LIN Transceiver with 3.3 V or 5 V Voltage Regulator

General Description

The NCV7420 is a fully featured local interconnect network (LIN) transceiver designed to interface between a LIN protocol controller and the physical bus. The transceiver is implemented in I3T technology enabling both high-voltage analog circuitry and digital functionality to co-exist on the same chip.

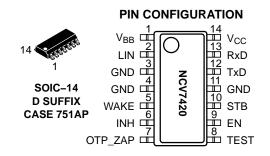
The NCV7420 LIN device is a member of the in–vehicle networking (IVN) transceiver family of ON Semiconductor that integrates a LIN v2.0/2.1 physical transceiver and either a 3.3 V or a 5 V voltage regulator.

The LIN bus is designed to communicate low rate data from control devices such as door locks, mirrors, car seats, and sunroofs at the lowest possible cost. The bus is designed to eliminate as much wiring as possible and is implemented using a single wire in each node. Each node has a slave MCU–state machine that recognizes and translates the instructions specific to that function. The main attraction of the LIN bus is that all the functions are not time critical and usually relate to passenger comfort.



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ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 19 of this data sheet.

KEY FEATURES

LIN-Bus Transceiver

- LIN compliant to specification revision 2.0 and 2.1 (backward compatible to version 1.3) and J2602
- I3T high voltage technology
- Bus voltage ±45 V
- Transmission rate up to 20 kBaud

Protection

- Thermal shutdown
- Indefinite short–circuit protection on pins LIN and WAKE towards supply and ground
- Load dump protection (45 V)
- Bus pins protected against transients in an automotive environment
- \bullet System ESD protection level for LIN, WAKE and V_{BB} up to $\pm 12~kV$

Voltage Regulator

- \bullet Output voltage 5 V / ~50 mA or 3.3 V / ~50 mA
- Wake-up input
- Enable inputs for standby and sleep mode
- INH output for auxiliary purposes (switching of an external pull-up or resistive divider towards battery, control of an external voltage regulator etc.)

EMI Compatibility

- Integrated slope control
- Meets most demanding EMS/EME requirements

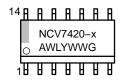
Modes

- Normal mode: LIN communication in either low (up to 10 kBaud) or normal slope
- Sleep mode: V_{CC} is switched "off" and no communication on LIN bus
- Standby mode: V_{CC} is switched "on" but there is no communication on LIN bus
- Wake-up bringing the component from sleep mode into standby mode is possible either by LIN command or digital input signal on WAKE pin. Wake-up from LIN bus can also be detected and flagged when the chip is already in standby mode.

Quality

- NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Require ments; AEC-Q100 Qualified and PPAP Capable
- These Devices are Pb–Free, Halogen Free/BFR Free and are RoHS Compliant

MARKING DIAGRAM



NCV7420 = Specific Device Code -x = -3 = NCV7420D23G -4 = NCV7420D24G -5 = NCV7420D25G -6 = NCV7420D26G

A = Assembly Location

WL = Wafer Lot
 Y = Year
 WW = Work Week
 G = Pb-Free Package

Table 1. KEY TECHNICAL CHARACTERISTICS - 3.3 V version

Symbol	Parameter	Min	Тур	Max	Unit
V _{BB}	Nominal battery operating voltage (Note 1)	5	12	26	V
	Load dump protection (Note 2)			45	
I _{BB_SLP}	Supply current in sleep mode			20	μΑ
V _{CC_OUT}	Regulated V _{CC} output, V _{CC} load 1 mA-30 mA	3.23	3.30	3.37	V
(Note 4)	Regulated V _{CC} output, V _{CC} load 0 mA-50 mA	3.19	3.30	3.41	1
I _{OUT_MAX}	Maximum V _{CC} output current (Note 3)	50			mA
V _{WAKE}	Operating DC voltage on WAKE pin	0		V_{BB}	V
	Maximum rating voltage on WAKE pin	-45		45	
T _{JSD}	Junction thermal shutdown temperature	165		195	°C
T_J	Operating junction temperature	-40		+150	°C

Table 2. KEY TECHNICAL CHARACTERISTICS - 5 V version

Symbol	Parameter	Min	Тур	Max	Unit
V_{BB}	Nominal battery operating voltage (Note 1)	6	12	26	V
	Load dump protection			45	1
I _{BB_SLP}	Supply current in sleep mode			20	μΑ
V _{CC_OUT} (Note 4)	Regulated V _{CC} output, V _{CC} load 1 mA-30 mA	4.9	5.0	5.1	V
(Note 4)	Regulated V _{CC} output, V _{CC} load 0 mA-50 mA	4.83	5.0	5.17	
I _{OUT_MAX}	Maximum V _{CC} output current (Note 3)	50			mA
V_{WAKE}	Operating DC voltage on WAKE pin	0		V_{BB}	V
	Maximum rating voltage on WAKE pin	-45		45	
T _{JSD}	Junction thermal shutdown temperature	165		195	°C
TJ	Operating junction temperature	-40		+150	°C

^{1.} Below 5 V on V_{BB} in normal mode, the bus will either stay recessive or comply with the voltage level specifications and transition time specifications as required by SAE J2602. It is ensured by the battery monitoring circuit.

Table 3. THERMAL CHARACTERISTICS

Symbol	Parameter	Conditions	Value	Unit
$R_{\theta JA1}$	Thermal resistance junction–to–ambient, 1S0P PCB (Note 5)	free air	140	K/W
$R_{\theta JA}2$	Thermal resistance junction-to-ambient, 2S2P PCB (Note 6)	free air	80	K/W

^{5.} Test board according to EIA/JEDEC Standard JESD51-3, signal layer with 20% trace coverage

^{2.} The applied transients shall be in accordance with ISO 7637 part 1, test pulse 5. The device complies with functional class C; class A can be reached depending on the application and external conditions.

^{3.} Thermal aspects of the entire end-application have to be taken into account in order to avoid thermal shutdown of NCV7420.

^{4.} V_{CC} voltage regulator output must be properly decoupled by external capacitor of min. 8 μ F with ESR < 1 Ω to ensure stability.

^{6.} Test board according to EIA/JEDEC Standard JESD51-7, signal layers with 20% trace coverage

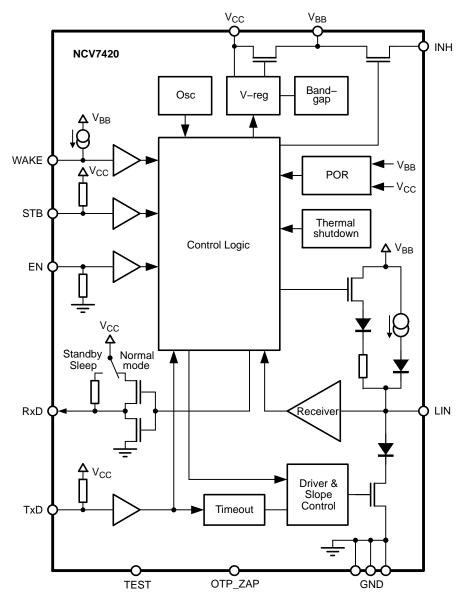


Figure 1. Block Diagram

Typical Application

Application Schematic

The EMC immunity of the Master-mode device can be further enhanced by adding a capacitor between the LIN output and ground. The optimum value of this capacitor is

determined by the length and capacitance of the LIN bus, the number and capacitance of Slave devices, the pull-up resistance of all devices (Master & Slave), and the required time constant of the system, respectively.

 V_{CC} voltage must be properly stabilized by external capacitor: capacitor of min. 8 μF (ESR < 1 $\Omega).$

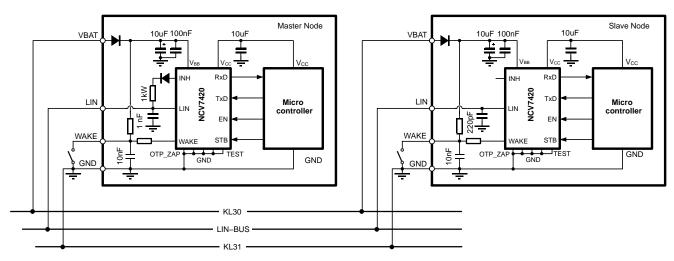


Figure 2. Typical Application Diagram

Table 4. PIN DESCRIPTION

Pin	Name	Description
1	V_{BB}	Battery supply input
2	LIN	LIN bus output/input
3	GND	Ground
4	GND	Ground
5	WAKE	High voltage digital input pin to switch the part from sleep– to standby mode
6	INH	Inhibit output
7	OTP_ZAP	Supply for programming of trimming bits at factory testing, should be grounded in the application
8	TEST	Digital input for factory testing, should be grounded in the application
9	EN	Enable input, transceiver in normal operation mode when high
10	STB	Standby mode control input
11	GND	Ground
12	TxD	Transmit data input, low in dominant state
13	RxD	Receive data output; low in dominant state; push-pull output
14	V _{CC}	Supply voltage (output)

Overall Functional Description

LIN is a serial communication protocol that efficiently supports the control of mechatronic nodes in distributed automotive applications. The domain is class—A multiplex buses with a single master node and a set of slave nodes.

NCV7420 is designed as a master or slave node for the LIN communication interface with an integrated 3.3 V or 5 V voltage regulator having a current capability up to 50 mA for supplying any external components (microcontroller).

NCV7420 contains the LIN transmitter, LIN receiver, voltage regulator, power–on–reset (POR) circuits and thermal shutdown (TSD). The LIN transmitter is optimized for the maximum specified transmission speed of 20 kBaud

with EMC performance due to reduced slew rate of the LIN output.

The junction temperature is monitored via a thermal shutdown circuit that switches the LIN transmitter and voltage regulator off when temperature exceeds the TSD trigger level.

NCV7420 has four operating states (normal mode, low slope mode, standby mode, and sleep mode) that are determined by the input signals EN, WAKE, STB, and TxD.

Operating States

NCV7420 provides four operating states, two modes for normal operation with communication, one standby without communication and one low power mode with very low current consumption. See Figure 3.

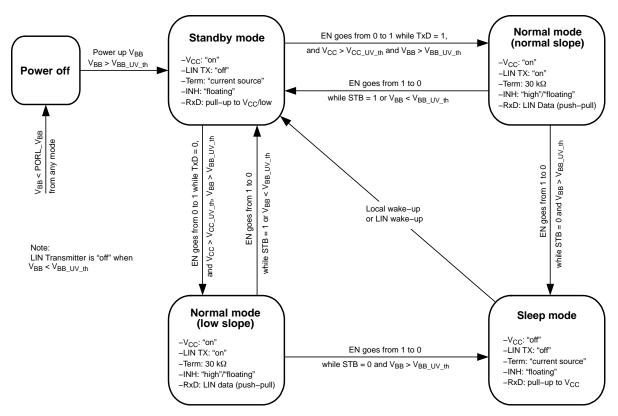


Figure 3. State Diagram

Table 5. MODE SELECTION

Mode	V _{CC}	RxD	INH	LIN	30 kΩ on LIN	Note
Normal – Slope	ON	Low = Dominant State High = Recessive State	High if STB=High during state transition; Floating otherwise	Normal Slope	ON	(Note 7)
Normal – Low Slope	ON	Low = Dominant State High = Recessive State	High if STB=High during state transition; Floating otherwise	Low Slope	ON	(Note 8)
Standby	ON	Low after LIN wake-up, high otherwise	Floating	OFF	OFF	(Notes 9 and 10)
Sleep	OFF	Clamped to V _{CC}	Floating	OFF	OFF	

- 7. The normal slope mode is entered when pin EN goes HIGH while TxD is in HIGH state during EN transition.
- 8. The low slope mode is entered when pin EN goes HIGH while TxD is in LOW state during EN transition. LIN transmitter gets on only after TxD returns to high after the state transition.
- 9. The standby mode is entered automatically after power-up.
- 10. In standby mode, RxD High state is achieved by internal pull-up resistor to V_{CC}.

Normal Slope Mode

In normal slope mode the transceiver can transmit and receive data via LIN bus with speed up to 20 kBaud. The transmit data stream of the LIN protocol is present on the TxD pin and converted by the transmitter into a LIN bus signal with controlled slew rate to minimize EMC emission. The receiver consists of the comparator that has a threshold with hysteresis in respect to the supply voltage and an input filter to remove bus noise. The LIN output is pulled HIGH via an internal 30 k Ω pull-up resistor. For master applications it is needed to put an external 1 k Ω resistor with a serial diode between LIN and V_{BB} (or INH). See Figure 2. The mode selection is done by EN=HIGH when TxD pin is

HIGH. If STB pin is high during the standby-to-normal slope mode transition, INH pin is pulled high. Otherwise, it stays floating.

Low Slope Mode

In low slope mode the slew rate of the signal on the LIN bus is reduced (rising and falling edges of the LIN bus signal are longer). This further reduces the EMC emission. As a consequence the maximum speed on the LIN bus is reduced up to 10 kBaud. This mode is suited for applications where the communication speed is not critical. The mode selection is done by EN=HIGH when TxD pin is LOW. In order not to transmit immediately a dominant state on the bus (because

TxD=LOW), the LIN transmitter is enabled only after TxD returns to HIGH. If STB pin is high during the standby-to-low slope mode transition, INH pin is pulled high. Otherwise, it stays floating.

Standby Mode

The standby mode is always entered after power–up of the NCV7420. It can also be entered from normal mode when the EN pin is low and the standby pin is high. From sleep mode it can be entered after a local wake–up or LIN wake–up. In standby mode the V_{CC} voltage regulator for supplying external components (e.g. a microcontroller) stays active. Also the LIN receiver stays active to be able to detect a remote wake–up via bus. The LIN transmitter is disabled and the slave internal termination resistor of 30 $k\Omega$ between LIN and V_{BB} is disconnected in order to minimize current consumption. Only a pull–up current source between V_{BB} and LIN is active.

Sleep Mode

The Sleep Mode provides extreme low current consumption. This mode is entered when both EN and STB pins are LOW coming from normal mode. The internal termination resistor of 30 k Ω between LIN and V_{BB} is disconnected and also the V_{CC} regulator is switched off to minimize current consumption.

Wake-up

NCV7420 has two possibilities to wake—up from sleep or standby mode (see Figure 3):

- Local wake-up: enables the transition from sleep mode to standby mode
- Remote wake—up via LIN: enables the transition from sleep— to standby mode and can be also detected when already in standby mode.

A local wake-up is **only** detected in sleep mode if a transition from LOW to HIGH or from HIGH to LOW is seen on the WAKE pin.

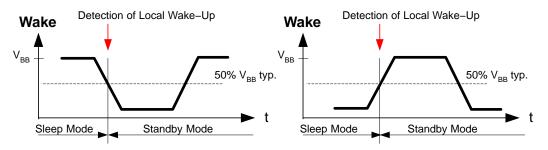


Figure 4. Local Wake-up Signal

A remote wake—up is **only** detected if a combination of (1) a falling edge at the LIN pin (transition from recessive to dominant) is followed by (2) a dominant level maintained

for a time period > t_{WAKE} and (3) again a rising edge at pin LIN (transition from dominant to recessive) happens.

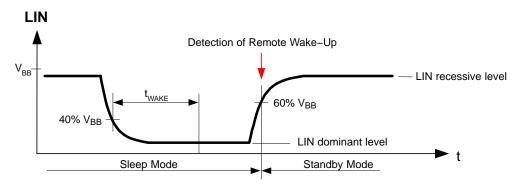


Figure 5. Remote Wake-up Behavior

The wake-up source is distinguished by pin RxD in the standby mode:

- RxD remains HIGH after power-up or local wake-up.
- RxD is kept LOW until normal mode is entered after a remote wake-up (LIN).

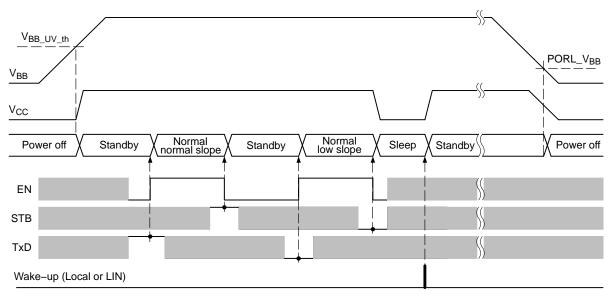


Figure 6. Operating Modes Transitions

Electrical Characteristics

Definitions

All voltages are referenced to GND (Pin 11). Positive currents flow into the IC.

Table 6. ABSOLUTE MAXIMUM RATINGS - 3.3 V and 5 V versions

Symbol	Parameter	Min	Max	Unit
V_{BB}	Battery voltage on pin V _{BB} (Note 11)	-0.3	+45	V
V _{CC}	DC voltage on pin V _{CC}	0	+7	V
I _{VCC}	Current delivered by the V _{CC} regulator	50		mA
V_{LIN}	LIN bus voltage (Note 12)	-45	+45	V
V_{INH}	DC voltage on inhibit pin	-0.3	V _{BB} + 0.3	V
V_{WAKE}	DC voltage on WAKE pin	-45	45	V
V _{DIG_IN}	DC input voltage on pins TxD, RxD, EN, STB	-0.3	V _{CC} + 0.3	V
TJ	Maximum junction temperature	-40	+165	°C
V _{ESD}	Electrostatic discharge voltage on all pins; HBM (Note 13)	-2	+2	kV
	Electrostatic discharge voltage on LIN, INH, WAKE and V _{BB} towards GND; HBM (Note 13)	-4	+4	kV
	Electrostatic discharge on LIN, WAKE and V _{BB} ; system HBM (Note 14)	-8	+8	kV
	Electrostatic discharge voltage on all pins; CDM (Note 16)	-500	+500	V
V _{ESD}	Electrostatic discharge voltage on all pins; HBM (Note 13)	-4	+4	kV
(EMC/ESD improved	Electrostatic discharge voltage on LIN, INH, WAKE and V _{BB} towards GND; HBM (Note 13)	-6	+6	kV
versions)	Electrostatic discharge on LIN, WAKE and V _{BB} ; system HBM (Note 15)	-12	+12	kV
	Electrostatic discharge voltage on all pins; CDM (Note 16)	-750	+750	V

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

^{11.} The applied transients shall be in accordance with ISO 7637 part 1, test pulses 1, 2, 3a, 3b, and 5. The device complies with functional class C; class A can be reached depending on the application and external components.

^{12.} The applied transients shall be in accordance with ISO 7637 part 1, test pulses 1, 2, 3a, and 3b. The device complies with functional class C; class A can be reached depending on the application and external components.

^{13.} Equivalent to discharging a 100 pF capacitor through a 1500 Ω resistor.

^{14.} Equivalent to discharging a 150 pF capacitor through a 330 Ω resistor conform to IEC Standard 61000–4–2. LIN bus filter 220 pF, V_{BB} blocking capacitor 100 nF, 3k3/10n R/C network on WAKE.

^{15.} Equivalent to discharging a 150 pF capacitor through a 330 Ω resistor conform to IEC Standard 61000–4–2. No filter on LIN, V_{BB} blocking capacitor 100 nF, 3k3/10n R/C network on WAKE.

^{16.} Charged device model according ESD-STM5.3.1.

Table 7. DC CHARACTERISTICS - 3.3 V version

 $(V_{BB} = 5 \text{ V to } 26 \text{ V}; T_{J} = -40 ^{\circ}\text{C} \text{ to } +150 ^{\circ}\text{C}; \text{ Bus Load} = 500 \ \Omega \text{ (V}_{BB} \text{ to LIN)}; \text{ unless otherwise specified.)}$

Symbol	Parameter	Conditions	Min	Тур	Max	Uni
SUPPLY – Pin V _{BB}	3		•		•	
I _{BB_ON}	Supply current	Normal mode; LIN recessive			1.6	mA
I _{BB_STB}	Supply current	Standby mode, V _{BB} = 5–18 V, T _J < 105°C			70	μΑ
I _{BB_SLP}	Supply current	Sleep mode, $V_{BB} = 5-18 \text{ V}$, $T_J < 105^{\circ}\text{C}$			20	μΑ
OLTAGE REGUL	ATOR – Pin V _{CC}	•	•			
V _{CC_OUT}	Regulator output voltage	V _{CC} load 1 mA – 30 mA	3.23	3.30	3.37	V
		V _{CC} load 0 mA – 50 mA	3.19	3.30	3.41	
I _{OUT_MAX_ABS}	Absolute maximum output current	Thermal shutdown must be taken into account			50	m/
I _{OUT_LIM}	Overcurrent limitation		50	100	170	m/
ΔV_{CC_OUT}	Line Regulation (Note 22)	$V_{BB} 5-26 \text{ V, } I_{OUT} = 5 \text{ mA,}$ $T_{J} = 25^{\circ}\text{C}$		0.5		m\
	Load Regulation (Note 22)	I_{OUT} 1–50 mA, V_{BB} = 14 V, T_{J} = 25°C		45		m\
V _{DO}	Dropout Voltage (V _{BB} -V _{CC_OUT})	I _{OUT} = 1 mA, T _J = 25°C		13		m\
	Figure 11, (Notes 21, 22)	I _{OUT} = 10 mA, T _J = 25°C		134		m\
		I _{OUT} = 50 mA, T _J = 25°C		732		m\
IN TRANSMITTE	R – Pin LIN					
$V_{LIN_dom_LoSup}$	LIN dominant output voltage	$TxD = low; V_{BB} = 7.3 V$			1.2	V
$V_{LIN_dom_HiSup}$	LIN dominant output voltage	$TxD = low; V_{BB} = 18 V$			2.0	V
V_{LIN_REC}	LIN Recessive Output Voltage (Note 17)	TxD = high; $I_{LIN} = 10 \mu A$	V _{BB} – 1.5		V_{BB}	V
I _{LIN_lim}	Short circuit current limitation	$V_{LIN} = V_{BB_MAX}$	40		200	m/
R _{SLAVE}	Internal pull-up resistance		20	33	47	k۵
C _{LIN}	Capacitance on pin LIN (Note 19)			15	25	рF
IN RECEIVER - F	Pin LIN					
V _{bus_dom}	Bus voltage for dominant state				0.4	V _B
V _{bus_rec}	Bus voltage for recessive state		0.6			V _B
V _{rec_dom}	Receiver threshold	LIN bus recessive \rightarrow dominant	0.4		0.6	V _B
V _{rec_rec}	Receiver threshold	LIN bus dominant \rightarrow recessive	0.4		0.6	V _B
V _{rec_cnt}	Receiver centre voltage	(Vrec_dom + Vrec_rec) / 2	0.475		0.525	V _B
V _{rec_hys}	Receiver hysteresis	(Vrec_rec - Vrec_dom)	0.05		0.175	V _B
I _{LIN_off_dom}	LIN output current bus in dominant state	Driver off; $V_{BB} = 12 \text{ V}$, $V_{LIN} = 0 \text{ V}$	-1			m/
I _{LIN_off_rec}	LIN output current bus in recessive state	Driver off; V _{BB} < 18 V V _{BB} < V _{LIN} < 18 V			1	μA
I _{LIN_no_GND}	Communication not affected	V _{BB} = GND = 12 V; 0 < V _{LIN} < 18 V	-1		1	m

 $^{17.} The \ voltage \ drop \ in \ Normal \ mode \ between \ LIN \ and \ V_{BB} \ pin \ is \ the \ sum \ of \ the \ diode \ drop \ and \ the \ drop \ at \ serial \ pull-up \ resistor. \ The \ drop \$ at the switch is negligible. See Figure 1.

18. By one of the trimming bits, following reconfiguration can be done during chip–level testing in order to fit the NCV7420–3 into different

interface: pins TxD and EN will have typ. 10 $k\Omega$ pull-down resistor to ground and pin WAKE will have typ. 10 μ A pull-up current source.

^{19.} Guaranteed by design. Not tested.

^{20.} V_{BB} undervoltage threshold is always higher than V_{BB} POR low level ($V_{BB_UV_th} > PORL_V_{BB}$) 21. Measured at output voltage $V_{CC_OUT} = (V_{CC_OUT}@V_{BB} = 5 \text{ V}) - 2\%$. 22. Values based on design and characterization. Not tested in production.

Table 7. DC CHARACTERISTICS - 3.3 V version

 $(V_{BB} = 5 \text{ V to } 26 \text{ V}; T_{J} = -40 ^{\circ}\text{C} \text{ to } +150 ^{\circ}\text{C}; \text{ Bus Load} = 500 \ \Omega \text{ (V}_{BB} \text{ to LIN)}; \text{ unless otherwise specified.)}$

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
LIN RECEIVER -	Pin LIN					
I _{LIN_no_VBB}	LIN bus remains operational	$V_{BB} = GND = 0 V;$ 0 < V_{LIN} < 18 V			5	μΑ
Pin WAKE			•		•	
V_{WAKE_th}	Threshold voltage		0.35		0.65	V_{BB}
I _{LEAK}	Input leakage current (Note 18)	V _{WAKE} = 0 V; V _{BB} = 18 V	-1	-0.5	1	μΑ
t _{WAKE_MIN}	Debounce time	Sleep mode; rising and falling edge	8		54	μS
Pins TxD and ST	В		•		•	•
V _{IL}	Low level input voltage				0.8	V
V _{IH}	High level input voltage		2.0			V
R _{PU}	Pull–up resistance to V _{CC} (Note 18)		50		200	kΩ
Pin INH				-		
Delta_V _H	High level voltage drop	I _{INH} = 15 mA		0.35	0.75	V
I _{LEAK}	Leakage current	Sleep mode; V _{INH} = 0 V	-1		1	μΑ
Pin EN						
V _{IL}	Low level input voltage				0.8	V
V _{IH}	High level input voltage		2.0			V
R _{PD}	Pull-down resistance to ground (Note 18)		50		200	kΩ
Pin RxD						
V_{OL}	Low level output voltage	I _{SINK} = 2 mA			0.65	V
V_{OH}	High level output voltage (In Normal mode)	Normal mode, $I_{SOURCE} = -2 \text{ mA}$	V _{CC} – 0.65 V			V
R _{PU}	Pull-up resistance to V _{CC} (In Standby and Sleep mode)	Standby mode, Sleep mode	5	10	15	kΩ
POR AND VOLTA	AGE MONITOR		•		•	•
V _{BB_UV_th}	V _{BB} undervoltage threshold (Note 20)		3	4.2	4.75	V
PORL_V _{BB}	V _{BB} POR low level comparator	NCV7420D23	2.5		4.2	V
		NCV7420D24	1.7		3.8	V
V _{CC_UV_th}	V _{CC} undervoltage threshold		2		3	V
THERMAL SHUT	DOWN					
T _{JSD}	Thermal Shutdown Junction Temperature	For shutdown	165		195	°C
T _{JSD_HYST}	Thermal shutdown hysteresis		9	1	18	°C

^{17.} The voltage drop in Normal mode between LIN and VBB pin is the sum of the diode drop and the drop at serial pull-up resistor. The drop at the switch is negligible. See Figure 1.

^{18.} By one of the trimming bits, following reconfiguration can be done during chip-level testing in order to fit the NCV7420-3 into different interface: pins TxD and EN will have typ. 10 kΩ pull-down resistor to ground and pin WAKE will have typ. 10 μA pull-up current source.

^{19.} Guaranteed by design. Not tested. 20. V_{BB} undervoltage threshold is always higher than V_{BB} POR low level ($V_{BB_UV_th} > PORL_V_{BB}$) 21. Measured at output voltage $V_{CC_OUT} = (V_{CC_OUT}@V_{BB} = 5 \text{ V}) - 2\%$. 22. Values based on design and characterization. Not tested in production.

Table 8. DC CHARACTERISTICS - 5 V version

 $(V_{BB} = 6 \text{ V to } 26 \text{ V}; T_{J} = -40^{\circ}\text{C} \text{ to } +150^{\circ}\text{C}; \text{ Bus Load} = 500 \ \Omega \text{ (V}_{BB} \text{ to LIN)}; \text{ unless otherwise specified.)}$

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
SUPPLY – Pin V _{BI}	в					
I _{BB_ON}	Supply current	Normal mode; LIN recessive			1.6	mA
I _{BB_STB}	Supply current	Standby mode, $V_{BB} = 6-18 \text{ V},$ $T_{J} < 105^{\circ}\text{C}$			70	μΑ
I _{BB_SLP}	Supply current	Sleep mode, $V_{BB} = 6-18 \text{ V}$, $T_{J} < 105^{\circ}\text{C}$			20	μΑ
VOLTAGE REGUL	ATOR – Pin V _{CC}					
V _{CC_OUT}	Regulator output voltage	V _{CC} load 1 mA – 30 mA	4.9	5.0	5.1	V
		V _{CC} load 0 mA – 50 mA	4.83	5.0	5.17	
I _{OUT_MAX_} ABS	Absolute maximum output current	Thermal shutdown must be taken into account			50	mA
I _{OUT_LIM}	Overcurrent limitation		50	100	170	mA
ΔV_{CC_OUT}	Line Regulation (Note 28)	V_{BB} 6–26 V, I_{OUT} = 5 mA, T_{J} = 25°C		0.9		mV
	Load Regulation (Note 28)	I_{OUT} 1–50 mA, V_{BB} = 14 V, T_{J} = 25°C		74		mV
V_{DO}	V _{DO} Dropout Voltage (V _{BB} –V _{CC_OUT}) Figure 19 (Notes 27, 28)	I _{OUT} = 1 mA, T _J = 25°C		13		mV
		I _{OUT} = 10 mA, T _J = 25°C		136		mV
		I _{OUT} = 50 mA, T _J = 25°C		794		mV
LIN TRANSMITTE	R – Pin LIN					
V _{LIN_dom_LoSup}	LIN dominant output voltage	$TxD = low; V_{BB} = 7.3 V$			1.2	V
V _{LIN_dom_HiSup}	LIN dominant output voltage	TxD = low; V _{BB} = 18 V			2.0	V
V _{LIN_rec}	LIN Recessive Output Voltage (Note 23)	TxD = high; I _{LIN} = 10 μA	V _{BB} – 1.5		V_{BB}	V
I _{LIN_lim}	Short circuit current limitation	$V_{LIN} = V_{BB_MAX}$	40		200	mA
R _{SLAVE}	Internal pull-up resistance		20	33	47	kΩ
C _{LIN}	Capacitance on pin LIN (Note 25)			15	25	pF
LIN RECEIVER – F	Pin LIN					
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{bus_dom}	Bus voltage for dominant state				0.4	V_{BB}
V _{bus_rec}	Bus voltage for recessive state		0.6			V _{BB}
V _{rec_dom}	Receiver threshold	LIN bus recessive → dominant	0.4		0.6	V _{BB}
V _{rec_rec}	Receiver threshold	LIN bus dominant → recessive	0.4		0.6	V_{BB}
V _{rec_cnt}	Receiver center voltage	(Vrec_dom + Vrec_rec) / 2	0.475		0.525	V _{BB}
V _{rec_hys}	Receiver hysteresis	(Vrec_rec - Vrec_dom)	0.05		0.175	V_{BB}
I _{LIN_off_dom}	LIN output current bus in dominant state	Driver off; V _{BB} = 12 V; V _{LIN} = 0 V	-1			mA

^{23.} The voltage drop in Normal mode between LIN and VBB pin is the sum of the diode drop and the drop at serial pull-up resistor. The drop at the switch is negligible. See Figure 1.

Driver off; V_{BB} < 18 V V_{BB} < V_{LIN} < 18 V

μΑ

I_{LIN_off_rec}

LIN output current bus in recessive state

^{24.} By one of the trimming bits, following reconfiguration can be done during chip-level testing in order to fit the NCV7420-5 into different interface: pins TxD and EN will have typ. 10 kΩ pull-down resistor to ground and pin WAKĒ will have typ. 10 μA pull-up current source.

^{25.} Guaranteed by design. Not tested.

^{26.} V_{BB} undervoltage threshold is always higher than V_{BB} POR low level (V_{BB_UV_th} > PORL_V_{BB})

^{27.} Measured at output voltage $V_{CC_OUT} = (V_{CC_OUT}@V_{BB} = 6 \text{ V}) - 2\%$. 28. Values based on design and characterization. Not tested in production.

Table 8. DC CHARACTERISTICS - 5 V version

 $(V_{BB}$ = 6 V to 26 V; T_{J} = -40°C to +150°C; Bus Load = 500 Ω (V_{BB} to LIN); unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
LIN RECEIVER -	Pin LIN			•		
I _{LIN_no_GND}	Communication not affected	V _{BB} = GND = 12 V; 0 < V _{LIN} < 18 V	-1		1	mA
I _{LIN_no_} VBB	LIN bus remains operational	V _{BB} = GND = 0 V; 0 < V _{LIN} < 18 V			5	μΑ
Pin WAKE						
V_{WAKE_th}	Threshold voltage		0.35		0.65	V_{BB}
I _{LEAK}	Input leakage current (Note 24)	V _{WAKE} = 0 V; V _{BB} = 18 V	-1	-0.5	1	μΑ
t _{WAKE_MIN}	Debounce time	Sleep mode; rising and falling edge	8		54	μS
Pins TxD and ST	В					
V _{IL}	Low level input voltage				0.8	V
V _{IH}	High level input voltage		2.0			V
R _{PU}	Pull–up resistance to V _{CC} (Note 24)		50		200	kΩ
Pin INH						
Delta_V _H	High level voltage drop	I _{INH} = 15 mA		0.35	0.75	V
I _{LEAK}	Leakage current	Sleep mode; V _{INH} = 0 V	-1		1	μΑ
Pin EN						
V _{IL}	Low level input voltage				0.8	V
V _{IH}	High level input voltage		2.0			V
R _{PD}	Pull-down resistance to ground (Note 24)		50		200	kΩ
Pin RxD						
V _{OL}	Low level output voltage	I _{SINK} = 2 mA			0.65	V
V _{OH}	High level output voltage (In Normal mode)	Normal mode, I _{SOURCE} = -2 mA	V _{CC} – 0.65 V			V
R _{PU}	Pull–up resistance to V _{CC} (In Standby and Sleep mode)	Standby mode, Sleep mode	5	10	15	kΩ
POR AND VOLTA	AGE MONITOR					
$V_{BB_UV_th}$	V _{BB} undervoltage threshold (Note 26)		3	4.2	4.75	V
PORL_V _{BB}	V _{BB} POR low level comparator	NCV7420D25	2.5		4.2	V
		NCV7420D26	1.7		3.8	V
$V_{CC_UV_th}$	V _{CC} undervoltage threshold		3		4.5	V
THERMAL SHUT	DOWN					
T _{JSD}	Thermal Shutdown Junction Temperature	For shutdown	165		195	°C
T _{JSD_HYST}	Thermal shutdown hysteresis		9		18	°C

^{23.} The voltage drop in Normal mode between LIN and V_{BB} pin is the sum of the diode drop and the drop at serial pull-up resistor. The drop at the switch is negligible. See Figure 1.

^{24.} By one of the trimming bits, following reconfiguration can be done during chip-level testing in order to fit the NCV7420-5 into different interface: pins TxD and EN will have typ. 10 kΩ pull-down resistor to ground and pin WAKE will have typ. 10 μA pull-up current source.

^{25.} Guaranteed by design. Not tested.

^{26.} V_{BB} undervoltage threshold is always higher than V_{BB} POR low level (V_{BB_UV_th} > PORL_V_{BB})

^{27.} Measured at output voltage V_{CC_OUT} = (V_{CC_OUT}@V_{BB} = 6 V) – 2%. 28. Values based on design and characterization. Not tested in production.

AC Characteristics – 3.3 V and 5 V versions – ($V_{BB} = 7 \text{ V to } 18 \text{ V}; T_J = -40 ^{\circ}\text{C} \text{ to } +150 ^{\circ}\text{C}; \text{ unless otherwise specified.}$)

Table 9. AC CHARACTERISTICS LIN TRANSMITTER - Pin LIN

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
D1	Duty Cycle 1 = t _{BUS_REC(min)} / (2 x t _{BIT}) see Figure 23	Normal slope mode $TH_{REC(max)} = 0.744 \text{ x V}_{BB}$ $TH_{DOM(max)} = 0.581 \text{ x V}_{BB}$ $t_{BIT} = 50 \mu\text{s}$ $V_{BB} = 7 \text{ V to } 18 \text{ V}$	0.396		0.5	
D2	Duty Cycle 2 = t _{BUS_REC(max)} / (2 x t _{BIT}) see Figure 23	Normal slope mode $TH_{REC(min)} = 0.422 \times V_{BB}$ $TH_{DOM(min)} = 0.284 \times V_{BB}$ $t_{BIT} = 50 \ \mu s$ $V_{BB} = 7.6 \ V \ to \ 18 \ V$	0.5		0.581	
D3	Duty Cycle 3 = t _{BUS_REC(min)} / (2 x t _{BIT}) see Figure 23	Normal slope mode $TH_{REC(max)} = 0.778 \text{ x V}_{BB}$ $TH_{DOM(max)} = 0.616 \text{ x V}_{BB}$ $t_{BIT} = 96 \mu\text{s}$ $V_{BB} = 7 \text{ V to } 18 \text{ V}$	0.417		0.5	
D4	Duty Cycle 4 = t _{BUS_REC(max)} / (2 x t _{BIT}) see Figure 23	Normal slope mode $TH_{REC(min)} = 0.389 \times V_{BB}$ $TH_{DOM(min)} = 0.251 \times V_{BB}$ $t_{BIT} = 96 \ \mu s$ $V_{BB} = 7.6 \ V \ to \ 18 \ V$	0.5		0.590	
t _{trx_prop_down}	Propagation Delay of TxD to LIN. TxD high to low	(Note 29)			6	μs
t _{trx_prop_up}	Propagation Delay of TxD to LIN. TxD low to high	(Note 29)			6	μS
t _{fall_norm}	LIN falling edge	Normal slope mode; V _{BB} = 12 V; L1, L2 (Note 30)			22.5	μs
t _{rise_norm}	LIN rising edge	Normal slope mode; V _{BB} = 12 V; L1, L2 (Note 30)			22.5	μs
t _{sym_norm}	LIN slope symmetry	Normal slope mode; V _{BB} = 12 V; L1, L2 (Note 30)	-4		4	μs
t _{fall_norm}	LIN falling edge	Normal slope mode; V _{BB} = 12 V; L3 (Note 30)			27	μS
t _{rise_norm}	LIN rising edge	Normal slope mode; V _{BB} = 12 V; L3 (Note 30)			27	μS
t _{sym_norm}	LIN slope symmetry	Normal slope mode; V _{BB} = 12 V; L3 (Note 30)	- 5		5	μS
t _{fall_low}	LIN falling edge	Low slope mode (Note 31); V _{BB} = 12 V; L3 (Note 30)			62	μs
t _{rise_low}	LIN rising edge	Low slope mode (Note 31); V _{BB} = 12 V; L3 (Note 30)			62	μs
t _{wake}	Dominant timeout for wake-up via LIN bus		30		150	μs
t _{dom}	TxD dominant timeout	TxD = low	6		20	ms

^{29.} Values based on design and characterization. Not tested in production. 30. The AC parameters are specified for following RC loads on the LIN bus: L1 = 1 k Ω / 1 nF; L2 = 660 Ω / 6.8 nF; L3 = 500 Ω / 10 nF. 31. Low slope mode is not compliant to the LIN standard.

REGULATOR TYPICAL PERFORMANCE CHARACTERISTICS – 3.3 V VERSION

Load Transient Responses

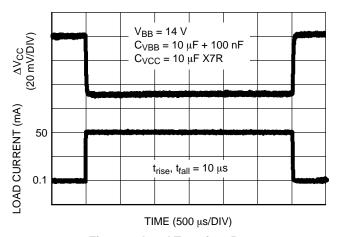


Figure 7. Load Transient Response (I_{CC} 100 μA to 50 mA)

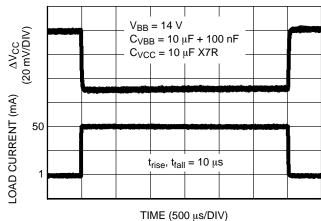


Figure 8. Load Transient Response (I_{CC} 1 mA to 50 mA)

Line Transient Responses

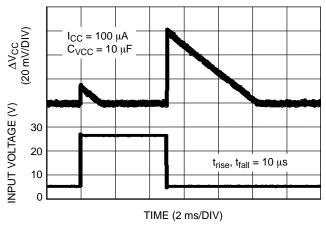


Figure 9. Line Transient Response (V_{BB} 5 V to 26 V)

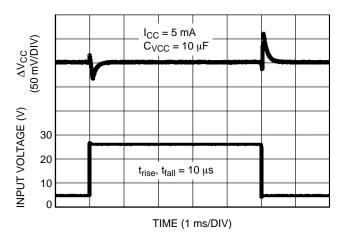
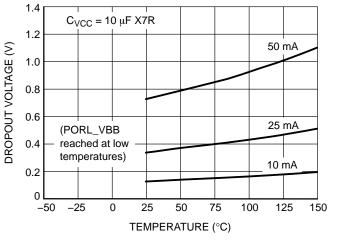


Figure 10. Line Transient Response (V_{BB} 5 V to 26 V)

REGULATOR TYPICAL PERFORMANCE CHARACTERISTICS – 3.3 V VERSION

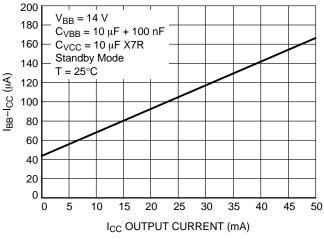
Static Characteristics

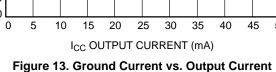


3.32 $V_{BB} = 14 \text{ V}$ 3.31 $C_{VBB} = 10 \mu F + 100 nF$ V_{CC} OUTPUT VOLTAGE (V) C_{VCC} = 10 μ F X7R 3.30 3.29 3.28 -40°C 3.27 25°C 3.26 85°C 3.25 135°C 150°C 3.24 0 5 10 15 20 25 30 35 40 45 I_{CC} OUTPUT CURRENT (mA)

Figure 11. Dropout Voltage vs. Temperature







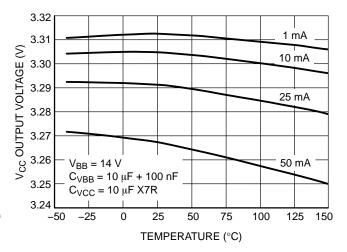


Figure 14. Output Voltage vs. Temperature

REGULATOR TYPICAL PERFORMANCE CHARACTERISTICS – 5 V VERSION

Load Transient Responses

Line Transient Responses

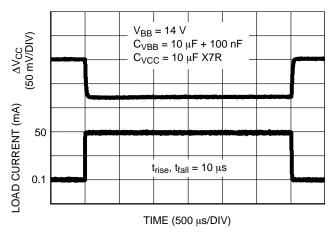


Figure 15. Load Transient Response (I_{CC} 100 μA to 50 mA)

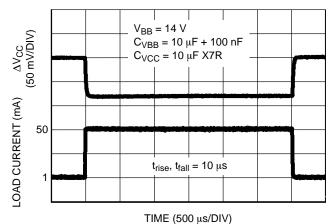


Figure 16. Load Transient Response (I_{CC} 1 mA to 50 mA)

(100 100 101 10 00 111

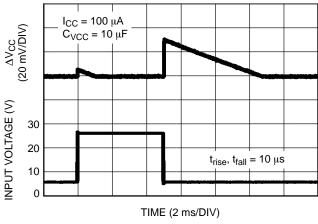


Figure 17. Line Transient Response (V_{BB} 6 V to 26 V)

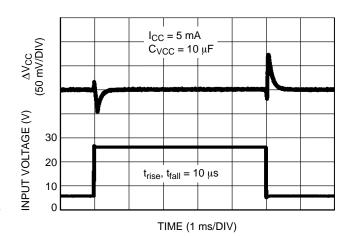
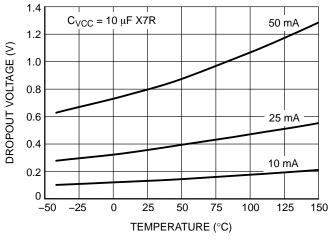


Figure 18. Line Transient Response (V_{BB} 6 V to 26 V)

REGULATOR TYPICAL PERFORMANCE CHARACTERISTICS – 5 V VERSION

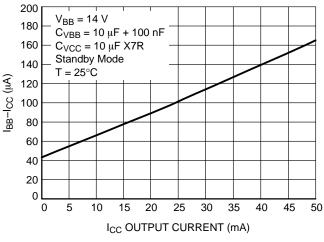
Static Characteristics

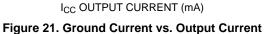


5.03 V_{BB} = 14 V 5.02 $C_{VBB} = 10 \mu F + 100 nF$ S 5.01 C_{VCC} = 10 μ F X7R VCC OUTPUT VOLTAGE 5.00 4.99 4.98 4.97 4.96 25°C 85°C 4.95 4.94 135°C 150 4.93 0 5 10 15 20 25 30 35 40 45 50 I_{CC} OUTPUT CURRENT (mA)

Figure 19. Dropout Voltage vs. Temperature







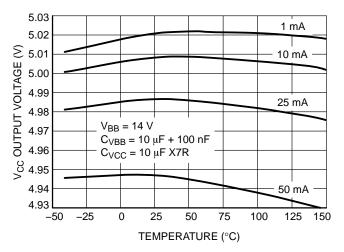


Figure 22. Output Voltage vs. Temperature

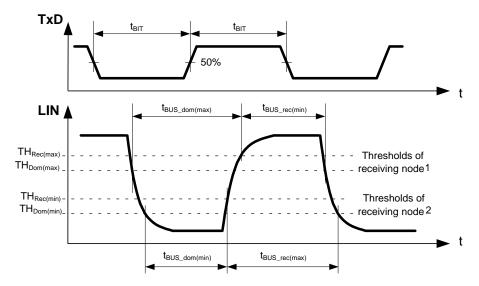


Figure 23. LIN Transmitter Duty Cycle

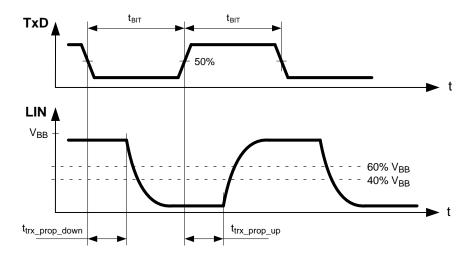


Figure 24. LIN Transmitter Timing

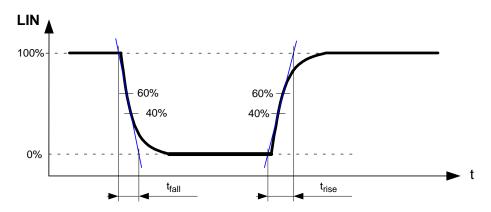


Figure 25. LIN Transmitter Rising and Falling Times

Table 10. AC CHARACTERISTICS LIN RECEIVER

Symbol Pin LIN	Parameter	Conditions	Min	Тур	Max	Unit
t _{rec_prop_down}	Propagation delay of receiver falling edge		0.1		6	μS
t _{rec_prop_up}	Propagation delay of receiver rising edge		0.1		6	μs
t _{rec_sym}	Propagation delay symmetry	t _{rec_prop_down} – t _{rec_prop_up}	-2		2	μS

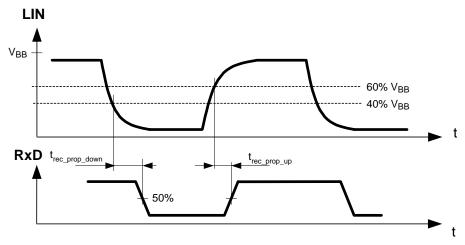


Figure 26. LIN Receiver Timing

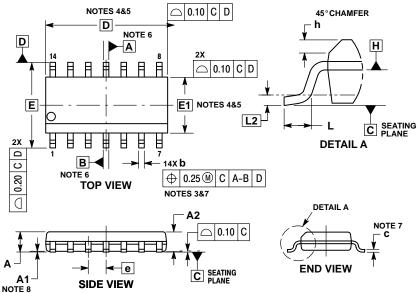
ORDERING INFORMATION

Part Number	Description	Temperature Range	Package	Shipping [†]
NCV7420D23G	LIN Transceiver + 3.3 V Vreg.	–40°C to 125°C	SOIC-14 (Pb-Free)	55 / Tube/Rail
NCV7420D23R2G	LIN Transceiver + 3.3 V Vreg.			3000 / Tape & Reel
NCV7420D24G	EMC/ESD Improved LIN Transceiver + 3.3 V Vreg.			55 / Tube/Rail
NCV7420D24R2G	EMC/ESD Improved LIN Transceiver + 3.3 V Vreg.			3000 / Tape & Reel
NCV7420D25G	LIN Transceiver + 5 V Vreg.			55 / Tube/Rail
NCV7420D25R2G	LIN Transceiver + 5 V Vreg.			3000 / Tape & Reel
NCV7420D26G	EMC/ESD Improved LIN Transceiver + 5 V Vreg.			55 / Tube/Rail
NCV7420D26R2G	EMC/ESD Improved LIN Transceiver + 5 V Vreg.			3000 / Tape & Reel

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

PACKAGE DIMENSIONS

SOIC 14 CASE 751AP **ISSUE B**

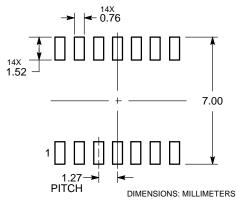


NOTES:

- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
 CONTROLLING DIMENSION: MILLIMETERS.
- DIMENSION & DOES NOT INCLUDE DAMBAR PROTRUSION.
 ALLOWABLE PROTRUSION SHALL BE 0.004 mm IN EXCESS OF
- ALLOWABLE PHOI HUSION SHALL BE 0.004 mm IN EXCESS OF MAXIMUM MATERIAL CONDITION.
 DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH, PROTRUSIONS OR GATE BURRS SHALL NOT EXCEED 0.006 mm PER SIDE. DIMENSION E1 DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION. FLASH OR PROTRUSION SHALL NOT EXCEED 0.010 mm PER SIDE. THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOT-
- TOM. DIMENSIONS D AND E1 ARE DETERMINED AT THE OUTER-MOST EXTREMES OF THE PLASTIC BODY AT DATUM H.
- DIMENSIONS A AND B ARE TO BE DETERMINED AT DATUM H. DIMENSIONS b AND c APPLY TO THE FLAT SECTION OF THE LEAD
- BETWEEN 0.10 TO 0.25 FROM THE LEAD TIP.
 A1 IS DEFINED AS THE VERTICAL DISTANCE FROM THE SEATING PLANE TO THE LOWEST POINT ON THE PACKAGE BODY.

	MILLIMETERS		
DIM	MIN	MAX	
Α		1.75	
A1	0.10	0.25	
A2	1.25		
b	0.31	0.51	
C	0.10	0.25	
D	8.65 BSC		
E	6.00 BSC		
E1	3.90 BSC		
е	1.27 BSC		
h	0.25	0.41	
L	0.40	1.27	
L2	0.25 BSC		

RECOMMENDED SOLDERING FOOTPRINT*



*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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