# **FLM DO 8 M12**

## Fieldline Modular Device With Eight Digital Outputs

Data Sheet 697100

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This data sheet is only valid in association with the FLS FLM SYS INST UM E user manual or the user manual for your bus system (see "Ordering Data" on page 14).

## Function

The device is designed for use in the Fieldline modular local bus, which is opened by a Fieldline modular bus coupler. It is used to output digital signals.

#### Features

- Connection to the Fieldline modular local bus using M12 connectors (B-encoded)
- Connection of digital actuators using M12 connectors, each with a load capacity of 500 mA (nominal current)
- Flexible voltage supply concept
- LED diagnostic and status indicators
- Short-circuit and overload protection of the actuator supply
- IP65/IP67 protection



Figure 1 The FLM DO 8 M12 Fieldline device

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## Connections



Figure 2	Connections of the FLM DO 8 M12

#### Pin Assignment of LB IN/LB OUT



Figure 3 Pin assignment of LB IN/ LB OUT (M12 B-encoded)

Des.	Meaning
FE	Functional earth ground
LB IN	Local bus IN
LB OUT	Local bus OUT
U <sub>LS</sub> IN	Voltage supply IN (logic)
U <sub>LS</sub> OUT	Voltage supply OUT (logic) for additional devices
OUT1 to OUT8	Outputs 1 to 8
U <sub>A</sub> IN	Voltage supply IN of the outputs (OUT1 to OUT8) with voltages $U_{A11}$ and $U_{A12}$
U <sub>A</sub> OUT	Voltage supply OUT of the outputs for other devices



In general, the maximum current load of 4 A per contact must not be exceeded.

Pin	IN	OUT
1	DO	DO
2	DO	DO
3	DI	DI
4	DI	DI
5	GND	GND



The thread is used for shielding.



### Pin Assignment of the Voltage Supply $\mathrm{U}_{\mathrm{LS}}$



Pin	IN	OUT
1	U <sub>L</sub> +24 V	U <sub>L</sub> +24 V
2	U <sub>S</sub> GND	U <sub>S</sub> GND
3	U <sub>L</sub> GND	U <sub>L</sub> GND
4	U <sub>S</sub> +24 V	U <sub>S</sub> +24 V
5	500 kbaud/ 2 Mbaud	500 kbaud/ 2 Mbaud
		•

• The transmission speed is switched at the bus coupler.

### Pin Assignment of the Voltage Supply $U_A$ of the Outputs





Pin	IN	OUT
1	U <sub>A11</sub> +24 V	U <sub>A11</sub> +24 V
2	U <sub>A12</sub> GND	U <sub>A12</sub> GND
3	U <sub>A11</sub> GND	U <sub>A11</sub> GND
4	U <sub>A12</sub> +24 V	U <sub>A12</sub> +24 V
5	Not used	Not used

# Figure 5 Pin assignment of the voltage supply $U_A$ of the outputs

## Pin Assignment of the Outputs



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Figure 6 Pin assignment of the outputs

Pin	Output Socket
1	Not used
2	Not used
3	GND
4	Output
5	FE





#### Local LED Diagnostic and Status Indicators





Des.	Color	Meaning
D	Green LED	Diagnostics
	ON:	Bus active
	Flashing, 0.5 Hz:	Communications power present, bus not active
	Flashing, 2 Hz:	Communications power present, bus active, I/O error
	Flashing, 4 Hz:	Communications power present, transmission path to the left of the flashing device failed, device to the left of the flashing device failed, devices to the right of the flashing device are not part of the configuration frame
	OFF:	Communications power not present, bus not active
US	Green LED	Voltage supply for OUT1 to OUT8
	ON:	Voltage supply present
	OFF:	Voltage supply too low
ХХ	Yellow LED	Status indicators of the outputs
	ON:	Output active
	OFF:	Output not active
UA11	Green LED	Voltage supply for OUT1 to OUT4
	ON:	Voltage supply for OUT1 to OUT4 present
	OFF:	Voltage supply for OUT1 to OUT4 too low
UA12	Green LED	Voltage supply for OUT5 to OUT8
	ON:	Voltage supply for OUT5 to OUT8 present
	OFF:	Voltage supply for OUT5 to OUT8 too low
E11	Red LED	Overload of outputs OUT1 to OUT4
	ON:	Outputs OUT1 to OUT4 overloaded
	OFF:	Outputs OUT1 to OUT4 not overloaded
E11	Red LED	Overload of outputs OUT5 to OUT8
	ON:	Outputs OUT5 to OUT8 overloaded
	OFF:	Outputs OUT5 to OUT8 not overloaded



#### Internal Circuit Diagram



Figure 8 Internal wiring of the connection points



For information on electrically isolated areas, please refer to page 13.

Key:





## **Connection Example**



Figure 9 Typical connection of actuators

## **Connection Notes**



#### Meet noise immunity requirements Connect FE using a mounting screw

or a cable connection to the FE connection latch (when mounting on a non-conductive surface).



#### Ensure degree of protection

To ensure IP65/IP67 protection, cover unused sockets with protective caps.



#### Avoid polarity reversal

Avoid polarity reversal of the supply voltages  $U_S$ ,  $U_A$ , and  $U_L$  in order to prevent damage to the device.



# Observe connection point assignment

When connecting the actuators, observe the assignment of the connection points to the OUT process data (see "Process Data" on page 8).



# **Programming Data/Configuration Data**

#### INTERBUS

ID code	BD <sub>hex</sub> (189 <sub>dec</sub> )
Length code	81 <sub>hex</sub>
Process data channel	8 bits
Output address area	8 bits
Parameter channel (PCP)	0 bits
Register length (bus)	8 bits

#### Other Bus Systems



For the programming data of other bus systems, please refer to the appropriate electronic device data sheet (GSD, EDS). For additional information, please refer to the user manuals, see "Ordering Data" on page 14.

## **Process Data**

#### Assignment of the Connection Points to the OUT Process Data

(Byte.bit)	Byte				Byt	e 0			
view	Bit	7	6	5	4	3	2	1	0
Device	Input	8	7	6	5	4	3	2	1



For the assignment of the illustrated (byte.bit) view for your INTERBUS control or computer system, please refer to data sheet DB GB IBS SYS ADDRESS, Part No. 90 00 99 0.



# **Technical Data**

## **Device Dimensions**



General Data	
Order designation	FLM DO 8 M12
Order no.	27 36 29 1
Housing dimensions (width x height x depth)	70 mm x 178 mm x 49.3 mm (2.756 x 7.008 x 1.941 in.)
Weight	310 g, approximately
Operating mode	Process data mode with 8 bits
Type of actuator connection	2, 3 or 4-wire technology
Permissible temperature (operation)	-25°C to +60°C (-13°F to +140°F)
Permissible temperature (storage/transport)	-25°C to +85°C (-13°F to +185°F)
Permissible humidity (storage/transport)	95%
For a short period, slight condensation	on may appear on the housing.

Permissible air pressure (operation)	80 kPa to 106 kPa (up to 2000 m [6562 ft.] above sea level)
Permissible air pressure (storage/transport)	70 kPa to 106 kPa (up to 3000 m [9843 ft.] above sea level)
Degree of protection	IP65/IP67 according to IEC 60529
Class of protection	Class 3 according to VDE 0106, IEC 60536

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n each space direction
half sinusoidal wave positive and in each space direction

For additional information on mechanical requirements and ambient conditions, please contact Phoenix Contact.

Voltage Supply		
Nominal value	24 V DC	
Tolerance	±25%	
Current consumption at U <sub>L</sub> at 24 V DC		
At 500 kbaud	40 mA, typical (50 mA, maximum)	
At 2 Mbaud	45 mA, typical (50 mA, maximum)	
Current consumption at U <sub>S</sub> at 24 V DC	5 mA, typical, + actuator current (600 mA, maximum)	

Digital Outputs		
Number	8	
Nominal output voltage U <sub>OUT</sub>	U <sub>Axx</sub> – 1 V	
Differential voltage for Inom	≤ 1 V	
Nominal current I <sub>nom</sub> per channel	500 mA	
Total current	4 A (observe derating)	
Protection	Short circuit; overload	

Single chip structure, i.e., all channels are thermally isolated. An error in one channel can affect the other channels. The outputs have separate overload protection.





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•	Digital Outputs (Continued)		
ß	At an ambient temperature of 45°C (113°F) or higher, voltages $U_L$ and $U_S$ at socket $U_{LS}$ OUT can each only carry a maximum current of 2 A. Voltages $U_{A11}$ and $U_{A12}$ at socket OUT can each only carry a maximum current of 2 A.		
Nominal I	oad per channel		
– Ohmic 12 W		12 W	
– Inductive 12		12 VA (1.2 H, 48 Ω)	
– Lamp	– Lamp 12 W		
Signal de	lay upon power up	Approximately 50 µs, typical	
Signal de	lay upon power down	Approximately 70 µs, typical	
R B	The behavior of the output voltage dep	pends on the switched load.	
Switching	frequency with		
-	nal ohmic load	300 Hz, maximum	
R S	This switching frequency is limited b the software, and the control or com	y the number of bus devices, the bus structure, puter system used.	
– Nomir			
	the software, and the control or com	puter system used.	
	the software, and the control or com nal inductive load nal lamp load	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum	
– Nomir Overload	the software, and the control or com nal inductive load nal lamp load	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum	
– Nomir Overload Restart fre	the software, and the control or com nal inductive load nal lamp load response	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum Auto restart	
– Nomir Overload Restart fre Response	the software, and the control or com nal inductive load nal lamp load response equency with ohmic overload (2 $\Omega$ )	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum Auto restart 45 Hz, approximately	
– Nomir Overload Restart fro Response Reverse v	the software, and the control or com nal inductive load nal lamp load response equency with ohmic overload (2 Ω) e with inductive overload	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum Auto restart 45 Hz, approximately Output may be damaged	
– Nomir Overload Restart fro Response Reverse v Resistand voltages	the software, and the control or com nal inductive load nal lamp load response equency with ohmic overload (2 $\Omega$ ) e with inductive overload voltage protection against short pulses	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum Auto restart 45 Hz, approximately Output may be damaged Protected against reverse voltages	
- Nomin Overload Restart fro Response Reverse v Resistanc voltages Response	the software, and the control or com nal inductive load nal lamp load response equency with ohmic overload (2 $\Omega$ ) e with inductive overload voltage protection against short pulses e to permanently applied reverse	puter system used.0.5 Hz (1.2 H, 48 Ω), maximum300 Hz, maximumAuto restart45 Hz, approximatelyOutput may be damagedProtected against reverse voltagesUp to 2 AThe output follows the supply voltage without	
- Nomir Overload Restart fro Response Reverse v Resistanc voltages Response Validity of voltage su	the software, and the control or com nal inductive load nal lamp load response equency with ohmic overload (2 $\Omega$ ) e with inductive overload voltage protection against short pulses e to permanently applied reverse e upon power down foutput data after connecting the upply (power up) of the voltage induced on circuit	puter system used. 0.5 Hz (1.2 H, 48 Ω), maximum 300 Hz, maximum Auto restart 45 Hz, approximately Output may be damaged Protected against reverse voltages Up to 2 A The output follows the supply voltage without delay.	

Digital Outputs (Continued)		
Protective circuit type	Integrated free-wheeling diode for each channel	
Overcurrent shutdown	0.7 A, minimum	
Output current when switched off	20 μA, maximum	
Output current with ground connection interrupt when switched off	5 mA, maximum	

#### **Error Messages**

Overload of outputs

Yes

If an error is triggered at the outputs due to an overload, the device switches off the corresponding output and sends an I/O error message to the master.

< 30 m (98.43 ft.)

Permissible cable length to the actuator

Output Characteristic Curve When Switched On (Typical)		
Output Current (A) Differential Output Voltage (V)		
0	0	
0.1	0.04	
0.2	0.08	
0.3	0.12	
0.4	0.16	
0.5	0.20	

Output Characteristic Curve for Ground Connection Interrupt (U <sub>Axx</sub> = 30 V DC)		
Load Resistance (kΩ)	Output Voltage (V)	
œ	29.9	
1000	11.2	
100	1.7	
10	0.2	
1	0	

Interface		
Bus system	Fieldline modular local bus	
Incoming Bus		
Coupling of shield connection	Directly to FE	
Transmission speed	500 kbaud/2 Mbaud	
Outgoing Bus		
Coupling of shield connection	Directly to FE	
Transmission speed	500 kbaud/2 Mbaud	

Electrical Isolation/Isolation of the Voltage Areas			
For device connection, please note the instructions and regulations in the "Installing the Fieldline Product Range" user manual FLS FLM SYS INST UM E (Order No. 26 98 97 3).			
Separate Potentials in the FLM DO 8 M12			
- Test Dis	tance	- Test Voltage	
24 V supply (bus logic) / FE 500 V AC, 50 Hz, 1 min			
24 V supply (bus logic) / digital outputs (actuator supply) 500 V AC, 50 Hz, 1 min			
24 V supply (bus logic) / local bus 500 V AC, 50 Hz, 1 min			
Digital out	Digital outputs (actuator supply) / FE 500 V AC, 50 Hz, 1 min		
Digital outputs (actuator supply) / local bus 500 V AC, 50 Hz, 1 mir			
Local bus / FE 500 V AC, 50 Hz, 1 min			



# **Ordering Data**

Description	Order Designation	Order No.
Fieldline modular device with eight digital outputs	FLM DO 8 M12	27 36 29 1
Protective caps (for unused sockets) pack of 5	IBS IP PROT-IO	27 59 91 9
Protective caps (for unused connectors) pack of 5	PROT-M12-M	27 36 19 4
Shielded connector, 5-pos. female connector, B-encoded, for the incoming local bus	SACC-M12FSB-5SC SH	15 13 59 6
Shielded connector, 5-pos. male connector, B-encoded, for the outgoing local bus	SACC-M12MSB-5SC SH	15 13 57 0
Markers pack of 10	ZBF 12:UNBEDRUCKT	08 09 73 5
"Installing the Fieldline Product Range" user manual	FLS FLM SYS INST UM E	26 98 97 3
"Configuring an INTERBUS System Using Devices in the Fieldline Product Range" user manual	FLS FLM IB SYS PRO UM E	26 99 06 6
"Configuring a PROFIBUS DP System Using Devices in the Fieldline Product Range" user manual	FLS FLM PB SYS PRO UM E	26 99 07 9
"Configuring a DeviceNet™ System Using Devices in the Fieldline Product Range" user manual	FLS FLM DN SYS PRO UM E	26 99 08 2
"Configuring a CANopen System Using Devices in the Fieldline Product Range" user manual	FLS FLM CO SYS PRO UM E	26 99 09 5
Additional accessories for connecting the actual catalog.	ors can be found in the Phoenix Conta	act PLUSCON



Make sure you always use the latest documentation. It can be downloaded at <u>www.phoenixcontact.com</u>.



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