

DATA SHEET

TEA1654 **GreenChip™II SMPS control IC**

Product specification

2003 May 12

GreenChip™II SMPS control IC

TEA1654

FEATURES

Distinctive features

- Universal mains supply operation (70 to 276 V AC)
- High level of integration, giving a very low external component count.

Green features

- Valley or zero voltage switching for minimum switching losses
- Efficient quasi-resonant operation at high power levels
- Frequency reduction at low power standby for improved system efficiency (<3 W)
- Cycle skipping mode at very low loads; $P_i < 300$ mW at no-load operation for a typical adapter application
- On-chip start-up current source
- Standby indication pin to indicate low output power consumption.

Protection features

- Safe restart mode for system fault conditions
- Continuous mode protection by means of demagnetization detection (zero switch-on current)
- Accurate and adjustable overvoltage protection (latched)
- Short winding protection
- Undervoltage protection (foldback during overload)
- Overtemperature protection (latched)
- Low and adjustable overcurrent protection trip level
- Soft (re)start
- Mains voltage-dependent operation-enabling level
- General purpose input for lock protection.

APPLICATIONS

Typical application areas are adapters and chargers (e.g. for laptops, camcorders and printers) and all applications that demand an efficient and cost-effective solution up to 250 W.

GENERAL DESCRIPTION

The GreenChip™(1)II is the second generation of green Switched Mode Power Supply (SMPS) control ICs operating directly from the rectified universal mains. A high level of integration leads to a cost effective power supply with a very low number of external components.

The special built-in green functions allow the efficiency to be optimum at all power levels. This holds for quasi-resonant operation at high power levels, as well as fixed frequency operation with valley switching at medium power levels. At low power (standby) levels, the system operates at reduced frequency and with valley detection.

The proprietary high voltage BCD800 process makes direct start-up possible from the rectified mains voltage in an effective and green way. A second low voltage BICMOS IC is used for accurate, high speed protection functions and control.

Highly efficient, reliable supplies can easily be designed using the GreenChipII control IC.

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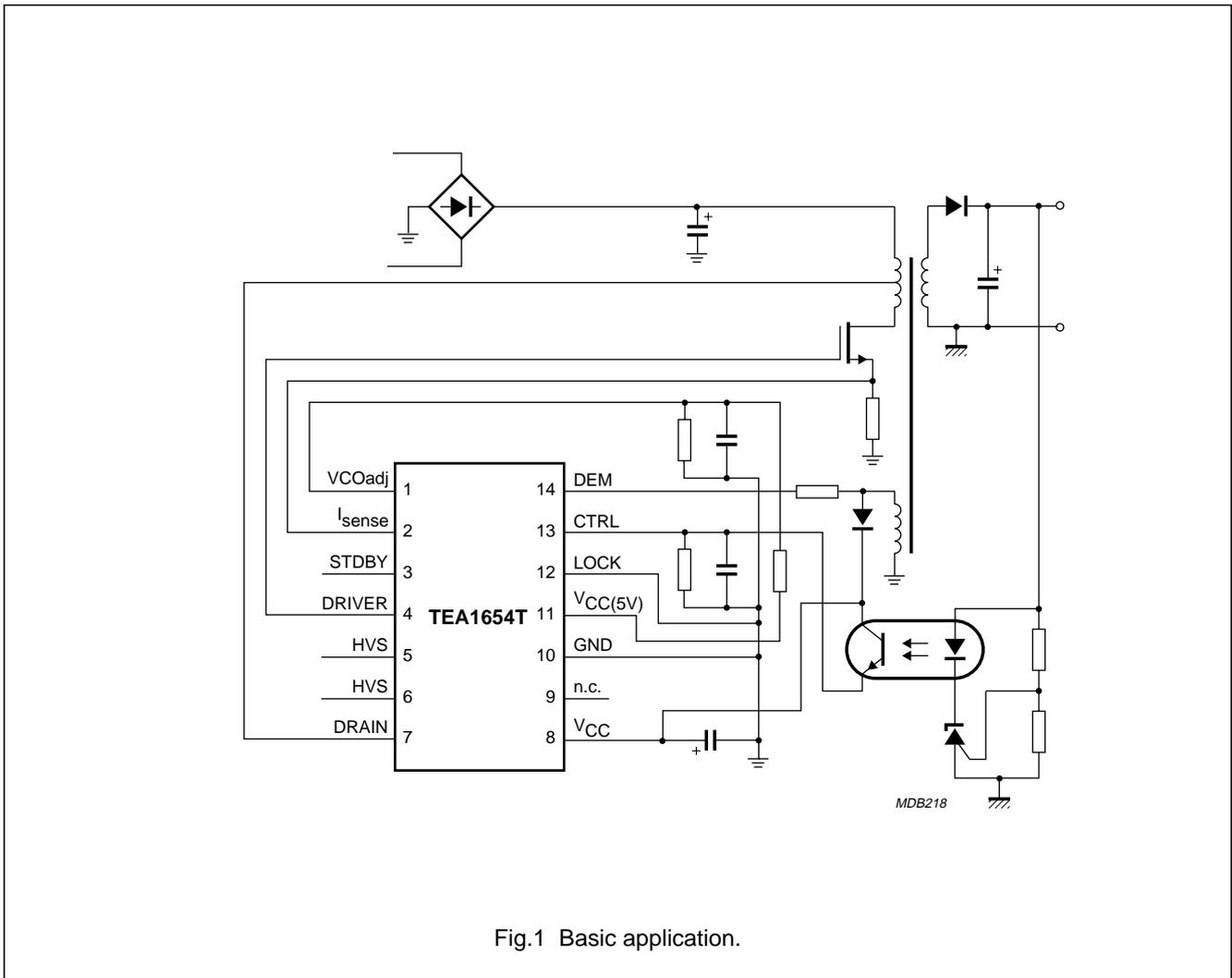


Fig.1 Basic application.

ORDERING INFORMATION

| TYPE NUMBER | PACKAGE | | |
|-------------|---------|--|----------|
| | NAME | DESCRIPTION | VERSION |
| TEA1654T | SO14 | plastic small outline package; 14 leads; body width 3.9 mm | SOT108-1 |

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BLOCK DIAGRAM

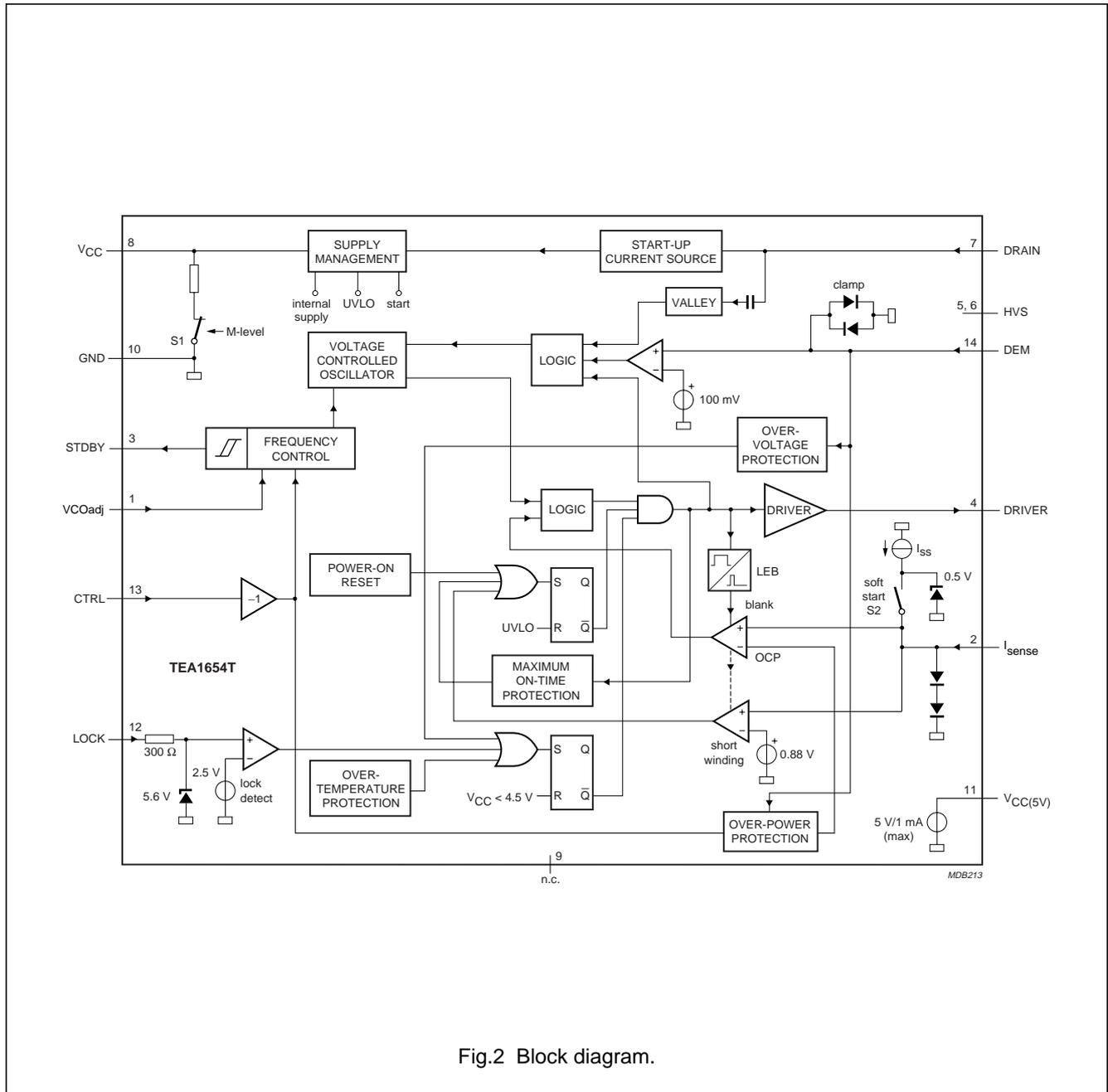


Fig.2 Block diagram.

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PINNING

| SYMBOL | PIN | DESCRIPTION |
|---------------------|-----|---|
| VCOadj | 1 | VCO adjustment input |
| I _{sense} | 2 | programmable current sense input |
| STDBY | 3 | standby indication or control output |
| DRIVER | 4 | gate driver output |
| HVS | 5 | high voltage safety spacer, not connected |
| HVS | 6 | high voltage safety spacer, not connected |
| DRAIN | 7 | drain of external MOS switch, input for start-up current and valley sensing |
| V _{CC} | 8 | supply voltage |
| n.c. | 9 | not connected |
| GND | 10 | ground |
| V _{CC(5V)} | 11 | 5 V output |
| LOCK | 12 | lock input |
| CTRL | 13 | control input |
| DEM | 14 | input from auxiliary winding for demagnetization timing, OVP and OPP |

FUNCTIONAL DESCRIPTION

The TEA1654 is the controller of a compact flyback converter, with the IC situated at the primary side. An auxiliary winding of the transformer provides demagnetization detection and powers the IC after start-up.

The TEA1654 operates in multi modes (see Fig.4).

The next converter stroke is started only after demagnetization of the transformer current (zero current switching), while the drain voltage has reached the lowest voltage to prevent switching losses (green function). The primary resonant circuit of primary inductance and drain capacitor ensures this quasi-resonant operation. The design can be optimized in such a way that zero voltage switching can be reached over almost the complete universal mains range.

To prevent very high frequency operation at lower loads, the quasi-resonant operation changes smoothly in fixed frequency PWM control.

At very low power (standby) levels, the frequency is controlled down, via the VCO, to a minimum frequency of approximately 24 kHz.

Start-up, mains enabling operation level and undervoltage lock-out (see Figs 11 and 12)

Initially, the IC is self supplying from the rectified mains voltage via pin DRAIN. Supply capacitor C_{VCC} is charged by the internal start-up current source to a level of approximately 4 V (or higher, this is dependent on the drain voltage/M-level). Once the drain voltage exceeds the M-level (mains-dependent operation-enabling level), the start-up current source will continue charging capacitor C_{VCC} (switch S1 will be opened); see Fig.2. The IC will activate the power converter as soon as the voltage on pin V_{CC} passes the level V_{CC(start)}. The IC supply is taken over by the auxiliary winding as soon as the output voltage reaches its intended level and the IC supply from the mains voltage is subsequently stopped for high efficiency operation (green function).

The moment the voltage on pin V_{CC} drops below the undervoltage lock-out level V_{UVLO}, the IC stops switching and enters a safe restart from the rectified mains voltage. Inhibiting the auxiliary supply by external means causes the converter to operate in a stable safe restart mode.

Supply management

All (internal) reference voltages are derived from a temperature compensated, on-chip band gap circuit.

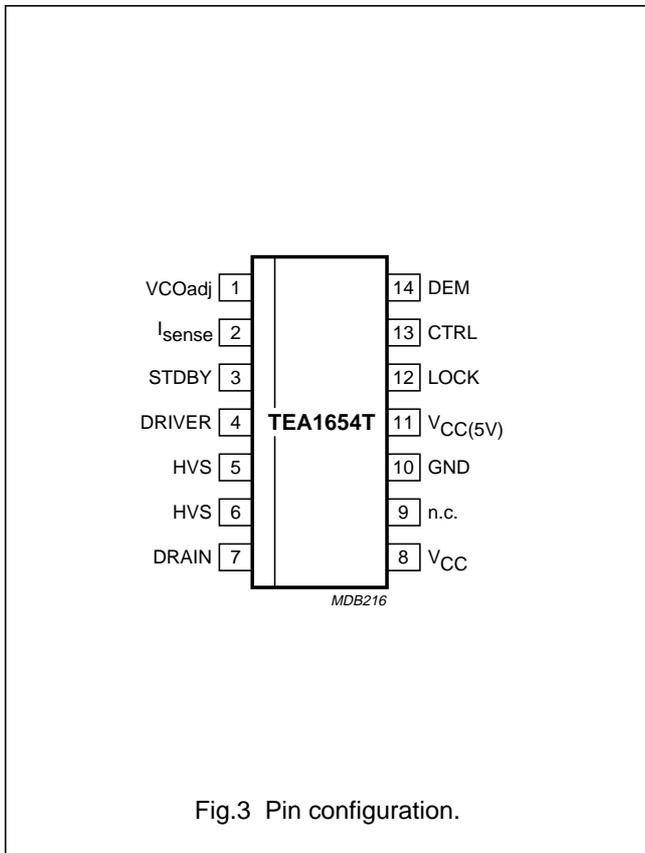


Fig.3 Pin configuration.

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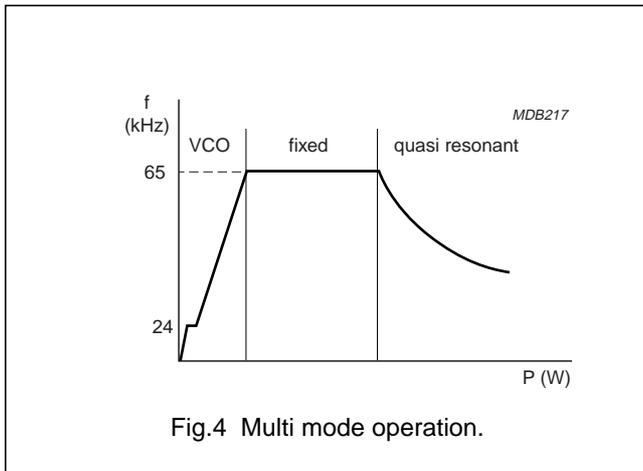


Fig.4 Multi mode operation.

Current mode control

Current mode control is used for its good line regulation behaviour.

The 'on-time' is controlled by the internally inverted control pin voltage, which is compared with the primary current information. The primary current is sensed across an external resistor. The driver output is latched in the logic, preventing multiple switch-on.

The internal control voltage is inversely proportional to the external control pin voltage, with an offset of 1.5 V. This means that a voltage range from 1 to 1.5 V on pin CTRL will result in an internal control voltage range from 0.5 to 0 V (a high external control voltage results in a low duty cycle).

Oscillator

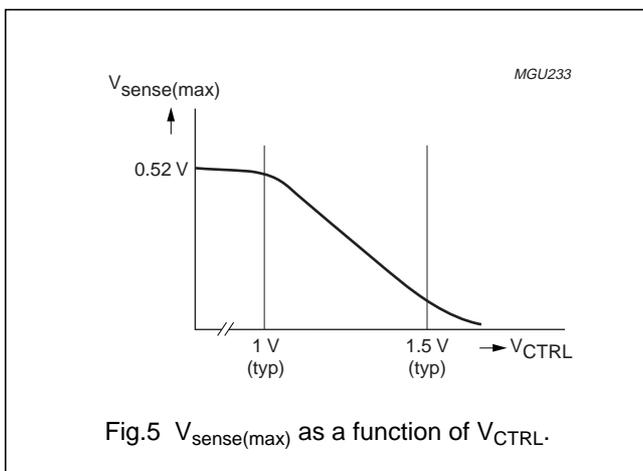


Fig.5 $V_{sense(max)}$ as a function of V_{CTRL} .

The maximum fixed frequency of the oscillator is set by an internal current source and capacitor. The maximum frequency is reduced once the control voltage enters the VCO control window. Then, the maximum frequency changes linearly with the control voltage until the minimum frequency is reached (see Figs 5 and 6).

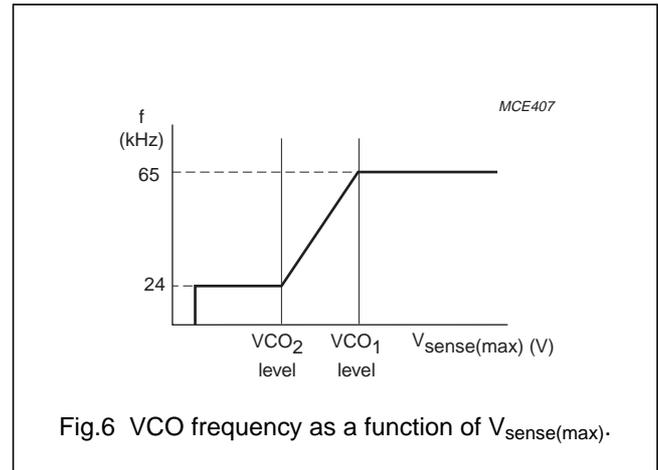


Fig.6 VCO frequency as a function of $V_{sense(max)}$.

VCO adjustment

The VCOadj pin can be used to set the VCO operation point. As soon as the peak voltage on the sense resistor is controlled below half the voltage on the VCOadj pin (VCO₁ level), frequency reduction will start. The actual peak voltage on sense will be somewhat higher due to switch-off delay (see Fig.7). The frequency reduction will stop approximately 25 mV lower (VCO₂ level), when the minimum frequency is reached.

Cycle skipping

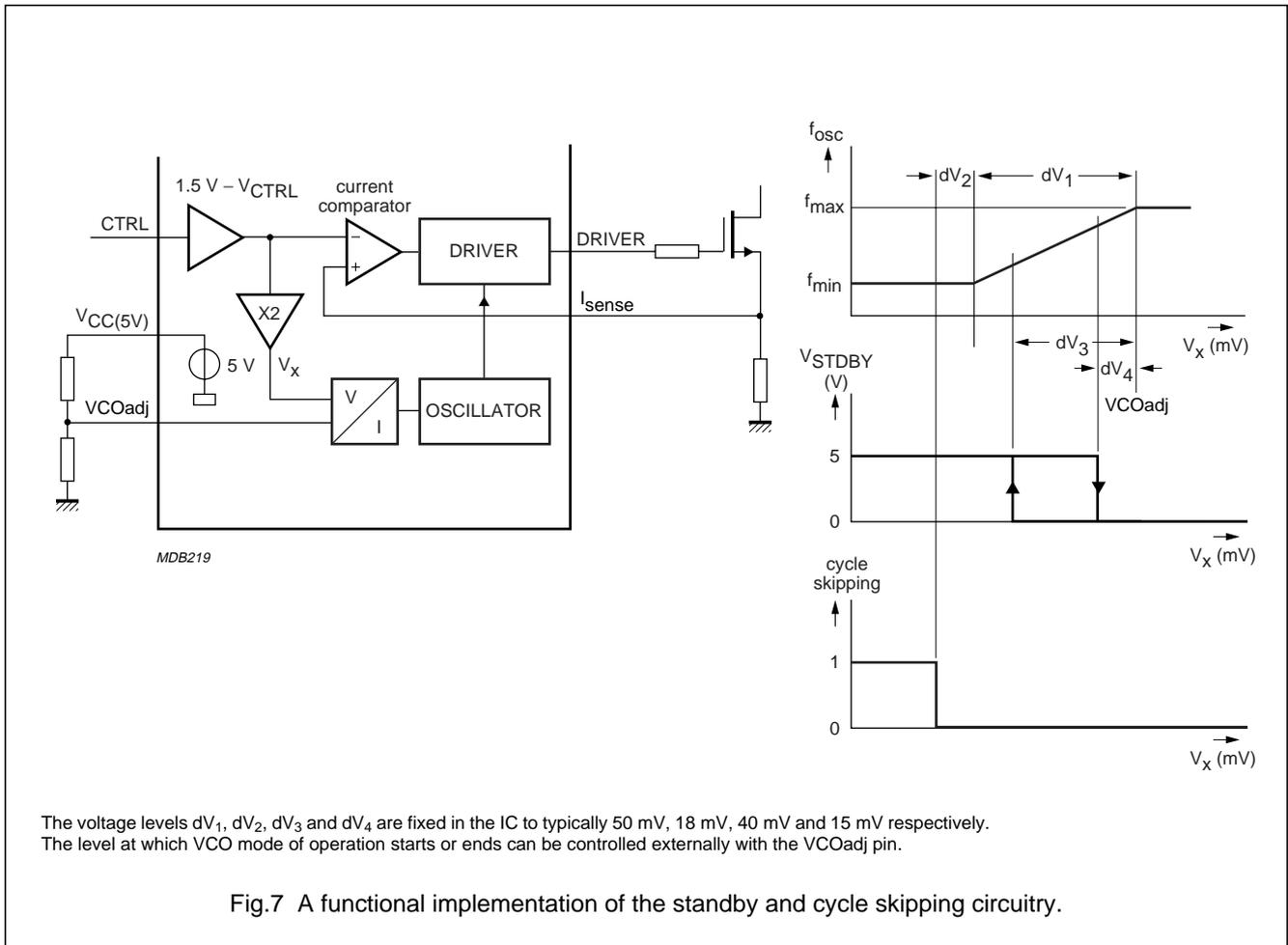
At very low power levels, a cycle skipping mode will be activated. A high control voltage will reduce the switching frequency to a minimum of 24 kHz. If the voltage on the control pin has raised even more, switch-on of the external power MOSFET will be inhibited until the voltage on the control pin has dropped to a lower value again (see Fig.7).

For system accuracy, it is not the absolute voltage on the control pin that will trigger the cycle skipping mode, but a signal derived from the internal VCO will be used.

Remark: If the no-load requirement of the system is such that the output voltage can be regulated to its intended level at a switching frequency of 24 kHz or above, the cycle skipping mode will not be activated.

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Standby output

The STDBY output pin ($V_{STDBY} = 5\text{ V}$) can be used to drive an external NPN transistor or FET in order to e.g. switch-off a PFC circuit. The STDBY output is activated by the internal VCO: as soon as the VCO has reduced the switching frequency to (almost) the minimum frequency of 24 kHz, the STDBY output will be activated (see Fig.7). The STDBY output will go low again as soon as the VCO allows a switching frequency close to the maximum frequency of 65 kHz.

Demagnetization

The system will be in discontinuous conduction mode all the time. The oscillator will not start a new primary stroke until the secondary stroke has ended.

Demagnetization features a cycle-by-cycle output short-circuit protection by immediately lowering the frequency (longer off-time), thereby reducing the power level.

Demagnetization recognition is suppressed during the first time (t_{suppr}). This suppression may be necessary in applications where the transformer has a large leakage inductance and at low output voltages/start-up.

OverVoltage Protection (OVP)

An OVP mode is implemented in the GreenChip series. For the TEA1654, this works by sensing the auxiliary voltage via the current flowing into pin DEM during the secondary stroke. The auxiliary winding voltage is a well-defined replica of the output voltage. Any voltage spikes are averaged by an internal filter.

If the output voltage exceeds the OVP trip level, the OVP circuit switches off the power MOSFET. The controller then waits until the UVLO level is reached on pin V_{CC} . When V_{CC} drops to UVLO, capacitor C_{VCC} will be recharged to the V_{start} level, however the IC will not start switching again. Subsequently, V_{CC} will drop again to the UVLO level, etc.

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Operation only recommences when the V_{CC} voltage drops below a level of approximately 4.5 V (practically when the V_{mains} has been disconnected for a short period).

The output voltage (V_{OVP}) at which the OVP function trips, can be set by the demagnetization resistor R_{DEM} :

$$V_{OVP} = \frac{N_s}{N_{aux}} \times [I_{OVP(DEM)} \times R_{DEM} + V_{clamp(DEM)(pos)}]$$

where N_s is the number of secondary turns and N_{aux} is the number of auxiliary turns of the transformer.

Current $I_{OVP(DEM)}$ is internally trimmed.

The value of the demagnetization resistor (R_{DEM}) can be adjusted to the turns ratio of the transformer, thus making an accurate OVP possible.

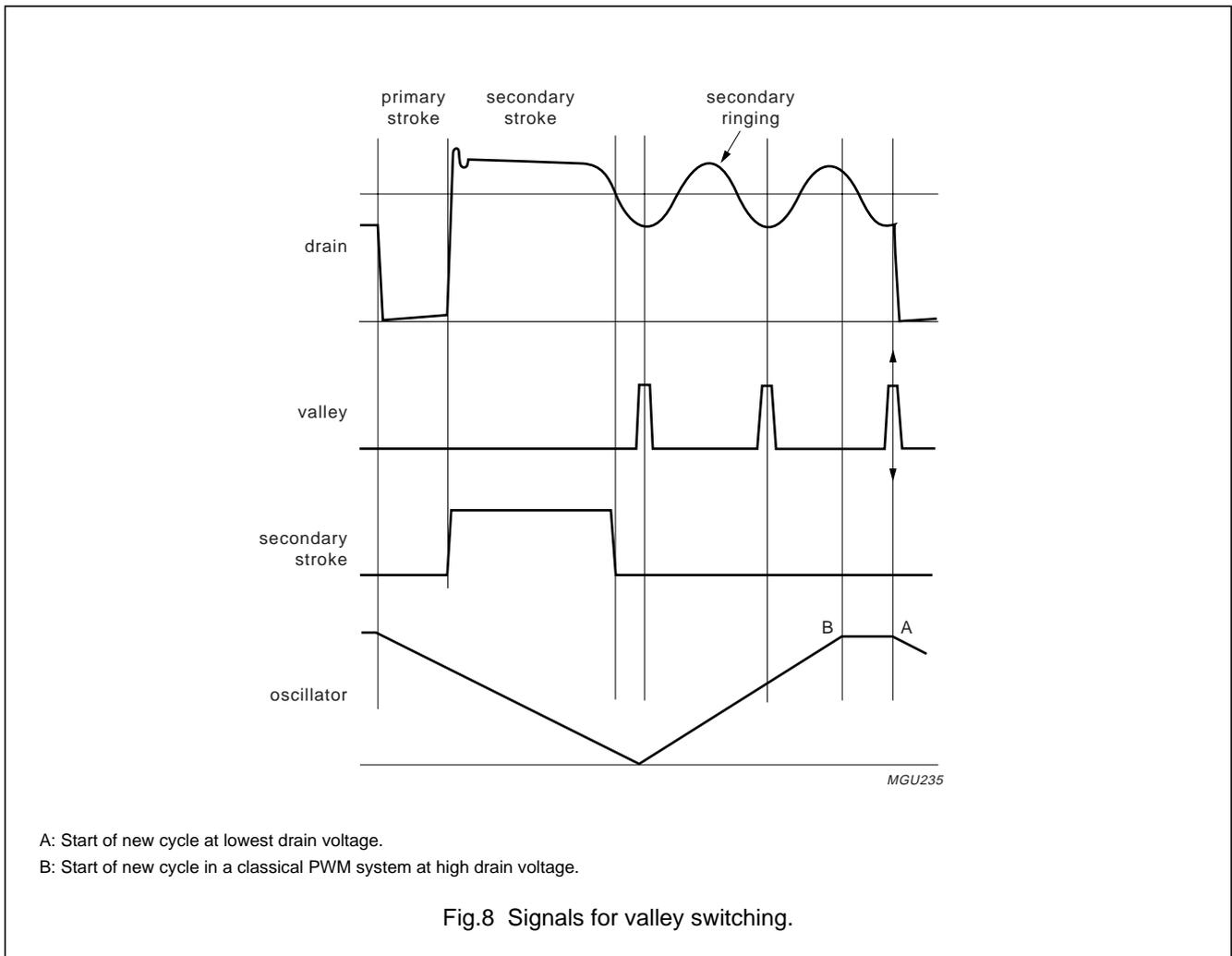
Valley switching (see Fig.8)

A new cycle starts when the power switch is switched on. After the 'on-time' (which is determined by the 'sense' voltage and the internal control voltage), the switch is opened and the secondary stroke starts.

After the secondary stroke, the drain voltage shows an oscillation with a frequency of approximately

$$\frac{1}{2 \times \pi \times \sqrt{L_p \times C_d}}$$

where L_p is the primary self inductance of the transformer and C_d is the capacitance on the drain node.



A: Start of new cycle at lowest drain voltage.
 B: Start of new cycle in a classical PWM system at high drain voltage.

Fig.8 Signals for valley switching.

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As soon as the oscillator voltage is high again and the secondary stroke has ended, the circuit waits for the lowest drain voltage before starting a new primary stroke. This method is called valley detection. Figure 8 shows the drain voltage together with the valley signal, the signal indicating the secondary stroke and the oscillator signal.

In an optimum design, the reflected secondary voltage on the primary side will force the drain voltage to zero. Thus, zero voltage switching is very possible, preventing large

capacitive switching losses $(P = \frac{1}{2} \times C \times V^2 \times f)$, and

allowing high frequency operation, which results in small and cost effective inductors.

OverCurrent Protection (OCP)

The cycle-by-cycle peak drain current limit circuit uses the external source resistor to measure the current accurately. This allows optimum size determination of the transformer core (cost issue). The circuit is activated after the leading edge blanking time t_{leb} . The OCP protection circuit limits the 'sense' voltage to an internal level.

OverPower Protection (OPP)

During the primary stroke, the rectified mains input voltage is measured by sensing the current drawn from pin DEM. This current is dependent on the mains voltage, according

to the following formula: $I_{DEM} \approx \frac{V_{aux}}{R_{DEM}} \approx \frac{N \times V_{mains}}{R_{DEM}}$

where: $N = \frac{N_{aux}}{N_p}$

The current information is used to adjust the peak drain current, which is measured via pin I_{sense} . The internal compensation is such that an almost mains independent maximum output power can be realized.

The OPP curve is given in Fig.9.

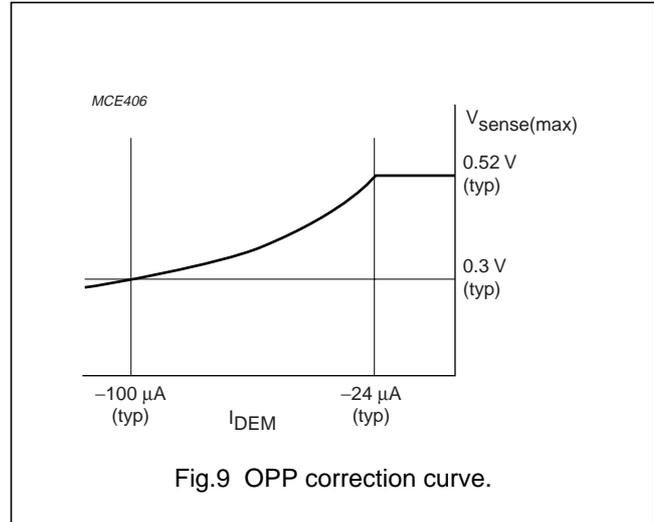


Fig.9 OPP correction curve.

Minimum and maximum 'on-time'

The minimum 'on-time' of the SMPS is determined by the Leading Edge Blanking (LEB) time. The IC limits the 'on-time' to $50 \mu s$. When the system desires an 'on-time' longer than $50 \mu s$, a fault condition is assumed, and the IC will stop switching and enter the safe restart mode.

Short winding protection

After the leading edge blanking time, the short winding protection circuit is also activated. If the 'sense' voltage exceeds the short winding protection voltage V_{swp} , the converter will stop switching. Once V_{CC} drops below the UVLO level, capacitor C_{VCC} will be recharged and the supply will restart again. This cycle will be repeated until the short-circuit is removed (safe restart mode).

The short winding protection will also protect in case of a secondary diode short-circuit.

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LOCK input

Pin LOCK is a general purpose (high-impedance) input pin, which can be used to switch off the IC. As soon as the voltage on this pin is raised above 2.5 V, switching will stop immediately. The voltage on the V_{CC} pin will cycle between V_{CC(start)} and V_{CC(UVLO)}, but the IC will not start switching again until the latch function is reset. The latch is reset as soon as the V_{CC} drops below 4.5 V (typical value). The internal OVP and OTP will also trigger this latch (see Fig.2).

The detection level of this input is related to the V_{CC(5V)} pin voltage in the following way: 0.5 × V_{CC(5V)} ± 4%. An internal Zener diode clamp of 5.6 V will protect this pin from excessive voltages. No internal filtering is done on this input.

OverTemperature Protection (OTP)

An accurate temperature protection is provided in the circuit. When the junction temperature exceeds the thermal shutdown temperature, the IC will stop switching. When V_{CC} drops to UVLO, capacitor C_{VCC} will be recharged to the V_{start} level, however the IC will not start switching again. Subsequently, V_{CC} will drop again to the UVLO level, etc.

Operation only recommences when the V_{CC} voltage drops below a level of approximately 4.5 V (practically when the V_{mains} has been disconnected for a short period).

Soft start-up

To prevent transformer rattle during hiccup, the transformer peak current is slowly increased by the soft start function. This can be achieved by inserting a resistor and a capacitor between pin I_{sense} and the sense resistor (see Fig.10). An internal current source charges the capacitor to V = I_{SS} × R_{SS}, with a maximum of approximately 0.5 V.

The start level and the time constant of the increasing primary current level can be adjusted externally by changing the values of R_{SS} and C_{SS}.

$$I_{\text{primary(max)}} = \frac{V_{\text{ocp}} - (I_{\text{SS}} \times R_{\text{SS}})}{R_{\text{sense}}}$$

$$\tau = R_{\text{SS}} \times C_{\text{SS}}$$

The charging current I_{SS} will flow as long as the voltage on pin I_{sense} is below approximately 0.5 V. If the voltage on pin I_{sense} exceeds 0.5 V, the soft start current source will start limiting the current I_{SS}. At the V_{CC(start)} level, the I_{SS} current source is completely switched off.

Since the soft start current I_{SS} is subtracted from pin V_{CC} charging current, the R_{SS} value will affect the V_{CC} charging current level by a maximum of 60 μA (typical value).

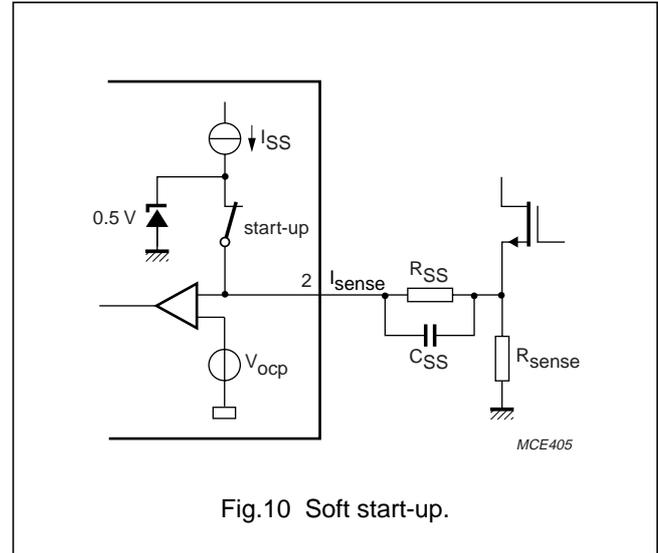


Fig.10 Soft start-up.

5 V output

Pin V_{CC(5V)} can be used for supplying external circuitry. The maximum output current must be limited to 1 mA. If higher peak currents are required, an external RC combination should limit the current drawn from this pin to 1 mA maximum.

The 5 V output voltage will be available as soon as the start-up voltage is reached. As the high voltage supply can not supply the 5 V pin during start-up and/or shutdown, during latched shutdown (via pin LOCK or other latched protection such as OVP or OTP), the voltage is switched to zero.

Driver

The driver circuit to the gate of the power MOSFET has a current sourcing capability of typically 170 mA and a current sink capability of typically 700 mA. This permits fast turn-on and turn-off of the power MOSFET for efficient operation. A low driver source current has been chosen to limit the ΔV/Δt at switch-on. This reduces Electro Magnetic Interference (EMI) and also limits the current spikes across R_{sense}.

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LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134); note 1.

| SYMBOL | PARAMETER | CONDITIONS | MIN. | MAX. | UNIT |
|---------------------|------------------------------------|--------------------------|------|------|------|
| Voltages | | | | | |
| V _{VCOadj} | voltage on pin VCOadj | continuous | -0.4 | +5 | V |
| V _{sense} | voltage on pin I _{sense} | current limited | -0.4 | - | V |
| V _{DRAIN} | voltage on pin DRAIN | | -0.4 | +650 | V |
| V _{CC} | supply voltage | continuous | -0.4 | +20 | V |
| V _{LOCK} | voltage on pin LOCK | continuous | -0.4 | +7 | V |
| V _{CTRL} | voltage on pin CTRL | | -0.4 | +5 | V |
| V _{DEM} | voltage on pin DEM | current limited | -0.4 | - | V |
| Currents | | | | | |
| I _{sense} | current on pin I _{sense} | | -1 | +10 | mA |
| I _{STDBY} | current on pin STDBY | | -1 | - | mA |
| I _{DRIVER} | current on pin DRIVER | d < 10% | -0.8 | +2 | A |
| I _{DRAIN} | current on pin DRAIN | | - | +5 | mA |
| I _{CC(5V)} | current on pin V _{CC(5V)} | | -1 | 0 | mA |
| I _{CTRL} | current on pin CTRL | | - | +5 | mA |
| I _{DEM} | current on pin DEM | | -250 | +250 | μA |
| General | | | | | |
| P _{tot} | total power dissipation | T _{amb} < 70 °C | - | 0.75 | W |
| T _{stg} | storage temperature | | -55 | +150 | °C |
| T _j | junction temperature | | -20 | +145 | °C |
| ESD | | | | | |
| V _{esd} | electrostatic discharge voltage | | | | |
| | pins 1 to 6 and pins 9 to 14 | HBM class 1; note 2 | - | 2000 | V |
| | pin 7 | HBM class 1; note 2 | - | 1500 | V |
| | any other pin | MM; note 3 | - | 400 | V |

Notes

- All voltages are measured with respect to ground; positive currents flow into the chip; pin V_{CC} must not be current driven. The voltage ratings are valid provided other ratings are not violated; current ratings are valid provided the maximum power rating is not violated.
- Human Body Model (HBM): equivalent to discharging a 100 pF capacitor through a 1.5 kΩ series resistor.
- Machine Model (MM): equivalent to discharging a 200 pF capacitor through a 0.75 μH coil and a 10 Ω resistor.

THERMAL CHARACTERISTICS

| SYMBOL | PARAMETER | CONDITIONS | VALUE | UNIT |
|----------------------|---|---------------------|-------|------|
| R _{th(j-a)} | thermal resistance from junction to ambient | in free air; note 1 | 100 | K/W |

Note

- With pin GND connected to sufficient copper area on the printed-circuit board.

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QUALITY SPECIFICATION

In accordance with "SNW-FQ-611D".

CHARACTERISTICS

$T_{amb} = 25\text{ °C}$; $V_{CC} = 15\text{ V}$; all voltages are measured with respect to ground; currents are positive when flowing into the IC; unless otherwise specified.

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|--|---|--------------------|-----------|-------|---------------|
| Start-up current source (pin DRAIN) | | | | | | |
| I_{DRAIN} | supply current from pin DRAIN | $V_{CC} = 0\text{ V}$; $V_{DRAIN} > 100\text{ V}$ | 1.0 | 1.2 | 1.4 | mA |
| | | with auxiliary supply; $V_{DRAIN} > 100\text{ V}$ | – | 100 | 300 | μA |
| BV_{DSS} | breakdown voltage | | 650 | – | – | V |
| M-level | mains-dependent operation-enabling level | | 60 | – | 100 | V |
| Supply voltage management (pin V_{CC}) | | | | | | |
| $V_{CC(start)}$ | start-up voltage on V_{CC} | | 10.3 | 11 | 11.7 | V |
| $V_{CC(UVLO)}$ | undervoltage lock-out on V_{CC} | | 8.1 | 8.7 | 9.3 | V |
| $V_{CC(hys)}$ | hysteresis voltage on V_{CC} | $V_{CC(start)} - V_{CC(UVLO)}$ | 2.0 | 2.3 | 2.6 | V |
| $I_{CC(h)}$ | pin V_{CC} charging current (high) | $V_{DRAIN} > 100\text{ V}$; $V_{CC} < 3\text{ V}$ | –1.2 | –1 | –0.8 | mA |
| $I_{CC(l)}$ | pin V_{CC} charging current (low) | $V_{DRAIN} > 100\text{ V}$; $3\text{ V} < V_{CC} < V_{CC(UVLO)}$ | –1.2 | –0.75 | –0.45 | mA |
| $I_{CC(restart)}$ | pin V_{CC} restart current | $V_{DRAIN} > 100\text{ V}$; $V_{CC(UVLO)} < V_{CC} < V_{CC(start)}$ | –650 | –550 | –450 | μA |
| $I_{CC(oper)}$ | supply current under normal operation | no load on pin DRIVER | 1.1 | 1.3 | 1.5 | mA |
| Demagnetization management (pin DEM) | | | | | | |
| $V_{th(DEM)}$ | demagnetization comparator threshold voltage on pin DEM | | 50 | 100 | 150 | mV |
| I_{DEM} | pin DEM current | $V_{DEM} = 50\text{ mV}$ | –50 ⁽¹⁾ | – | 0 | nA |
| $V_{clamp(DEM)(neg)}$ | negative clamp voltage on pin DEM | $I_{DEM} = -150\text{ }\mu\text{A}$ | –0.5 | –0.25 | –0.05 | V |
| $V_{clamp(DEM)(pos)}$ | positive clamp voltage on pin DEM | $I_{DEM} = 250\text{ }\mu\text{A}$ | 0.5 | 0.7 | 0.9 | V |
| t_{suppr} | suppression of transformer ringing at start of secondary stroke | | 1.1 | 1.5 | 1.9 | μs |
| Pulse width modulator | | | | | | |
| $t_{on(min)}$ | minimum on-time | | – | t_{ieb} | – | ns |
| $t_{on(max)}$ | maximum on-time | latched | 40 | 50 | 60 | μs |
| Oscillator | | | | | | |
| $f_{osc(l)}$ | oscillator low fixed frequency | $V_{CTRL} > 1.5\text{ V}$ | 19 | 24 | 29 | kHz |
| $f_{osc(h)}$ | oscillator high fixed frequency | $V_{CTRL} < 1\text{ V}$ | 50 | 63 | 75 | kHz |
| $V_{VCO(start)}$ | peak voltage on pin I_{sense} , where frequency reduction starts | see Figs 6 and 7 | – | V_{CO1} | – | mV |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|--|--|------|--------------------|------|------------------|
| $V_{VCO(max)}$ | peak voltage on pin I_{sense} , where the frequency is equal to $f_{osc(l)}$ | | – | $V_{CO1} - 25$ | – | mV |
| Duty cycle control (pin CTRL) | | | | | | |
| $V_{CTRL(min)}$ | minimum voltage on pin CTRL for maximum duty cycle | | – | 1.0 | – | V |
| $V_{CTRL(max)}$ | maximum voltage on pin CTRL for minimum duty cycle | | – | 1.5 | – | V |
| 5 V output (pin $V_{CC(5V)}$) | | | | | | |
| $V_{CC(5V)}$ | output voltage | $I_O = 1 \text{ mA}$ | 4.75 | 5.0 | 5.25 | V |
| $I_{CC(5V)}$ | current capability of pin $V_{CC(5V)}$ | | –1.0 | – | – | mA |
| LOCK input (pin LOCK) | | | | | | |
| V_{LOCK} | LOCK trip level | | 2.37 | 2.5 | 2.63 | V |
| $V_{CC(reset)}$ | voltage level on pin V_{CC} which resets the latch | $V_{LOCK} < 2.3 \text{ V}$ | – | 4.5 | – | V |
| $REL_{LOCK,5V}$ | relation to 5 V output (pin $V_{CC(5V)}$) | $V_{LOCK} = 0.5 \times V_{CC(5V)}$ | –4 | – | +4 | % |
| Valley switch (pin DRAIN) | | | | | | |
| $\Delta V/\Delta t_{valley}$ | valley recognition voltage change | | –85 | – | +85 | V/ μs |
| $t_{valley-swon}$ | delay from valley recognition to switch-on | | – | 150 ⁽¹⁾ | – | ns |
| Overcurrent and short winding protection (pin I_{sense}) | | | | | | |
| $V_{sense(max)}$ | maximum source voltage OCP | $\Delta V/\Delta t = 0.1 \text{ V}/\mu\text{s}$ | 0.48 | 0.52 | 0.56 | V |
| t_{PD} | propagation delay from detecting $V_{sense(max)}$ to switch-off | $\Delta V/\Delta t = 0.5 \text{ V}/\mu\text{s}$ | – | 140 | 185 | ns |
| V_{swp} | short winding protection voltage | | 0.83 | 0.88 | 0.96 | V |
| t_{leb} | blanking time for current and short winding protection | | 300 | 370 | 440 | ns |
| I_{SS} | soft start current | $V_{sense} < 0.5 \text{ V}$ | 45 | 60 | 75 | μA |
| Overvoltage protection (pin DEM) | | | | | | |
| $I_{OVP(DEM)}$ | OVP level on pin DEM | set by resistor R_{DEM} ; see Section "OverVoltage Protection (OVP)" | 54 | 60 | 66 | μA |
| Overpower protection (pin DEM) | | | | | | |
| $I_{OPP(DEM)}$ | OPP current on pin DEM to start OPP correction | set by resistor R_{DEM} ; see Section "OverPower Protection (OPP)" | – | –24 | – | μA |
| $I_{OPP50\%(DEM)}$ | OPP current on pin DEM, where maximum source voltage is limited to 0.3 V | | – | –100 | – | μA |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|-----------------------------------|---|--|------|------------------|------|--------------------|
| Standby output (pin STDBY) | | | | | | |
| V_{STDBY} | standby output voltage | | 4.75 | 5.0 | 5.25 | V |
| I_{source} | source current capability | $V_{\text{STDBY}} = 1.5 \text{ V}$ | 20 | 22 | 24 | μA |
| I_{sink} | sink current capability | $V_{\text{STDBY}} = 1.5 \text{ V}$ | 2 | – | – | mA |
| Driver (pin DRIVER) | | | | | | |
| I_{source} | source current capability of driver | $V_{\text{CC}} = 9.5 \text{ V}; V_{\text{DRIVER}} = 2 \text{ V}$ | – | –170 | –88 | mA |
| I_{sink} | sink current capability of driver | $V_{\text{CC}} = 9.5 \text{ V}; V_{\text{DRIVER}} = 2 \text{ V}$ | – | 300 | – | mA |
| | | $V_{\text{CC}} = 9.5 \text{ V}; V_{\text{DRIVER}} = 9.5 \text{ V}$ | 400 | 700 | – | mA |
| $V_{\text{o(driver)(max)}}$ | maximum output voltage of driver | $V_{\text{CC}} > 12 \text{ V}$ | – | 11.5 | 12 | V |
| Temperature protection | | | | | | |
| $T_{\text{prot(max)}}$ | maximum temperature protection level | | 130 | 140 | 150 | $^{\circ}\text{C}$ |
| $T_{\text{prot(hys)}}$ | hysteresis for the temperature protection level | | – | 8 ⁽¹⁾ | – | $^{\circ}\text{C}$ |

Note

1. Guaranteed by design.

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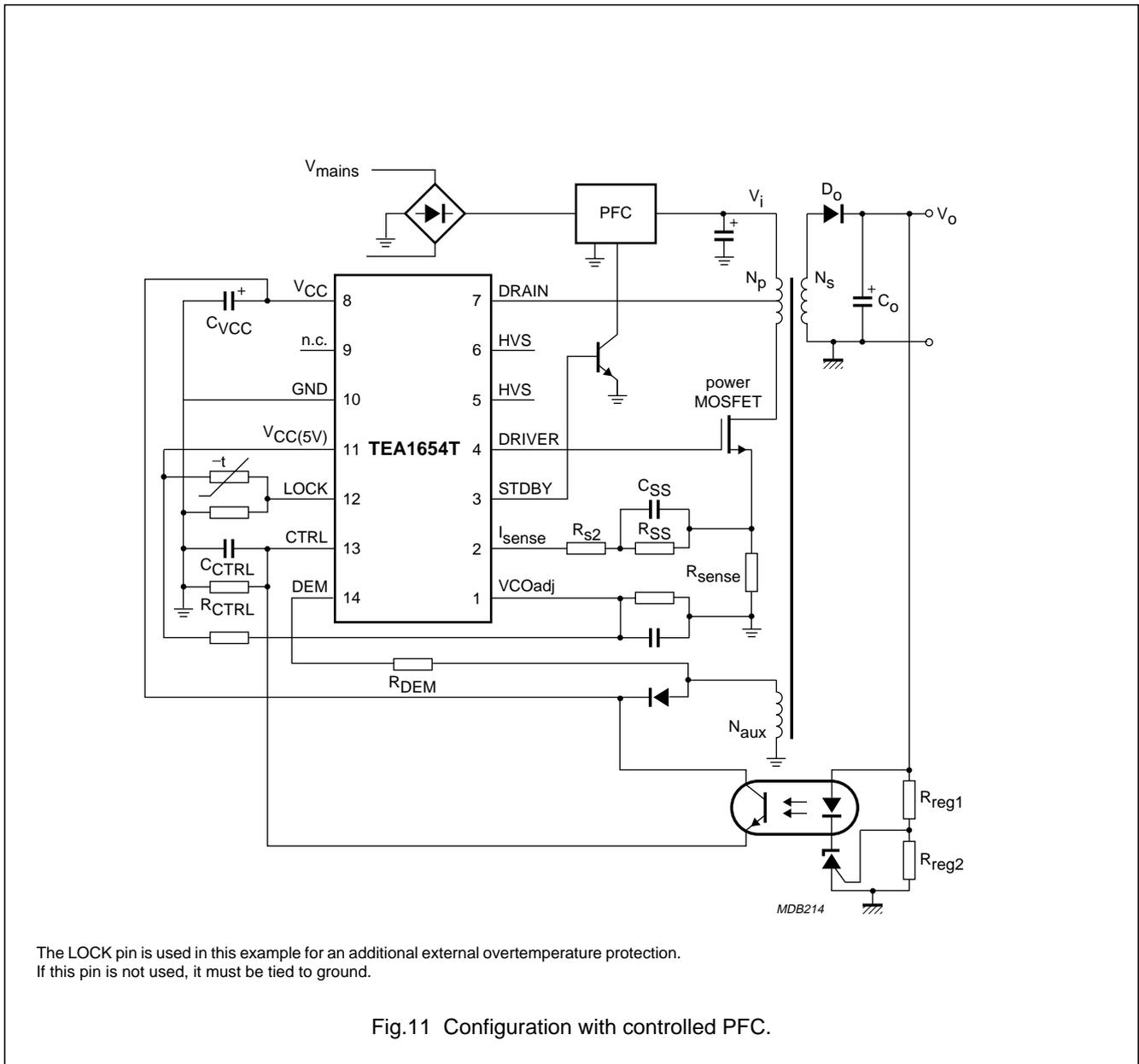
TEA1654

APPLICATION INFORMATION

A converter with the TEA1654 consists of an input filter, a transformer with a third winding (auxiliary), and an output stage with a feedback circuit.

Capacitor C_{VCC} (at pin V_{CC}) buffers the supply voltage of the IC, which is powered via the high voltage rectified mains during start-up and via the auxiliary winding during operation.

A sense resistor converts the primary current into a voltage at pin I_{sense} . The value of this sense resistor defines the maximum primary peak current.



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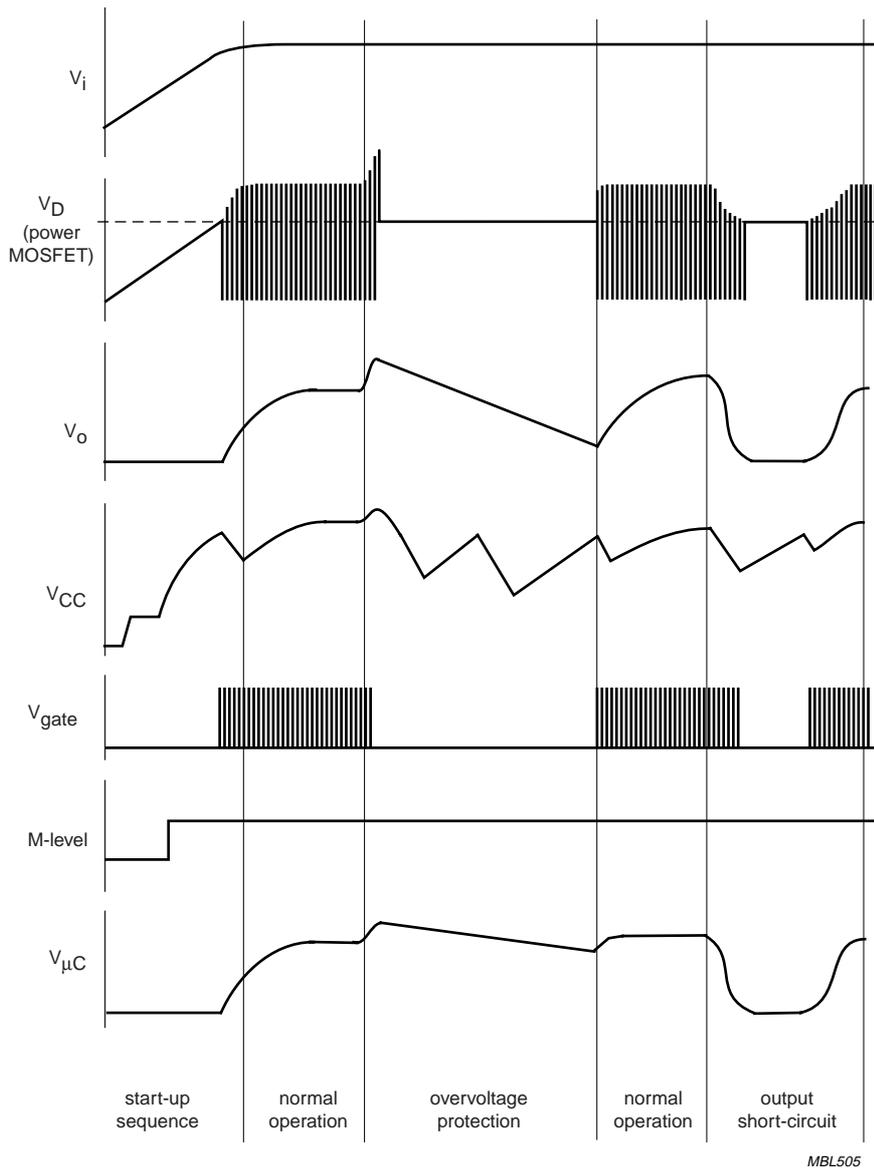


Fig.12 Typical waveforms.

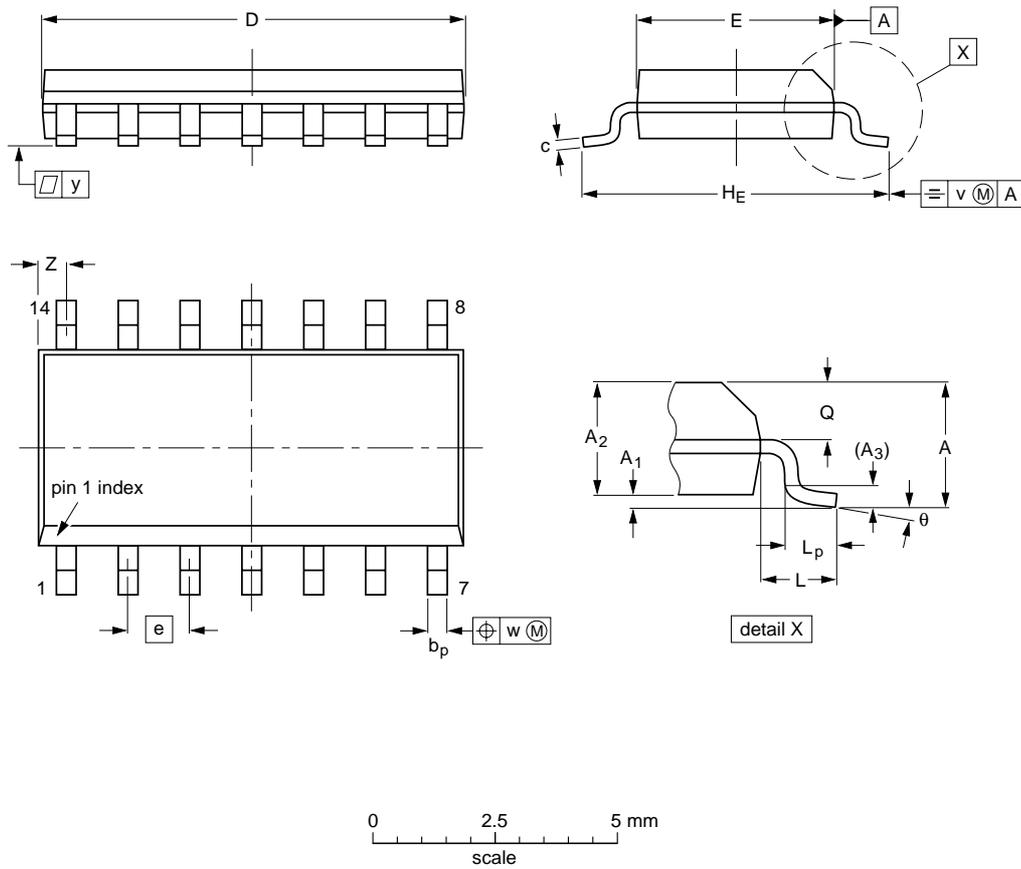
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PACKAGE OUTLINE

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽¹⁾ | e | H _E | L | L _p | Q | v | w | y | Z ⁽¹⁾ | θ |
|--------|--------|----------------|----------------|----------------|----------------|------------------|------------------|------------------|------|----------------|-------|----------------|----------------|------|------|-------|------------------|----------|
| mm | 1.75 | 0.25 0.10 | 1.45 1.25 | 0.25 | 0.49 0.36 | 0.25 0.19 | 8.75 8.55 | 4.0 3.8 | 1.27 | 6.2 5.8 | 1.05 | 1.0 0.4 | 0.7 0.6 | 0.25 | 0.25 | 0.1 | 0.7 0.3 | 8° 0° |
| inches | 0.069 | 0.010 0.004 | 0.057 0.049 | 0.01 | 0.019 0.014 | 0.0100 0.0075 | 0.35 0.34 | 0.16 0.15 | 0.05 | 0.244 0.228 | 0.041 | 0.039 0.016 | 0.028 0.024 | 0.01 | 0.01 | 0.004 | 0.028 0.012 | |

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|--------|-------|--|---------------------|----------------------|
| | IEC | JEDEC | JEITA | | | |
| SOT108-1 | 076E06 | MS-012 | | | | 99-12-27 03-02-19 |

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SOLDERING

Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *"Data Handbook IC26; Integrated Circuit Packages"* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferably be kept:

- below 220 °C for all the BGA packages and packages with a thickness ≥ 2.5 mm and packages with a thickness < 2.5 mm and a volume ≥ 350 mm³ so called thick/large packages
- below 235 °C for packages with a thickness < 2.5 mm and a volume < 350 mm³ so called small/thin packages.

Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

- For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

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Suitability of surface mount IC packages for wave and reflow soldering methods

| PACKAGE ⁽¹⁾ | SOLDERING METHOD | |
|--|-----------------------------------|-----------------------|
| | WAVE | REFLOW ⁽²⁾ |
| BGA, LBGA, LFBGA, SQFP, TFBGA, VFBGA | not suitable | suitable |
| DHVQFN, HBCC, HBGA, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, HVQFN, HVSON, SMS | not suitable ⁽³⁾ | suitable |
| PLCC ⁽⁴⁾ , SO, SOJ | suitable | suitable |
| LQFP, QFP, TQFP | not recommended ⁽⁴⁾⁽⁵⁾ | suitable |
| SSOP, TSSOP, VSO, VSSOP | not recommended ⁽⁶⁾ | suitable |

Notes

1. For more detailed information on the BGA packages refer to the “(LF)BGA Application Note” (AN01026); order a copy from your Philips Semiconductors sales office.
2. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the “Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods”.
3. These packages are not suitable for wave soldering. On versions with the heatsink on the bottom side, the solder cannot penetrate between the printed-circuit board and the heatsink. On versions with the heatsink on the top side, the solder might be deposited on the heatsink surface.
4. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
5. Wave soldering is suitable for LQFP, TQFP and QFP packages with a pitch (e) larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
6. Wave soldering is suitable for SSOP, TSSOP, VSO and VSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

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DATA SHEET STATUS

| LEVEL | DATA SHEET STATUS ⁽¹⁾ | PRODUCT STATUS ⁽³⁾ | DEFINITION |
|-------|----------------------------------|-------------------------------|--|
| I | Objective data | Development | This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice. |
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Notes

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Contact information

For additional information please visit <http://www.semiconductors.philips.com>. Fax: +31 40 27 24825

For sales offices addresses send e-mail to: sales.addresses@www.semiconductors.philips.com.

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