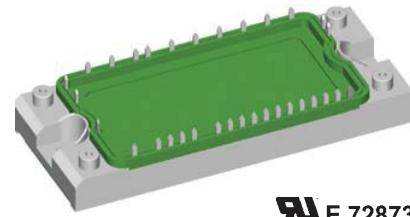
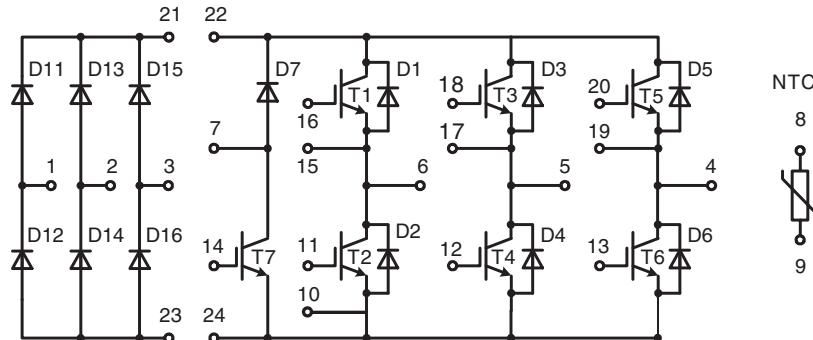


## Converter - Brake - Inverter Module (CBI2) with Trench IGBT technology

### Preliminary data



**E 72873**

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$ $I_{FAVM} = 38 \text{ A}$ $I_{FSM} = 300 \text{ A}$	$V_{CES} = 1200 \text{ V}$ $I_{C25} = 30 \text{ A}$ $V_{CE(sat)} = 1.7 \text{ V}$	$V_{CES} = 1200 \text{ V}$ $I_{C25} = 45 \text{ A}$ $V_{CE(sat)} = 1.7 \text{ V}$

#### Input Rectifier Bridge D11 - D16

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$		1600	V	
$I_{FAV}$	$T_c = 80^\circ\text{C}; \sin 180^\circ$	25	A	
$I_{DAVM}$	$T_c = 80^\circ\text{C}; \text{rectangular; } d = 1/3; \text{bridge}$	72	A	
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}; t = 10 \text{ ms; sine } 50 \text{ Hz}$	300	A	
$P_{tot}$	$T_c = 25^\circ\text{C}$	100	W	

Symbol	Conditions	Characteristic Values			
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.	max.
$V_F$	$I_F = 25 \text{ A}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.1	1.3	V
			1.1		V
$I_R$	$V_R = V_{RRM}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.02	mA	
			0.4		mA
$R_{thJC}$	(per diode)			1.3	K/W

#### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

#### Features

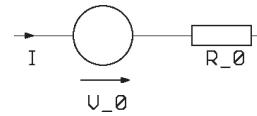
- High level of integration - only one power semiconductor module required for the whole drive
- Inverter with Trench IGBTs
  - low saturation voltage
  - positive temperature coefficient
  - fast switching
  - short tail current
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

**Output Inverter T1 - T6**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	45		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	25		A
$I_{CM}$	$T_C = 80^\circ\text{C}; t_p = 1 \text{ ms}$	50		A
$P_{tot}$	$T_C = 25^\circ\text{C}$	170		W
Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 25 \text{ A}; V_{GE} = 15 \text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.7 2.0	2.15 V	V
$V_{GE(th)}$	$I_C = 1 \text{ mA}; V_{GE} = V_{CE}$	5	5.8	6.5 V
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.7	2.7 mA	mA
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$		400	nA
$C_{ies}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$	1.8		nF
$Q_{Gon}$	$V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 25 \text{ A}$	240		nC
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 25 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 36 \Omega$	90 50 520 90 2.5 3.4		ns ns ns ns mJ mJ
<b>RBSOA</b>	$I_C = I_{CM}; V_{GE} = \pm 15 \text{ V}$ $R_G = 36 \Omega; T_{VJ} = 125^\circ\text{C}$			$V_{CEK} \leq V_{CES} - L_S \frac{di}{dt}$ V
$I_{sc}$ <b>(SCSOA)</b>	$V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 36 \Omega;$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^\circ\text{C}$	100		A
$R_{thJC}$	(per IGBT)		0.73	K/W

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings		
$I_{F25}$	$T_C = 25^\circ\text{C}$	25		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	17		A
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 25 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.1 1.6	2.6 V	V
$I_{RM}$ $Q_{rr}$ $t_{rr}$ $E_{rec}$	$I_F = tbd \text{ A}; di_F/dt = -tbd \text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}$ $V_R = 600 \text{ V}; V_{GE} = 0 \text{ V}$	tbd tbd tbd tbd		A $\mu\text{C}$ ns mJ
$R_{thJC}$	(per diode)		2.1	K/W

**Equivalent Circuits for Simulation****Conduction**

IGBT (typ. at  $V_{GE} = 15 \text{ V}; T_J = 125^\circ\text{C}$ )  
T1-T6

$$V_o = 0.92 \text{ V}; R_o = 42.8 \text{ m}\Omega$$

T7

$$V_o = 0.92 \text{ V}; R_o = 72 \text{ m}\Omega$$

Diode (typ. at  $T_J = 125^\circ\text{C}$ )

D1-D6

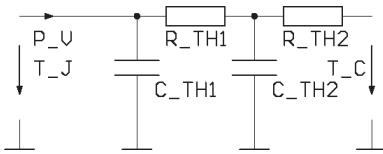
$$V_o = tbd \text{ V}; R_o = tbd \text{ m}\Omega$$

D7

$$V_o = tbd \text{ V}; R_o = tbd \text{ m}\Omega$$

D11-D16

$$V_o = tbd \text{ V}; R_o = tbd \text{ m}\Omega$$

**Thermal Response**

IGBT (typ.)

T1-T6

$$C_{th1} = tbd \text{ J/K}; R_{th1} = tbd \text{ K/W}$$

$$C_{th2} = tbd \text{ J/K}; R_{th2} = tbd \text{ K/W}$$

T7

$$C_{th1} = tbd \text{ J/K}; R_{th1} = tbd \text{ K/W}$$

$$C_{th2} = tbd \text{ J/K}; R_{th2} = tbd \text{ K/W}$$

Diode (typ.)

D1-D6

$$C_{th1} = tbd \text{ J/K}; R_{th1} = tbd \text{ K/W}$$

$$C_{th2} = tbd \text{ J/K}; R_{th2} = tbd \text{ K/W}$$

D7

$$C_{th1} = tbd \text{ J/K}; R_{th1} = tbd \text{ K/W}$$

$$C_{th2} = tbd \text{ J/K}; R_{th2} = tbd \text{ K/W}$$

D11-D16

$$C_{th1} = tbd \text{ J/K}; R_{th1} = tbd \text{ K/W}$$

$$C_{th2} = tbd \text{ J/K}; R_{th2} = tbd \text{ K/W}$$

## Brake Chopper T7

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200	V	
$V_{GES}$	Continuous	$\pm 20$	V	
$I_{C25}$	$T_C = 25^\circ\text{C}$	30	A	
$I_{C80}$	$T_C = 80^\circ\text{C}$	15	A	
$I_{CM}$	$T_C = 80^\circ\text{C}; t_p = 1 \text{ ms}$	30	A	
$P_{tot}$	$T_C = 25^\circ\text{C}$	120	W	
Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 15 \text{ A}; V_{GE} = 15 \text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.7 2.0	2.1 V	V
$V_{GE(th)}$	$I_C = 0.5 \text{ mA}; V_{GE} = V_{CE}$	5	5.8	6.5 V
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.25	0.1 mA	mA
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$		400	nA
$C_{ies}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$	1.1		nF
$Q_{Gon}$	$V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 15 \text{ A}$	150		nC
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 15 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 75 \Omega$	90 50 520 90 1.5		ns ns ns ns mJ
RBSOA	$I_C = I_{CM}; V_{GE} = \pm 15 \text{ V}$ $R_G = 75 \Omega; T_{VJ} = 125^\circ\text{C}$	$V_{CEK} \leq V_{CES} - L_S \frac{di}{dt}$		V
$I_{sc}$ (SCSOA)	$V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 75 \Omega$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^\circ\text{C}$	60		A
$R_{thJC}$			1.05	K/W

## Brake Chopper D7

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200	V	
$I_{F25}$	$T_C = 25^\circ\text{C}$	16	A	
$I_{F80}$	$T_C = 80^\circ\text{C}$	11	A	
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 65 \text{ A}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	3.0 2.6	3.3 V	V
$I_R$	$V_R = V_{RRM}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.07	0.06 mA	mA
$R_{thJC}$			3.2	K/W

## Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^\circ\text{C}$	4.75	5.0	5.25 k $\Omega$
$B_{25/50}$			3375	K

## Module

Symbol	Conditions	Maximum Ratings		
$T_{VJ}$	operating	-40...+125	$^\circ\text{C}$	
$T_{JM}$		150	$^\circ\text{C}$	
$T_{stg}$		-40...+125	$^\circ\text{C}$	
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
$M_d$	Mounting torque (M5)	2.7 - 3.3	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m $\Omega$
$d_s$	Creepage distance on surface	6		mm
$d_A$	Strike distance in air	6		mm
$R_{thCH}$	with heatsink compound	0.02		K/W
Weight		180		g

Dimensions in mm (1 mm = 0.0394")

