Constant Current LED Driver with PWM Dimming Control

■ GENERAL DESCRIPTION

The NJW4616 is a constant current LED driver with PWM dimming control. The output current can be set by external sensing resister, and the NJW4616 can set up to 300mA. Because the withstand voltage of the output (LED) pin is 40V, it can series-connect the LED depending on forward voltage of the LED.

The LED dimming control can be regulated via PWM duty cycle. It is suitable for back light, light source and so on.

■ FEATURES

- Supply Voltage Range 2.5V to 40V
- Output Voltage
 Output Current

V_{LED}=40V max. I_{I FD}=20mA to 300mA

- Output Current Accuracy ±1.5%
- To 11 of White LED can be operated. (at LED Vf=3.4V)
- Quiescent Current
 450µA max.
- PWM Dimming Control and Enable Control (Common Pin)
- Over Current Protection
- Thermal Shutdown Protection
- LED Short Protection
- Package SOT-89-5
- BLOCK DIAGRAM



■ PACKAGE OUTLINE



NJW4616U2 (SOT-89-5)

■ PIN CONFIGURATION



■ PIN DESCRIPTIONS

Pin No.	Pin Name	I/O	Function
1	EN/PWM	I	Standby control pin and PWM signal input pin for dimming control. [At Standby control] Normal operation: High Level. Standby mode: Low Level. [At PWM signal input] The LED dimming control can be regulated by PWM duty cycle. In the case without dimming, I _{LED} becomes the current set by the external resistor (Rs) when High level is input to this pin. Note that this pin should not be open.
2	GND	-	Ground pin
3	R _s	0	Resistor connect pin of I_{LED} setting. The LED current can be set with connected resistor (R _S) between R _S pin and GND pin. R _S [Ω] = 0.2 [V] / I_{LED} [A]
4	LED	0	Constant current circuit output pin Connect cathode pin of LED.
5	V _{DD}	-	Power Supply pin

■ ABSOLUTE MAXIMUM RATINGS	(Ta = 25°C)		
PARAMETER	SYMBOL RATINGS		UNIT
Supply Voltage	V _{DD}	-0.3 to +45	V
Output Voltage	V _{LED}	-0.3 to +45	V
EN/PWM Pin Voltage	V _{ENPWM}	-0.3 to +45	V
Power Dissipation	P _D	625 (*1) 2400 (*2)	mW
Junction Temperature Range	Tj	-40 to +150	°C
Operating Temperature Range	T _{opr}	-40 to +125	°C
Storage Temperature Range	T _{stg}	-50 to +150	°C

(*1) Mounted on glass epoxy board. (76.2 × 114.3 × 1.6mm: based on EIA/JEDEC standard size, 2Layers, Cu area 100mm²)

(*2) Mounted on glass epoxy board. (76.2 × 114.3 × 1.6mm: based on EIA/JEDEC standard, 4Layers),

(For 4Layers: Applying 74.2 × 74.2mm inner Cu area and a thermal via hole to a board based on JEDEC standard JESD51-5)

■ RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply Voltage	V _{DD}		2.5	-	40	V
Output Current	I _{LED}		20	-	300	mA
Output Voltage	V _{LED}		-	-	40	V

■ ELECTRICAL CHARACTERISTICS

(Unless otherwise noted, $V_{DD} = 12V$, $V_{LED} = 1V$, $R_S = 2\Omega$, $V_{ENPWM} = V_{DD}$, $Ta = 25^{\circ}C$)						
PARAMETER	SYMBOL	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Quiescent Current	I _{DD}		-	330	450	μA
Quiescent Current at OFF State	I _{DD_OFF}	V _{ENPWM} =GND	-	-	0.1	μA
Output Current Accuracy	ΔI_{LED}		-1.5	-	+1.5	%
Output (LED) Pin Leak Current	I _{LEAK}	$V_{ENPWM} = GND,$ $V_{DD} = V_{LED} = 40V$	-	-	0.1	μA
OFF Delay Time	t _{D_OFF}		10	25	45	ms
EN/PWM Pin ON Voltage1	$V_{\text{ENPWM}_{ON}}$ 1	$V_{DD} < 5V, I_{LED} = OFF \rightarrow ON$	$0.7V_{DD}$	-	V_{DD}	V
EN/PWM Pin ON Voltage2	$V_{ENPWM_ON}2$	$V_{DD} \ge 5V, I_{LED} = OFF \rightarrow ON$	3.5	-	V_{DD}	V
EN/PWM Pin OFF Voltage	V_{ENPWM_OFF}	$I_{LED} = ON \rightarrow OFF$	0	-	0.5	V
EN/PWM Pin Input Current	ENPWM		-	7	-	μA
R _S Pin Output Current	I _{OUT_RS}	LED = OPEN	-	4	-	μA
PWM Dimming ON Delay Time	t _{PWM_ON}	$R_{S} = 0.62\Omega, V_{ENPWM} = L \rightarrow H$	-	10	-	μs
PWM Dimming OFF Delay Time	t _{PWM_OFF}	$R_{S} = 0.62\Omega, V_{ENPWM} = H \rightarrow L$	-	1	-	μs
LED Short Protection Detect Voltage	V_{LED_SHORT}		18	21	24	V
Maximum Output Current	I _{LED_MAX}	$R_{\rm S} = 0\Omega$	300	550	-	mA

■ TYPICAL APPLICATION



The R_s Resistance Setting formula:
$$R_{S}(\Omega) = \frac{0.2(V)}{I_{LED}(A)}$$

(*3) If the wiring from the power supply to the LED anode pin is long, the voltage may change due to the influence of the parasitic elements.

As the countermeasure, it should connect a decoupling capacitor as close to the LED as possible.

■ TYPICAL CHARACTERISTICS











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■ TYPICAL CHARACTERISTICS





TYPICAL CHARACTERISTICS



■ TYPICAL CHARACTERISTICS



The number of LED series connection

It is necessary to drive LED that is the LED forward voltage (Vf) or more. When the LED was series connected, the supply voltage should be input sum of LED Vf (Σ LED Vf) the series connected or more. In NJW4616, it is necessary as minimum V⁺ that is Σ LED Vf + NJW4616 output voltage (V_{LED} = 1V). The maximum LED connected number that NJW4616 can drive is limited by the recommended output voltage

maximum value (40V). Moreover, it should be used with Σ LED Vf within 39V that is subtracted the V_{LED} = 1V.

The table below shows maximum LED number at each Vf. (All LED Vf assumes ideally same)



(*4) If the wiring from the power supply to the V_{DD} pin is long, the voltage may change due to the influence of the parasitic elements.

As the countermeasure, it should connect a decoupling capacitor as close to the V_{DD} pin as possible.

■ PWM input pulse and PWM dimming accuracy

The ILED transient behavior corresponding to PWM input pulse has some delay at rise/fall time.



If enter a PWM signal with short pulse width, for the output current pulse width error becomes larger against the PWM input pulse width, it is incapable of accurate PWM dimming. The Output current pulse width error rate (ϵ_t) becomes the following value. ($\epsilon_t = t_{PWM_ON} - t_{PWM_OFF}$)

 $\epsilon_t = approx. 9\mu s$ (Output Current: I_{LED}=300mA,Ta=25°C typ. <Reference Value>)

The actual value of the output current pulse width error rate can calculate by above error rate (ϵ_t) and the frequency and Duty of the PWM input pulse. (f_{PWM}: PWM input pulse frequency, D: PWM input pulse Duty) Based on the allowable value of the output current pulse width error rate, you should determine the frequency and Duty of the PWM input pulse.

PWM Input pulse width	$= D / 100 \times (1 / f_{PWM})$
Output Current pulse width	= PWM Input pulse width - ε_t
Output Current pulse width error rate	9
= (Output Current	pulse width - PWM Input pulse width) / PWM Input pulse width × 100
	= $-\varepsilon_t$ / PWM Input pulse width × 100 [%]
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Output current pulse width error rate calculation example:

operation with PWM input pulse frequency 200Hz and Duty1%]



Protection Circuit

Over Current Protection (Refer to Maximum Output Current vs. Output Pin Voltage)

This protection function limits the output current, when the R_S pin and GND pin was shorted. The limited current is dependence on output (LED) pin voltage.

When the output (LED) pin voltage is less than "LED Short Protection Detect Voltage", maximum output current is limited to approx. 550mA (output (LED) pin voltage=1V, Ta=25°C).

The output current returns to set current, when the short status is release.

• LED Short Protection (Refer to Maximum Output Current vs. Output Pin Voltage)

This protection function limits the output current, when the output (LED) pin rises as in LED shorten at output FET ON. The output current is limited to approx. 300mA when the output (LED) pin voltage rose to approx. 21V.

• Thermal Shutdown Function (Refer to Output Current vs. Temperature)

When junction temperature of the NJW4616 exceeds the 160° C*, internal thermal shutdown circuit function stops the device function. When junction temperature decreases to 140° C* or less, the device operation returns to normal operation.

The purpose of this function is to prevent malfunctioning of IC at the high junction temperature. Therefore it is not something that urges positive use. It should make sure to operate within the junction temperature range rated (\leq +150°C).

*) Design value

The Loss of Constant Current Driver

The power consumption of the LED lighting circuit is classified as "the power consumption of the constant current driver" "the power consumption of the LED" and "the power consumption of the current sense resistor (R_s)". The loss of constant current driver is caused mainly by quiescent current (I_{DD}) and output current (I_{LED}). The power dissipation of the device can calculate by follow equation.



As shown in the above equation, the loss of constant current driver will increase in proportion to the voltage difference between the LED driving voltage V⁺ and Σ LED Vf.

It should set the LED operating Voltage (V⁺) and output current (I_{LED}) with consideration of P_D.



The device power dissipation must be below the power dissipation rate of the device package including thermal derating to ensure correct operation.

- (*1): Mounted on glass epoxy board. (76.2 × 114.3 × 1.6mm: based on EIA/JEDEC standard size, 2Layers, Cu area 100mm2)
- (*2): Mounted on glass epoxy board. (76.2 \times 114.3 \times 1.6mm: based on EIA/JEDEC standard, 4Layers),

(For 4Layers: Applying 74.2×74.2 mm inner Cu area and a thermal via hole to a board based on JEDEC standard JESD51-5)

■ Parallel Drive of NJW4616

For applications that require more than 300mA, it can correspond by parallel connecting two or more NJW4616. The LED current becomes sum of LED current of each NJW4616. Each device accepts different set current.

 $I_{LED}[A] = I_{LED}1 + I_{LED}2 = 0.2 / R_S1 [\Omega] + 0.2 / R_S2 [\Omega]$

(e.g. I_{LED} = 450 [mA] setting: $R_{S}1$ = 0.667 [Ω], $R_{S}2$ = 1.33 [Ω] ~)



MEMO

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