full MIL specified temperature range of -55°C to 125°C or operating life.

DESCRIPTION

The ADS5474 is a 14-bit, 400-MSPS analog-to-digital converter (ADC) that operates from both a 5-V supply and 3.3-V supply while providing LVDS-compatible digital outputs. This ADC is one of a family of 12-, 13-, 14-bit ADCs that operate from 210 MSPS to 500 MSPS. The ADS5474 input buffer isolates the internal switching of the onboard track and hold (T&H) from disturbing the signal source while providing a high-impedance input. An internal reference generator is also provided to simplify the system design.

Designed with a 1.4-GHz input bandwidth for the conversion of wide-bandwidth signals that exceed 400 MHz of input frequency at 400 MSPS, the ADS5474 has outstanding low noise performance and spurious-free dynamic range over a large input frequency range.

The ADS5474 is available in an 84-pin ceramic nonconductive tie-bar package (HFG). The device is built on Texas Instruments complementary bipolar process (BiCom3) and is specified over the full military temperature range (-55° C to $+125^{\circ}$ C T_{case}).



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

Over operating free-air temperature range, unless otherwise noted.

		ADS5474-SP	UNIT
	AVDD5 to GND	6	V
Supply voltage	AVDD3 to GND	5	V
	DVDD3 to GND	5	V
Analog input to G	ND	-0.3 to (AVDD5 + 0.3)	V
Clock input to GN	D	-0.3 to (AVDD5 + 0.3)	V
CLK to CLK		±2.5	V
Digital data output	t to GND	-0.3 to (DVDD3 + 0.3)	V
Operating case te	mperature range, T _C	-55 to +125	°C
Maximum junction	n temperature, T _J	+150	°C
Storage temperate	ure range	-65 to +150	°C
ESD, human-body	/ model (HBM)	2	kV

(1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied. Kirkendall voidings and current density information for calculation of expected lifetime are available upon request.

THERMAL CHARACTERISTICS⁽¹⁾

	PARAMETER	TEST CONDITIONS	TYP	UNIT
$R_{\theta JA}$	Junction-to-free-air thermal resistance	Junction-to-case thermal resistance	21.81	°C/W
R_{\thetaJC}	Junction-to-case thermal resistance	MIL-STD-883 Test Method 1012	0.849	°C/W

(1) This CQFP package has built-in vias that electrically and thermally connect the bottom of the die to a pad on the bottom of the package. To efficiently remove heat and provide a low-impedance ground path, a thermal land is required on the surface of the PCB directly underneath the body of the package. During normal surface mount flow solder operations, the heat pad on the underside of the package is soldered to this thermal land creating an efficient thermal path. Normally, the PCB thermal land has a number of thermal vias within it that provide a thermal path to internal copper areas (or to the opposite side of the PCB) that provide for more efficient heat removal. TI typically recommends an 11,9 mm2 board-mount thermal pad. This allows maximum area for thermal dissipation, while keeping leads away from the pad area to prevent solder bridging. A sufficient quantity of thermal/electrical vias must be included to keep the device within recommended operating conditions. This pad must be electrically at ground potential.



TEXAS INSTRUMENTS

www.ti.com

SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013



Figure 1. Operating Life Derating Chart, Electromigration Fail Mode

STRUMENTS

EXAS

RECOMMENDED OPERATING CONDITIONS

		MIN	TYP	MAX	UNIT
SUPPLIE	S				
AVDD5	Analog supply voltage	4.75	5	5.25	V
AVDD3	Analog supply voltage	3.1	3.3	3.6	V
DVDD3	Output driver supply voltage	3	3.3	3.6	V
ANALOG	S INPUT				
	Differential input range		2.2		V _{PP}
VCM	Input common mode		3.1		V
DIGITAL	OUTPUT (DRY, DATA, OVR)				
	Maximum differential output load		10		pF
CLOCK I	NPUT (CLK)				
	CLK input sample rate (sine wave)	20 ⁽¹⁾		400	MSPS
	Clock amplitude, differential sine wave ⁽¹⁾	0.5		5	V _{PP}
	Clock duty cycle ⁽¹⁾	40	50	60	%
Т _С	Operating case temperature range	-55		+125	°C

(1) Parameters are assured by characterization, but not production tested.

ELECTRICAL CHARACTERISTICS

Typical values at $T_C = +25^{\circ}C$: minimum and maximum values over full temperature range $T_{C,MIN} = -55^{\circ}C$ to $T_{C,MAX} = 125^{\circ}C$, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3 V_{PP} differential clock, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
Resolution				14		Bits
ANALOO	G INPUTS					
	Differential input range			2.2		V _{PP}
	Analog input common-mode voltage	Self-biased; see VCM specification below		3.1		V
	Input resistance (dc)	Each input to VCM		500		Ω
	Input capacitance	Each input to GND		7.4		pF
	Analog input bandwidth (–3dB)			1.28		GHz
CMRR	Common-mode rejection ratio	Common-mode signal < 50 MHz (see Figure 28)	100			dB
INTERN	AL REFERENCE VOLTAGE					
VREF	Reference voltage			2.4		V
VCM	Analog input common-mode voltage reference output	With internal VREF. Provided as an output via the VCM pin for dc-coupled applications.	2.9	3.1	3.3	V
	VCM temperature coefficient			-0.8		mV/°C
DYNAMI	CACCURACY					
	No missing codes			Assured		
DNL	Differential linearity error	f _{IN} = 10 MHz	-0.99	±0.7	2.5	LSB
INL	Integral linearity error	f _{IN} = 10 MHz	-7.0	±1.5	7.0	LSB
	Offset error		-16		16	mV
	Offset temperature coefficient			0.02		mV/°C
	Gain error		-5		5	%FS
	Gain temperature coefficient			-0.02		%FS/°C



www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

Typical values at $T_c = +25^{\circ}C$: minimum and maximum values over full temperature range $T_{C,MIN} = -55^{\circ}C$ to $T_{C,MAX} = 125^{\circ}C$, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3 V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER	SUPPLY			· · ·		
I _{AVDD5}	5-V analog supply current			338	380	mA
I _{AVDD3}	3.3-V analog supply current			185	210	mA
I _{DVDD3}	3.3-V digital supply current (includes LVDS)	f _S = 400 MSPS		75	85	mA
	Total power dissipation			2.5	2.835	W
	Power-up time	From turn-on of AVDD5		50		μs
	Wake-up time	From PDWN pin switched from HIGH (PDWN active) to LOW (ADC awake) (see Figure 29)		5		μs
	Power-down power dissipation	PDWN pin = logic HIGH		50	350	mW
PSRR	Power-supply rejection ratio, AVDD5 supply			75		dB
PSRR	Power-supply rejection ratio, AVDD3 supply	Without 0.1 μ F board supply capacitors, with < 1 MHz supply noise		90		dB
PSRR	Power-supply rejection ratio, DVDD3 supply			110		dB
DYNAMI	IC AC CHARACTERISTICS					
		f _{IN} = 30 MHz		70.5		
		f _{IN} = 70 MHz	65	68.7		
		f _{IN} = 130 MHz		69.9		
		f _{IN} = 230 MHz	65	69.8		
SNR	Signal-to-noise ratio	f _{IN} = 351 MHz		69.2		dBFS
		f _{IN} = 451 MHz		68.8		
		f _{IN} = 651 MHz		67.3		
		f _{IN} = 751 MHz		66.6		
		f _{IN} = 999 MHz		64.4		
		f _{IN} = 30 MHz		79.4		
		f _{IN} = 70 MHz	69	76.3		
		f _{IN} = 130 MHz		78.8		
		f _{IN} = 230 MHz	64.5	78		
SFDR	Spurious-free dynamic range	f _{IN} = 351 MHz		74.3		dBc
		f _{IN} = 451 MHz		70.5		
		f _{IN} = 651 MHz		58.6		
		f _{IN} = 751 MHz		54.3		
		f _{IN} = 999 MHz		46		
		f _{IN} = 30 MHz		92		
		f _{IN} = 70 MHz		87		
		f _{IN} = 130 MHz		87		
		f _{IN} = 230 MHz		84		
HD2	Second-harmonic	f _{IN} = 351 MHz		77		dBc
		f _{IN} = 451 MHz		75		
		f _{IN} = 651 MHz		68		
		f _{IN} = 751 MHz		64		
		f _{IN} = 999 MHz		53		



www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

Typical values at $T_C = +25^{\circ}C$: minimum and maximum values over full temperature range $T_{C,MIN} = -55^{\circ}C$ to $T_{C,MAX} = 125^{\circ}C$, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3 V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
DYNAM	IC AC CHARACTERISTICS (continu	ued)		
		f _{IN} = 30 MHz	81	
		f _{IN} = 70 MHz	86	
		f _{IN} = 130 MHz	80	
		f _{IN} = 230 MHz	80	
HD3	Third-harmonic	f _{IN} = 351 MHz	76	dBc
		f _{IN} = 451 MHz	72	
		f _{IN} = 651 MHz	60	
		f _{IN} = 751 MHz	56	
		f _{IN} = 999 MHz	48	1
		f _{IN} = 30 MHz	93	
		f _{IN} = 70 MHz	91	
	f _{IN} = 130 MHz	91		
	f _{IN} = 230 MHz	88		
	Worst harmonic/spur (other than HD2 and HD3)	f _{IN} = 351 MHz	87	dBc
		f _{IN} = 451 MHz	87	
		f _{IN} = 651 MHz	91	
		f _{IN} = 751 MHz	87	
		f _{IN} = 999 MHz	80	
		f _{IN} = 30 MHz	60 56 48 93 91 91 91 88 87 87 87 87 71 73.5 74.9 71.3 68.4	
		f _{IN} = 70 MHz	73.5	1
		f _{IN} = 130 MHz	74.9	1
		f _{IN} = 230 MHz	74.9	
ΉD	Total harmonic distortion	f _{IN} = 351 MHz	71.3	dBc
		f _{IN} = 451 MHz	68.4	1
		f _{IN} = 651 MHz	57.8	1
		f _{IN} = 751 MHz	53.6	1
		f _{IN} = 999 MHz	45	1



www.ti.com

ELECTRICAL CHARACTERISTICS (continued)

Typical values at $T_C = +25^{\circ}C$: minimum and maximum values over full temperature range $T_{C,MIN} = -55^{\circ}C$ to $T_{C,MAX} = 125^{\circ}C$, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, -1 dBFS differential input, and 3 V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DYNAMI	C AC CHARACTERISTICS (continue	ed)		· · ·	1	
		f _{IN} = 30 MHz		69.8		
		f _{IN} = 70 MHz	62.5	67.7		
		f _{IN} = 130 MHz		68.9		
		f _{IN} = 230 MHz	60.5	68.9		
SINAD	Signal-to-noise and distortion	f _{IN} = 351 MHz		67.5		dBc
		f _{IN} = 451 MHz		66.1		
		f _{IN} = 651 MHz		58.2		
		f _{IN} = 751 MHz		54.3		
		f _{IN} = 999 MHz		45.9		
		$f_{IN1} = 69 \text{ MHz}, f_{IN2} = 70 \text{ MHz},$ each tone at -7 dBFS		84.2		
	Two-tone SFDR	$f_{IN1} = 69 \text{ MHz}, f_{IN2} = 70 \text{ MHz},$ each tone at -16 dBFS		98.5		
		f_{IN1} = 297.5 MHz, f_{IN2} = 302.5 MHz, each tone at -7 dBFS		82.5		dBFS
		f_{IN1} = 297.5 MHz, f_{IN2} = 302.5 MHz, each tone at -16 dBFS		99		
		f _{IN} = 70 MHz	10.1	10.9		D'1-
ENOB	Effective number of bits	f _{IN} = 230 MHz	9.77	10.5		Bits
	RMS idle-channel noise	Inputs tied to common-mode		1.8		LSB
LVDS DI	GITAL OUTPUTS	•				
V _{OD}	Differential output voltage (±)		247	350	454	mV
V _{OC}	Common-mode output voltage		1.115		1.375	V
DIGITAL	. INPUTS					
VIH	High level input voltage		2.0			V
V _{IL}	Low level input voltage				0.8	V
I _{IH}	High level input current	PWD (pin 33)			1	μA
IIL	Low level input current		-1			μA
CIN	Input Capacitance			2.2		pF



www.ti.com

TIMING INFORMATION



(1) Polarity of DRY is undetermined. For further information, see the Digital Outputs section.

Figure 2. Timing Diagram

TIMING CHARACTERISTICS⁽¹⁾

Typical values at $T_C = +25^{\circ}$ C: minimum and maximum values over full temperature range $T_{C,MIN} = -55^{\circ}$ C to $T_{C,MAX} = +125^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, AVDD5 = 5 V, AVDD3 = 3.3 V, DVDD3 = 3.3 V, and 3 V_{PP} differential clock, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _a	Aperture delay			200		ps
	Aperture jitter, rms	Internal jitter of the ADC		103		fs
	Latency			3.5		cycles
t _{CLK}	Clock period		2.5		50	ns
t _{CLKH}	Clock pulse duration, high		1			ns
t _{CLKL}	Clock pulse duration, low		1			ns
t _{DRY}	CLK to DRY delay ⁽²⁾	Zero crossing, 10-pF parasitic loading to GND on each output pin	700	1600	2500	ps
t _{DATA}	CLK to DATA/OVR delay ⁽²⁾	Zero crossing, 10-pF parasitic loading to GND on each output pin	650	1600	2600	ps
t _{SKEW}	DATA to DRY skew	$t_{\text{DATA}} - t_{\text{DRY}},$ 10-pF parasitic loading to GND on each output pin	-700	0	700	ps
t _{RISE}	DRY/DATA/OVR rise time	10-pF parasitic loading to GND on each output pin		500		ps
t _{FALL}	DRY/DATA/OVR fall time	10-pF parasitic loading to GND on each output pin		500		ps

(1) Timing parameters are assured by characterization, but not production tested.

(2) DRY, DATA, and OVR are updated on the falling edge of CLK. The latency must be added to t_{DATA} to determine the overall propagation delay.

EXAS

INSTRUMENTS

SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

PIN CONFIGURATION



Submit Documentation Feedback 9



Texas

www.ti.com

Table 1. TERMINAL FUNCTIONS

т	ERMINAL	
NAME	NO.	DESCRIPTION
AIN	17	Differential input signal (positive)
AIN	18	Differential input signal (negative)
AVDD5	4, 9, 14, 15, 20, 23, 25, 27, 29, 33	Analog power supply (5 V)
AVDD3	37, 39, 41	Analog power supply (3.3 V)
DVDD3	2, 54, 70	Digital and output driver power supply (3.3 V)
GND	1,3, 8, 10, 13, 16, 19, 21, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 43, 55, 64, 69	Ground
CLK	11	Differential input clock (positive). Conversion is initiated on rising edge.
CLK	12	Differential input clock (negative)
<u>D0</u> , D0	50, 51	LVDS digital output pair, least-significant bit (LSB)
D1, D1, D2-D5, D6-D7, D8-D12	52, 53, 56–63, 65–68, 71–82	LVDS digital output pairs
D13, D13	81, 82	LVDS digital output pair, most significant bit (MSB)
DRY, DRY	84, 83	Data ready LVDS output pair
NC	5, 6, 46, 47, 48, 49	No connect
OVR, OVR	45, 44	Overrange indicator LVDS output. A logic high signals an analog input in excess of the full-scale range.
VCM	31	Common-mode voltage output (3.1 V nominal). Commonly used in DC-coupled applications to set the input signal to the correct common-mode voltage. (This pin is not used on the ADS5463-SP and ADS5444-SP)
PDWN	35	Power-down (active high). Device is in sleep mode when PDWN pin is logic HIGH. ADC converter is awake when PDWN is logic LOW (grounded). (This pin is not used on the ADS5463-SP and ADS5444-SP)
VREF	7	Reference voltage input/output (2.4 V nominal)





www.ti.com

TYPICAL CHARACTERISTICS

At T_A = +25°C, sampling rate = 400 MSPS, 50% clock duty cycle, 3-V_{PP} differential sinusoidal clock, analog input amplitude = -1 dBFS, AVDD5 = 5 V, AVDD3 = 3.3 V, and DVDD3 = 3.3 V, unless otherwise noted.



Figure 3.







Figure 4.

SPECTRAL PERFORMANCE FFT FOR 230 MHz INPUT SIGNAL



Figure 6.



TYPICAL CHARACTERISTICS (continued)

At T_A = +25°C, sampling rate = 400 MSPS, 50% clock duty cycle, 3-V_{PP} differential sinusoidal clock, analog input amplitude =

100 120

Frequency - MHz

Figure 9.

140 160 180 200

-120

12

0 20 40 60 80

Figure 10.

Frequency - MHz

100 120

140 160 180 200

-120

0 20 40 60 80 INSTRUMENTS

Texas

ADS5474-SP



SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

TYPICAL CHARACTERISTICS (continued)

At $T_A = +25^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, $3 - V_{PP}$ differential sinusoidal clock, analog input amplitude = -1 dBFS, AVDD5 = 5 V, AVDD3 = 3.3 V, and DVDD3 = 3.3 V, unless otherwise noted.







0 finit = 297.5 MHz and 302.5 MHz at -16 dBFS finit = 297.5 MHz, -16 dBFS finit = 297.5 MHz, -16 dBFS













EXAS



TEXAS INSTRUMENTS

SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

www.ti.com



At $T_A = +25^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, 3-V_{PP} differential sinusoidal clock, analog input amplitude = -1 dBFS, AVDD5 = 5 V, AVDD3 = 3.3 V, and DVDD3 = 3.3 V, unless otherwise noted.







Figure 21.



Figure 20.

SFDR vs AVDD5 OVER TEMPERATURE



Figure 22.



TYPICAL CHARACTERISTICS (continued)

Figure 25.



www.ti.com



ADS5474-SP

SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013



At $T_A = +25^{\circ}$ C, sampling rate = 400 MSPS, 50% clock duty cycle, 3-V_{PP} differential sinusoidal clock, analog input amplitude = -1 dBFS, AVDD5 = 5 V, AVDD3 = 3.3 V, and DVDD3 = 3.3 V, unless otherwise noted.











www.ti.com

APPLICATIONS INFORMATION

Theory of Operation

The ADS5474 is a 14-bit, 400-MSPS, monolithic pipeline ADC. Its bipolar analog core operates from 5-V and 3.3-V supplies, while the output uses a 3.3-V supply to provide LVDS-compatible outputs. The conversion process is initiated by the rising edge of the external input clock. At that instant, the differential input signal is captured by the input track-and-hold (T&H), and the input sample is converted sequentially by a series of lower resolution stages, with the outputs combined in a digital correction logic block. Both the rising and the falling clock edges are used to propagate the sample through the pipeline every half clock cycle. This process results in a data latency of 3.5 clock cycles, after which the output data are available as a 14-bit parallel word, coded in offset binary format.

Input Configuration

The analog input for the ADS5474 consists of an analog pseudo-differential buffer followed by a bipolar transistor T&H. The analog buffer isolates the source driving the input of the ADC from any internal switching and presents a high impedance that is easy to drive at high input frequencies, compared to an ADC without a buffered input. The input common-mode is set internally through a 500- Ω resistor connected from 3.1 V to each of the inputs (common-mode is ~2.4V on 12- and 13-bit members of this family). This configuration results in a differential input impedance of 1 k Ω .





For a full-scale differential input, each of the differential lines of the input signal (pins 16 and 17) swings symmetrically between (3.1 V + 0.55 V) and (3.1 V - 0.55 V). This range means that each input has a maximum signal swing of 1.1 V_{PP} for a total differential input signal swing of 2.2 V_{PP}. Operation below 2.2 V_{PP} is allowable, with the characteristics of performance versus input amplitude demonstrated in Figure 19 and Figure 20. For instance, for performance at 1.1 V_{PP} rather than 2.2 V_{PP}, refer to the SNR and SFDR at -6 dBFS (0 dBFS = 2.2 V_{PP}). The maximum swing is determined by the internal reference voltage generator, eliminating the need for any external circuitry for this purpose.



The ADS5474 performs optimally when the analog inputs are driven differentially. The circuit in Figure 31 shows one possible configuration using an RF transformer with termination either on the primary or on the secondary of the transformer. In addition, the evaluation module is configured with two back-to-back transformers, also demonstrating good performance. If voltage gain is required, a step-up transformer can be used.



Figure 31. Converting a Single-Ended Input to a Differential Signal Using an RF Transformer

In addition to the transformer configurations, Texas Instruments offers a wide selection of single-ended operational amplifiers that can be selected depending on the application. An RF gain-block amplifier, such as Texas Instruments' THS9001, can also be used for high-input-frequency applications. For large voltage gains at intermediate-frequencies in the 50 MHz to 400 MHz range, the configuration shown in Figure 32 can be used. The component values can be tuned for different intermediate frequencies. The example shown in Figure 32 is located on the evaluation module and is tuned for an IF of 170 MHz. More information regarding this configuration can be found in the *ADS5474 EVM User Guide* (SLAU194) and the *THS9001 50-MHz to 350-MHz Cascadeable Amplifier* data sheet (SLOS426), both available for download at www.ti.com.



Figure 32. Using the THS9001 IF Amplifier With the ADS5474

TEXAS INSTRUMENTS

www.ti.com

SLAS574A - SEPTEMBER 2013-REVISED DECEMBER 2013

For applications requiring dc-coupling with the signal source, a differential input/differential output amplifier such as the THS4509 (shown in Figure 33) provides good harmonic performance and low noise over a wide range of frequencies.



Figure 33. Using the THS4509 or THS4520 With the ADS5474

In this configuration, the THS4509 amplifier circuit provides 10 dB of gain, converts the single-ended input to differential, and sets the proper input common-mode voltage to the ADS5474 by utilizing the VCM output pin of the ADC. The 50-Ω resistors and 18-pF capacitor between the THS4509 outputs and ADS5474 inputs (along with the input capacitance of the ADC) limit the bandwidth of the signal to about 70 MHz (-3 dB). Input termination is accomplished via the 78.9-Ω resistor and 0.22-µF capacitor to ground, in conjunction with the input impedance of the amplifier circuit. A 0.22-μF capacitor and 49.9-Ω resistor are inserted to ground across the 78.9- Ω resistor and 0.22-µF capacitor on the alternate input to balance the circuit. Gain is a function of the source impedance, termination, and $348-\Omega$ feedback resistor. See the THS4509 data sheet for further component values to set proper 50- Ω termination for other common gains. Because the ADS5474 recommended input common-mode voltage is 3.1 V, the THS4509 operates from a single power-supply input with $V_{S+} = 5$ V and $V_{S_{-}} = 0 V$ (ground). This configuration has the potential to slightly exceed the recommended output voltage from the THS4509 of 3.6V due to the ADC input common-mode of 3.1V and the +0.55V full-scale signal. This will not harm the THS4509 but may result in a degradation in the harmonic performance of the THS4509. An amplifier with a wider recommended output voltage range is the THS4520, which is optimized for low noise and low distortion in the range of frequencies up to ~20 MHz. Applications that are not sensitive to harmonic distortion could consider either device at higher frequencies.



ADS5474-SP

www.ti.com

Clock Inputs

The ADS5474 clock input can be driven with either a differential clock signal or a single-ended clock input. The characterization of the ADS5474 is typically performed with a 3-V_{PP} differential clock, but the ADC performs well with a differential clock amplitude down to ~0.5 V_{PP}, as shown in . The clock amplitude becomes more of a factor in performance as the analog input frequency increases. In low-input-frequency applications, where jitter may not be a big concern, the use of a single-ended clock could save cost and board space without much performance tradeoff. When clocked with this configuration, it is best to connect CLK to ground with a 0.01-µF capacitor, while CLK is ac-coupled with a 0.01-µF capacitor to the clock source, as shown in Figure 35.







Figure 35. Single-Ended Clock

For jitter-sensitive applications, the use of a differential clock has some advantages at the system level. The differential clock allows for common-mode noise rejection at the printed circuit board (PCB) level. With a differential clock, the signal-to-noise ratio of the ADC is better for jitter-sensitive, high-frequency applications because the board level clock jitter is superior.

Larger clock amplitude levels are recommended for high analog input frequencies or slow clock frequencies. In the case of a sinusoidal clock, larger amplitudes result in higher clock slew rates and reduces the impact of clock noise on jitter. At high analog input frequencies, the sampling process is sensitive to jitter. And at slow clock frequencies, a small amplitude sinusoidal clock has a lower slew rate and can create jitter-related SNR degradation. Figure 36 demonstrates a recommended method for converting a single-ended clock source into a differential clock; it is similar to the configuration found on the evaluation board and was used for much of the characterization. See also *Clocking High Speed Data Converters* (SLYT075) for more details.

Copyright © 2013, Texas Instruments Incorporated





Figure 36. Differential Clock

The common-mode voltage of the clock inputs is set internally to 2.4 V using internal 1-k Ω resistors. It is recommended to use ac coupling, but if this scheme is not possible, the ADS5474 features good tolerance to clock common-mode variation. Additionally, the internal ADC core uses both edges of the clock for the conversion process. Ideally, a 50% duty-cycle clock signal should be provided.

The ADS5474 is capable of achieving 69.2 dBFS SNR at 350 MHz of analog input frequency. In order to achieve the SNR at 350 MHz the clock source rms jitter must be at least 144 fsec in order for the total rms jitter to be 177 fsec. A summary of maximum recommended rms clock jitter as a function of analog input frequency is provided in Table 2. The equations used to create the table are also presented.

INPUT FREQUENCY (MHz)	MEASURED SNR (dBc)	TOTAL JITTER (fsec rms)	MAXIMUM CLOCK JITTER (fsec rms)
30	69.3	1818	1816
70	69.1	798	791
130	69.1	429	417
230	68.8	251	229
350	68.2	177	144
450	67.4	151	110
750	65.6	111	42
1000	63.7	104	14

Table 2. Recommended RMS Clock Jitter

Equation 1 and Equation 2 are used to estimate the required clock source jitter.

SNR (dBc) = -20 \times LOG10 (2 \times π \times f_{IN} \times $j_{\text{TOTAL}})$

 $j_{TOTAL} = (j_{ADC}^{2} + j_{CLOCK}^{2})^{1/2}$

where:

j_{TOTAL} = the rms summation of the clock and ADC aperture jitter;

 j_{ADC} = the ADC internal aperture jitter which is located in the data sheet;

 j_{CLOCK} = the rms jitter of the clock at the clock input pins to the ADC; and

 f_{IN} = the analog input frequency.

Notice that the SNR is a strong function of the analog input frequency, not the clock frequency. The slope of the clock source edges can have a mild impact on SNR as well and is not taken into account for these estimates. For this reason, maximizing clock source amplitudes at the ADC clock inputs is recommended, though not required (faster slope is desirable for jitter-related SNR). For more information on clocking high-speed ADCs, see Application Note SLWA034, *Implementing a CDC7005 Low Jitter Clock Solution For High-Speed, High-IF ADC Devices*, on the Texas Instruments web site. Recommended clock distribution chips (CDCs) are the TI CDC7005, the CDCM7005-SP and CDCE72010. Depending on the jitter requirements, a band pass filter (BPF) is sometimes required between the CDC and the ADC. If the insertion loss of the BPF causes the clock amplitude to be too low for the ADC, or the clock source amplitude is too low to begin with, an inexpensive amplifier can be placed between the CDC and the BPF.

(1)

(2)



SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

Figure 37 represents a scenario where an LVCMOS single-ended clock output is used from a TI CDCM7005-SP with the clock signal path optimized for maximum amplitude and minimum jitter. This type of conditioning might generally be well-suited for use with greater than 150 MHz of input frequency. The jitter of this setup is difficult to estimate and requires a careful phase noise analysis of the clock path. The BPF (and possibly a low-cost amplifier because of insertion loss in the BPF) can improve the jitter between the CDC and ADC when the jitter provided by the CDC is still not adequate. The total jitter at the CDCM7005-SP output depends largely on the phase noise of the VCXO selected, as well as the CDCM7005-SP, and typically has 50–100 fs of rms jitter. If it is determined that the jitter from the CDCM7005-SP with a VCXO is sufficient without further conditioning, it is possible to clock the ADS5474 directly from the CDCM7005-SP using differential LVPECL outputs, as illustrated in Figure 38 (see the CDCM7005-SP data sheet for the exact schematic). This scenario may be more suitable for less than 150 MHz of input frequency where jitter is not as critical. A careful analysis of the required jitter is recommended before determining the proper approach.



This is an example block diagram.

Consult the CDCM7005 data sheet for proper schematic and specifications regarding allowable input and output frequency and amplitude ranges.

Figure 37. Optimum Jitter Clock Circuit

24

INSTRUMENTS

Texas

Copyright © 2013, Texas Instruments Incorporated





This is an example block diagram.

Low-Jitter Clock Distribution

Consult the CDCM7005 data sheet for proper schematic and specifications regarding allowable input and output frequency and amplitude ranges.

Figure 38. Acceptable Jitter Clock Circuit

Digital Outputs

The ADC provides 14 LVDS-compatible, offset binary data outputs (D13 to D0; D13 is the MSB and D0 is the LSB), a data-ready signal (DRY), and an over-range indicator (OVR). It is recommended to use the DRY signal to capture the output data of the ADS5474. DRY is source-synchronous to the DATA/OVR outputs and operates at the same frequency, creating a half-rate DDR interface that updates data on both the rising and falling edges of DRY. It is recommended that the capacitive loading on the digital outputs be minimized. Higher capacitance shortens the data-valid timing window. The values given for timing (see Figure 2) were obtained with a measured 10-pF parasitic board capacitance to ground on each LVDS line (or 5-pF differential parasitic capacitance). When setting the time relationship between DRY and DATA at the receiving device, it is generally recommended that setup time be maximized, but this partially depends on the setup and hold times of the device receiving the digital data (like an FPGA or Field Programmable Field Array). Since DRY and DATA are coincident, it will likely be necessary to delay either DRY or DATA such that setup time is maximized.

Referencing Figure 2, the polarity of DRY with respect to the sample N data output transition is undetermined because of the unknown startup logic level of the clock divider that generates the DRY signal (DRY is a frequency divide-by-two of CLK). Either the rising or the falling edge of DRY will be coincident with sample N and the polarity of DRY could invert when power is cycled off/on or when the power-down pin is cycled. Data capture from the transition and not the polarity of DRY is recommended, but not required. If the synchronization of multiple ADS5474 devices is required, it might be necessary to use a form of the CLKIN signal rather than DRY to capture the data.

The DRY frequency is identical on the ADS5474 and ADS5463 (where DRY equals ¹/₂ the CLK frequency), but different than it is on the pin-similar ADS5444 (where DRY equals the CLK frequency). The LVDS outputs all require an external 100- Ω load between each output pair in order to meet the expected LVDS voltage levels. For long trace lengths, it may be necessary to place a 100- Ω load on each digital output as close to the ADS5474 as possible and another 100-Ω differential load at the end of the LVDS transmission line to provide matched impedance and avoid signal reflections. The effective load in this case reduces the LVDS voltage levels by half.

The OVR output equals a logic high when the 14-bit output word attempts to exceed either all 0s or all 1s. This flag is provided as an indicator that the analog input signal exceeded the full-scale input limit of approximately 2.2 V_{PP} (± gain error). The OVR indicator is provided for systems that use gain control to keep the analog input signal within acceptable limits.



Power Supplies

www.ti.com

The ADS5474 uses three power supplies. For the analog portion of the design, a 5-V and 3.3-V supply (AVDD5 and AVDD3) are used, while the digital portion uses a 3.3-V supply (DVDD3). The use of low-noise power supplies with adequate decoupling is recommended. Linear supplies are preferred to switched supplies; switched supplies tend to generate more noise components that can be coupled to the ADS5474. The user may be able to supply power to the device with a less-than-ideal supply and still achieve good performance. It is not possible to make a single recommendation for every type of supply and level of decoupling for all systems. The power consumption of the ADS5474 does not change substantially over clock rate or input frequency as a result of the architecture and process.

Because there are two diodes connected in reverse between AVDD3 and DVDD3 internally, a power-up sequence is recommended. When there is a delay in power up between these two supplies, the one that lags could have current sinking through an internal diode before it powers up. The sink current can be large or small depending on the impedance of the external supply and could damage the device or affect the supply source.

The best power up sequence is one of the following options (regardless of when AVDD5 powers up):

1) Power up both AVDD3 and DVDD3 at the same time (best scenario), OR

2) Keep the voltage difference less than 0.8V between AVDD3 and DVDD3 during the power up (0.8V is not a hard specification - a smaller delta between supplies is safer).

If the above sequences are not practical then the sink current from the supply needs to be controlled or protection added externally. The max transient current (on the order of µsec) for DVDD3 or AVDD3 pin is 500mA to avoid potential damage to the device or reduce its lifetime.

Values for analog and clock input given in the Absolute Maximum Ratings are valid when the supplies are on. When the power supplies are off and the clock or analog inputs are still alive, the input voltage and current needs to be limited to avoid device damage. If the ADC supplies are off, the max/min continuous DC voltage is +/- 0.95 V and max DC current is 20 mA for each input pin (clock or analog), relative to ground.



Figure 39. PSRR vs Supply Injected Frequency



DEFINITION OF SPECIFICATIONS

Analog Bandwidth

The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low-frequency value.

Aperture Delay

The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

Aperture Uncertainty (Jitter)

The sample-to-sample variation in aperture delay.

Clock Pulse Duration/Duty Cycle

The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse duration) to the period of the clock signal, expressed as a percentage.

Differential Nonlinearity (DNL)

An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. DNL is the deviation of any single step from this ideal value, measured in units of LSB.

Common-Mode Rejection Ratio (CMRR)

CMRR measures the ability to reject signals that are presented to both analog inputs simultaneously. The injected common-mode frequency level is translated into dBFS, the spur in the output FFT is measured in dBFS, and the difference is the CMRR in dB.

Effective Number of Bits (ENOB)

ENOB is a measure in units of bits of converter performance as compared to the theoretical limit based on quantization noise:

ENOB = (SINAD - 1.76)/6.02 (3)

Gain Error

Gain error is the deviation of the ADC actual input full-scale range from its ideal value, given as a percentage of the ideal input full-scale range.

Integral Nonlinearity (INL)

INL is the deviation of the ADC transfer function from a best-fit line determined by a least-squares curve fit of that transfer function. The INL at each analog input value is the difference between the actual transfer function and this best-fit line, measured in units of LSB.

Offset Error

Offset error is the deviation of output code from midcode when both inputs are tied to common-mode.

Power-Supply Rejection Ratio (PSRR)

PSRR is a measure of the ability to reject frequencies present on the power supply.

The injected frequency level is translated into dBFS, the spur in the output FFT is measured in dBFS, and the difference is the PSRR in dB. The measurement calibrates out the benefit of the board supply decoupling capacitors.

Signal-to-Noise Ratio (SNR)

SNR is the ratio of the power of the fundamental (P_S) to the noise floor power (P_N), excluding the power at dc and in the first five harmonics.

$$SNR = 10\log_{10} \frac{P_S}{P_N}$$
(4)

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

Signal-to-Noise and Distortion (SINAD)

SINAD is the ratio of the power of the fundamental (P_S) to the power of all the other spectral components including noise (P_N) and distortion (P_D) , but excluding dc.

$$SINAD = 10\log_{10} \frac{P_S}{P_N + P_D}$$
(5)

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

Temperature Drift

Temperature drift (with respect to gain error and offset error) specifies the change from the value at the nominal temperature to the value at T_{MIN} or T_{MAX} . It is computed as the maximum variation the parameters over the whole temperature range divided by $T_{MIN} - T_{MAX}$.

Total Harmonic Distortion (THD)

THD is the ratio of the power of the fundamental (P_S) to the power of the first five harmonics (P_D).

$$\Gamma HD = 10 \log_{10} \frac{P_S}{P_D}$$
(6)

THD is typically given in units of dBc (dB to carrier).

Two-Tone Intermodulation Distortion (IMD3)

IMD3 is the ratio of the power of the fundamental (at frequencies f_1 , f_2) to the power of the worst spectral component at either frequency $2f_1 - f_2$ or $2f_2 - f_1$). IMD3 is given in units of either dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.



SLAS574A - SEPTEMBER 2013 - REVISED DECEMBER 2013

REVISION HISTORY

Texas Instruments

www.ti.com

PACKAGE MATERIALS INFORMATION

5-Jan-2022

TRAY



Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	K0 (µm)	P1 (mm)	CL (mm)	CW (mm)
ADS5474HFG/EM	HFG	CFP	84	1	2 x 5	150	315	135.9	7620	57	43.5	39.45

HFG (S-CQFP-F84)

CERAMIC QUAD FLATPACK WITH NCTB



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Ceramic quad flatpack with flat leads brazed to non-conductive tie bar carrier.
- D. This package is hermetically sealed with a metal lid.
- E. The leads are gold plated and can be solderdipped.
- F. Leads not shown for clarity purposes.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2022, Texas Instruments Incorporated