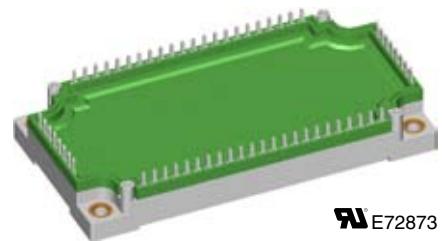
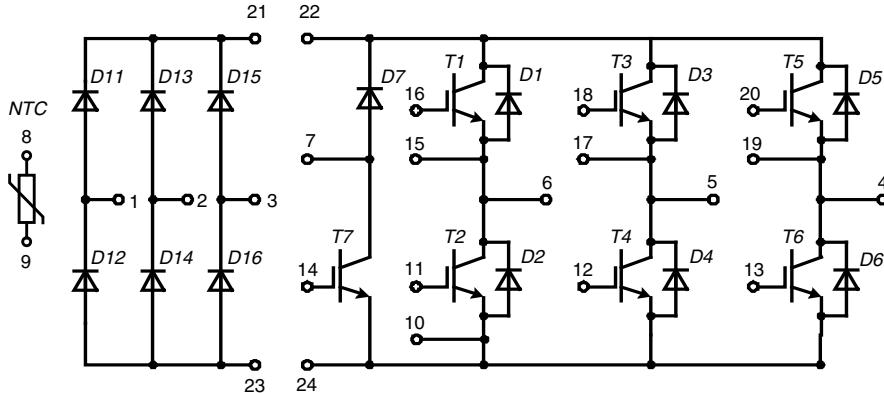


## Converter - Brake - Inverter Module (CBI3) with Trench IGBT technology



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 2200 \text{ V}$	$V_{CES} = 1700 \text{ V}$	$V_{CES} = 1700 \text{ V}$
$I_{FAVM} = 60 \text{ A}$	$I_{C25} = 48 \text{ A}$	$I_{C25} = 74 \text{ A}$
$I_{FSM} = 550 \text{ A}$	$V_{CE(sat)} = 2.1 \text{ V}$	$V_{CE(sat)} = 2.0 \text{ V}$

### Input Rectifier Bridge D11 - D16

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$		2200		V
$I_{FAV}$	$T_c = 80^\circ\text{C}; \text{sine } 180^\circ$	40		A
$I_{DAVM}$	$T_c = 80^\circ\text{C}; \text{rectangular; } d = 1/3; \text{bridge}$	130		A
$I_{FSM}$	$T_c = 25^\circ\text{C}; t = 10 \text{ ms; sine } 50 \text{ Hz}$	550		A
$P_{tot}$	$T_c = 25^\circ\text{C}$	110		W

### Symbol Conditions

### Characteristic Values

( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)

Symbol	Conditions		min.	typ.	max.	
$V_F$	$I_F = 50 \text{ A}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$			1.25	1.5	V
				1.25		V
$I_R$	$V_R = V_{RRM}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$			0.05	0.8	mA
				0.8		mA
$R_{thJC}$	(per diode)				1.1	K/W

### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- Electric braking operation

### Features

- High level of integration - only one power semiconductor module required for the whole drive
- IGBT technology with low saturation voltage, low switching losses and tail current, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

**Output Inverter T1 - T6**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1700		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	74		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	53		A
$I_{CM}$	$T_C = 80^\circ\text{C}; t_p = 1 \text{ ms}$	100		A
$P_{tot}$	$T_C = 25^\circ\text{C}$	290		W

**Symbol**    **Conditions****Characteristic Values** $(T_{VJ} = 25^\circ\text{C}, \text{unless otherwise specified})$ 

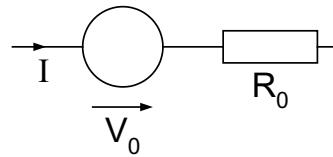
		min.	typ.	max.
$V_{CE(\text{sat})}$	$I_C = 50 \text{ A}; V_{GE} = 15 \text{ V}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.0 2.4	2.4 V V
$V_{GE(\text{th})}$	$I_C = 2 \text{ mA}; V_{GE} = V_{CE}$	5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$			0.4 mA mA
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$			400 nA
$C_{ies}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$		4.4	nF
$Q_{Gon}$	$V_{CE} = 900 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 75 \text{ A}$		600	nC
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 900 \text{ V}; I_C = 50 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 8 \Omega$		250 50 500 480 11 12	ns ns ns ns mJ mJ
<b>RBSOA</b>	$I_C = I_{CM}; V_{GE} = 15 \text{ V}$ $R_G = 27 \Omega; T_{VJ} = 125^\circ\text{C}$	$V_{CEK} \leq V_{CES} - L_S \frac{di}{dt}$		V
<b>t<sub>sc</sub></b> <b>(SCSOA)</b>	$V_{CE} = 1000 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 27 \Omega$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^\circ\text{C}$		10	$\mu\text{s}$
$R_{thJC}$			0.43	K/W

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings		
$I_{F25}$	$T_C = 25^\circ\text{C}$	56		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	39		A

**Symbol**    **Conditions****Characteristic Values**

		min.	typ.	max.
$V_F$	$I_F = 50 \text{ A}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.0 2.0	2.4 V V
$I_{RM}$ $Q_{rr}$ $t_{rr}$ $E_{rec}$	$I_F = 50 \text{ A}; di_F/dt = -1200 \text{ A}/\mu\text{s};$ $T_{VJ} = 125^\circ\text{C}; V_R = 900 \text{ V}; V_{GE} = 0 \text{ V}$		80 20 650 9	A $\mu\text{C}$ ns mJ
$R_{thJC}$	(per diode)			0.65 K/W

**Equivalent Circuits for Simulation****Conduction****IGBT** (typ. at  $V_{GE} = 15 \text{ V}; T_J = 125^\circ\text{C}$ )**T1-T6**       $V_0 = 1.0 \text{ V}; R_0 = 25 \text{ m}\Omega$ **T7**       $V_0 = 1.0 \text{ V}; R_0 = 28 \text{ m}\Omega$ **Diode** (typ. at  $T_J = 125^\circ\text{C}$ )**D1-D6**       $V_0 = 1.35 \text{ V}; R_0 = 15 \text{ m}\Omega$ **D7**       $V_0 = 1.65 \text{ V}; R_0 = 37 \text{ m}\Omega$ **D11-D16**       $V_0 = 0.83 \text{ V}; R_0 = 4.1 \text{ m}\Omega$

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1700	V	
$V_{GES}$	Continuous	$\pm 20$	V	
$I_{C25}$	$T_C = 25^\circ\text{C}$	48	A	
$I_{C80}$	$T_C = 80^\circ\text{C}$	34	A	
$I_{CM}$	$T_C = 80^\circ\text{C}; t_p = 1 \text{ ms}$	60	A	
$P_{tot}$	$T_C = 25^\circ\text{C}$	200	W	

**Symbol Conditions Characteristic Values**(T<sub>VJ</sub> = 25°C, unless otherwise specified)

			min.	typ.	max.	
$V_{CE(\text{sat})}$	$I_C = 30 \text{ A}; V_{GE} = 15 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$		1.9	2.2	V
		$T_{VJ} = 125^\circ\text{C}$		2.1		V
$V_{GE(\text{th})}$	$I_C = 2 \text{ mA}; V_{GE} = V_{CE}$		5		6.5	V
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$			0.3	mA
		$T_{VJ} = 125^\circ\text{C}$		0.6		mA
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$				400	nA
$C_{iss}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$			4.4		nF
$Q_{Gon}$	$V_{CE} = 900 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 30 \text{ A}$			600		nC
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{off}$ $E_{on}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 900 \text{ V}; I_C = 30 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 27 \Omega$			165		ns
				40		ns
				700		ns
				400		ns
				7		mJ
				6		mJ
<b>RBSOA</b>	$I_C = I_{CM}; V_{GE} = 15 \text{ V}$ $R_G = 27 \Omega; T_{VJ} = 125^\circ\text{C}$	$V_{CEK} \leq V_{CES} - L_S \frac{di}{dt}$			V	
$t_{sc}$ <b>(SCSOA)</b>	$V_{CE} = 900 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 45 \Omega$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^\circ\text{C}$			10		$\mu\text{s}$
$R_{thJC}$				0.62	K/W	

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1700	V	
$I_{F25}$	$T_C = 25^\circ\text{C}$	30	A	
$I_{F80}$	$T_C = 80^\circ\text{C}$	21	A	

**Symbol Conditions Characteristic Values**

			min.	typ.	max.	
$V_F$	$I_F = 30 \text{ A}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$			2.5	3.3	V
				2.6		V
$I_R$	$V_R = V_{RRM}; T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$				0.05	mA
				0.2		mA
$I_{RM}$ $t_{rr}$	$I_F = 30 \text{ A}; di_F/dt = -800 \text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}$ $V_R = 900 \text{ V}$			35		A
				700		ns
$R_{thJC}$	(per diode)			0.9	K/W	

## Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^\circ\text{C}$	4.75	5.0	5.25
$B_{25/50}$			3375	$\text{k}\Omega$ K

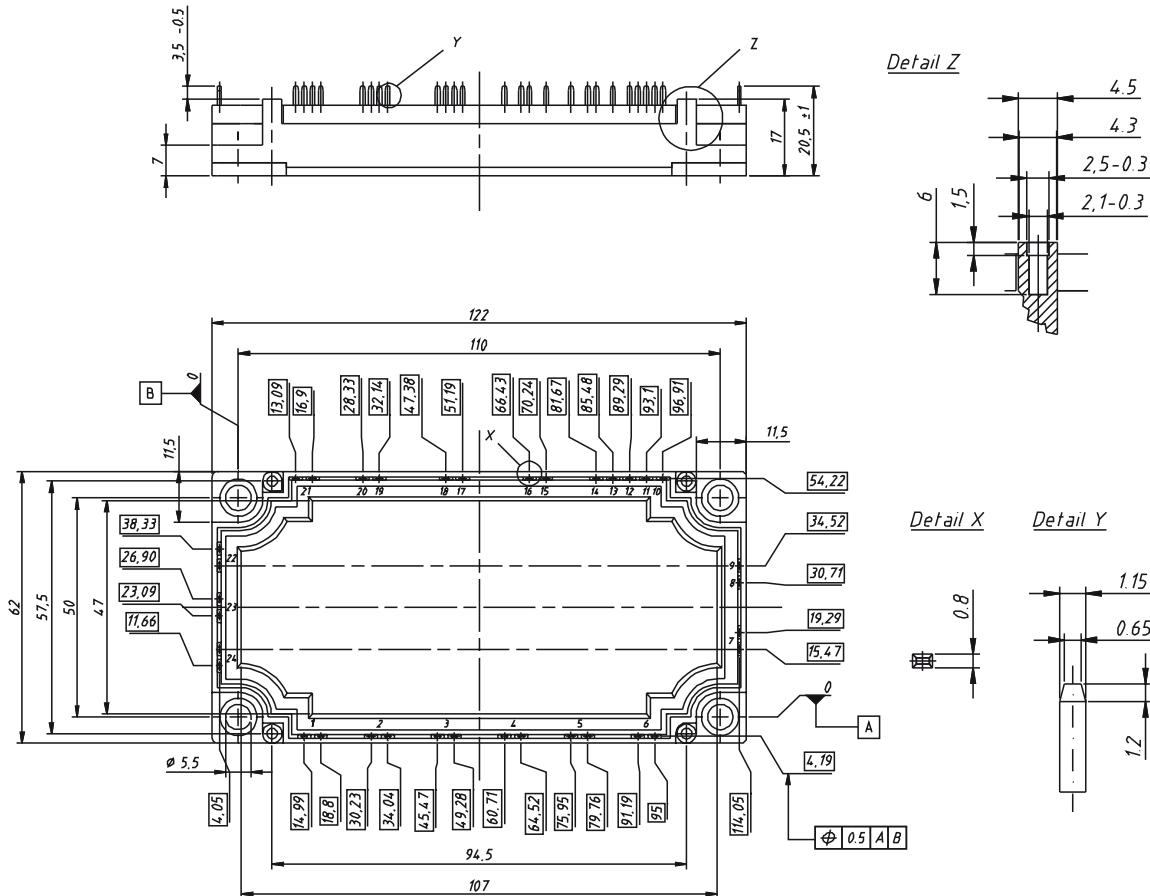
## Module

Symbol	Conditions	Maximum Ratings		
$T_{VJ}$	operating	-40...+125	$^\circ\text{C}$	
$T_{JM}$		+150	$^\circ\text{C}$	
$T_{stg}$		-40...+125	$^\circ\text{C}$	
$V_{ISO}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}; 1 \text{ min.}$	3400	V~	
$M_d$	Mounting torque (M5)	3 - 6	Nm	

## Symbol Conditions

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{therm-chip}$	Resistance terminal to chip		7	$\text{m}\Omega$
$d_s$	Creepage distance on surface	12.7		mm
$d_A$	Strike distance in air	9.6		mm
$R_{thCH}$	with heatsink compound		0.02	K/W
Weight		300		g

Dimensions in mm (1 mm = 0.0394")



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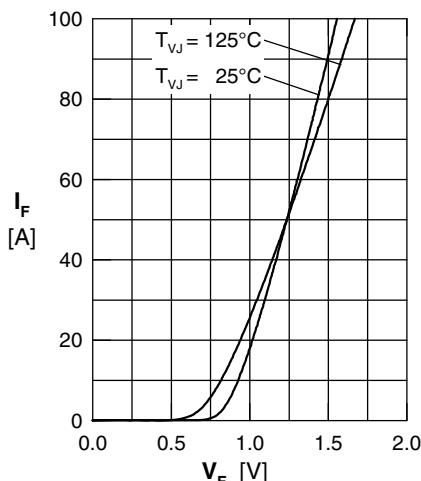
**Input Rectifier Bridge D11 - D16**


Fig. 1 Typ. forward current vs. voltage drop per diode

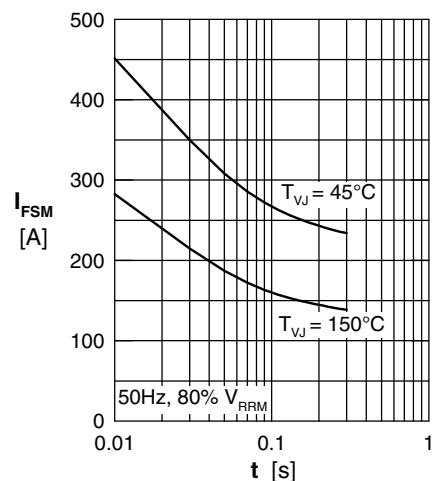


Fig. 2 Surge overload current

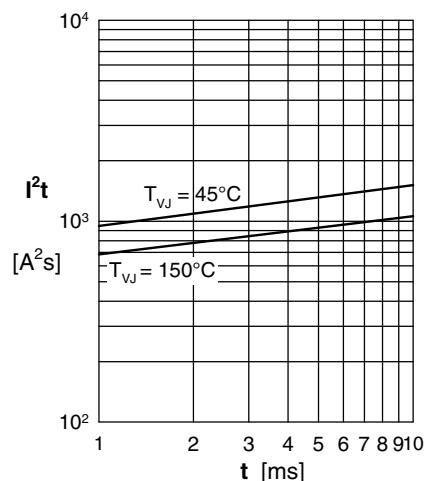


Fig. 3  $I^2t$  versus time per diode

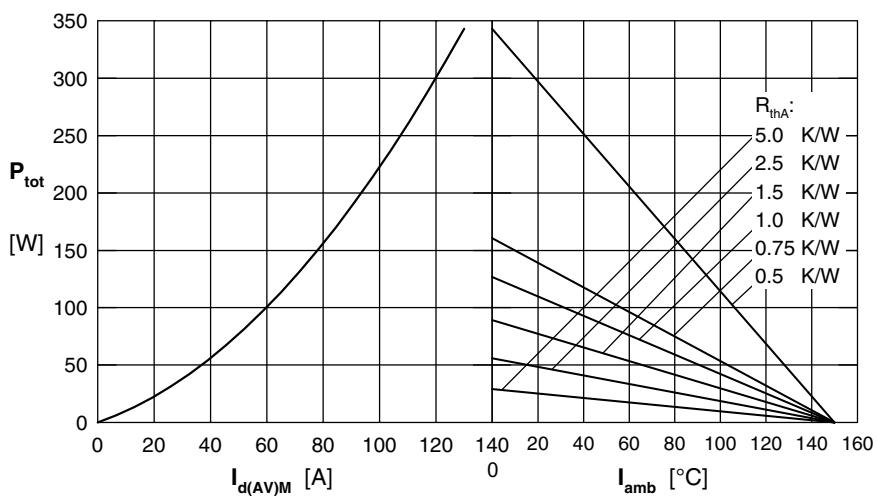


Fig. 4 Power dissipation versus direct output current & ambient temperature, sin 180°

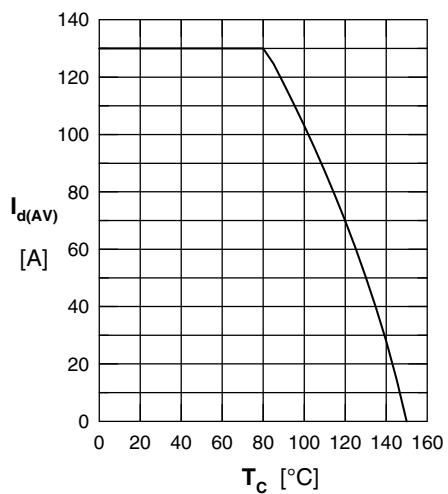


Fig. 5 Max. forward current vs. case temperature

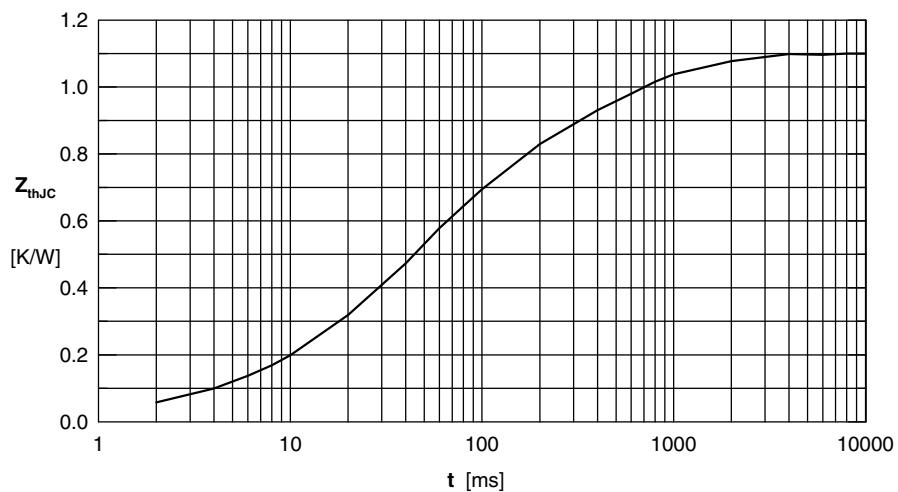
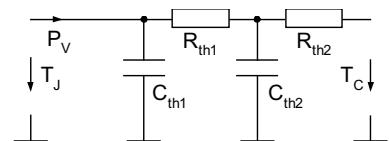


Fig. 6 Transient thermal impedance junction to case



	$R_i$	$\tau_i$
1	0.06	0.0085
2	0.024	0.001
3	0.586	0.045
4	0.114	0.85
5	0.317	0.35

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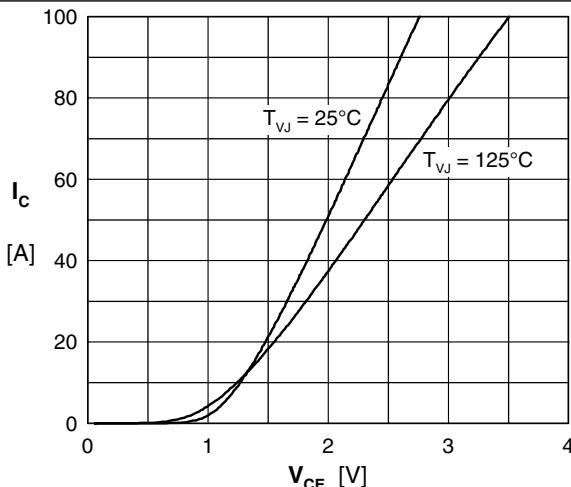
**Output Inverter T1 - T6 / D1 - D6**


Fig. 7 Typical output characteristic

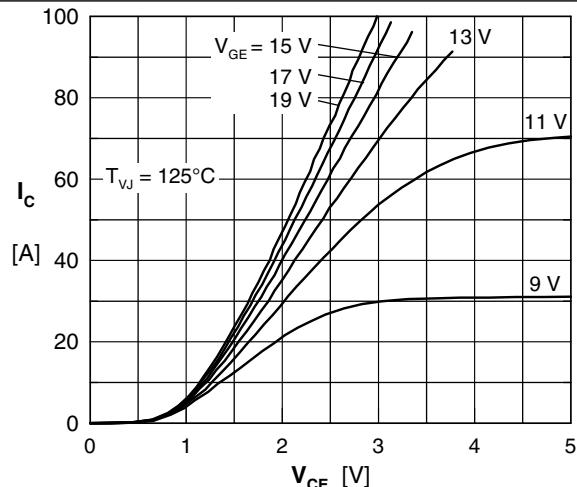


Fig. 8 Typical output characteristic

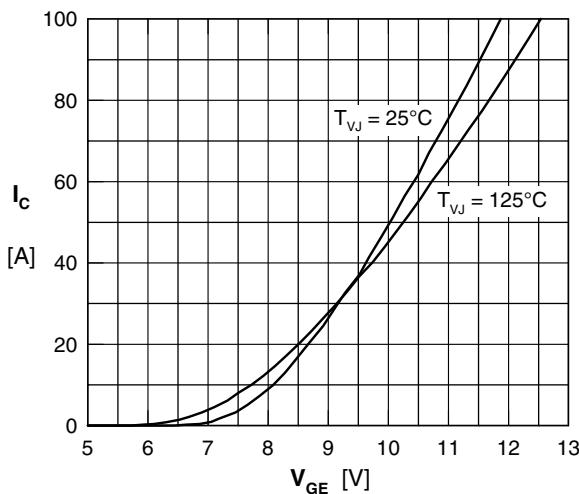


Fig. 9 Typical transfer characteristic

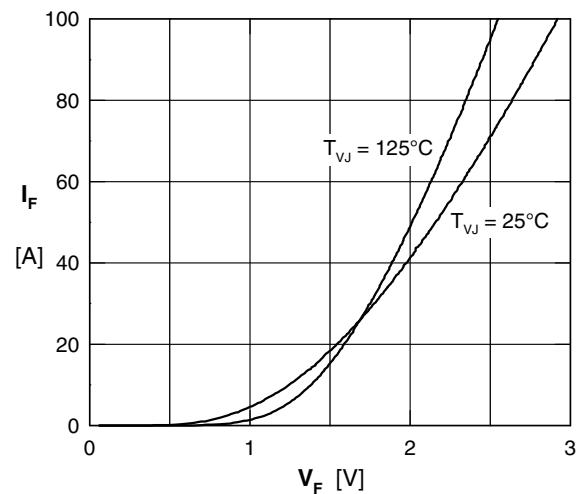


Fig. 10 Typical forward characteristic of free wheeling diode

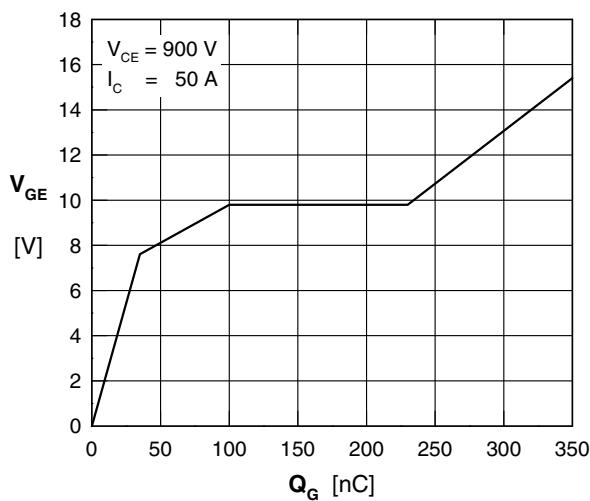


Fig. 11 Typical turn on gate charge

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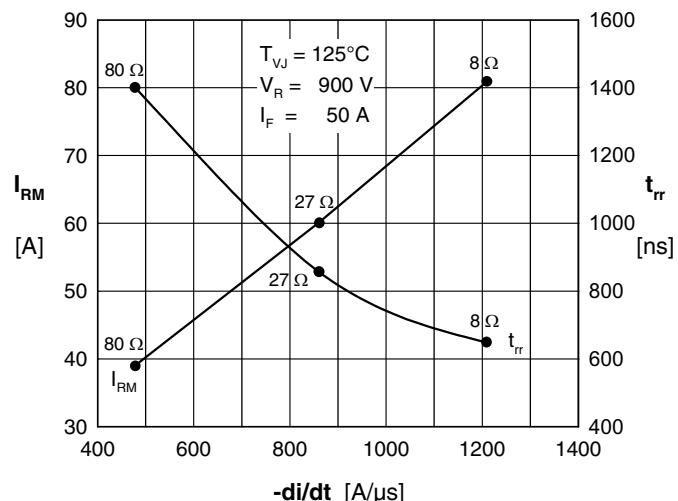


Fig. 12 Typ. turn-off characteristics of free wheeling diode

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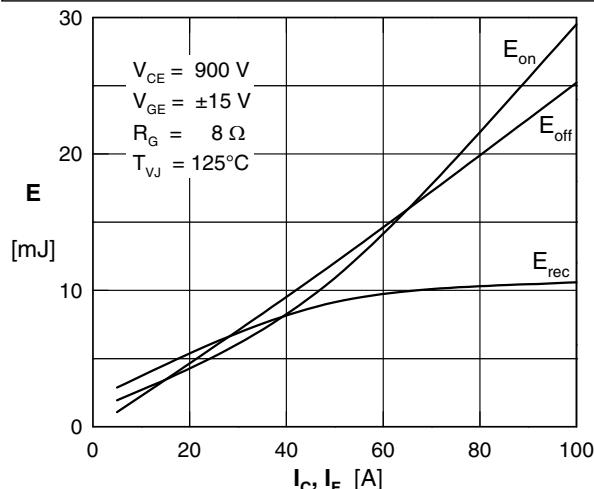
**Output Inverter T1 - T6 / D1 - D6**


Fig. 13 Typ. turn on energy & switching times  
versus collector current

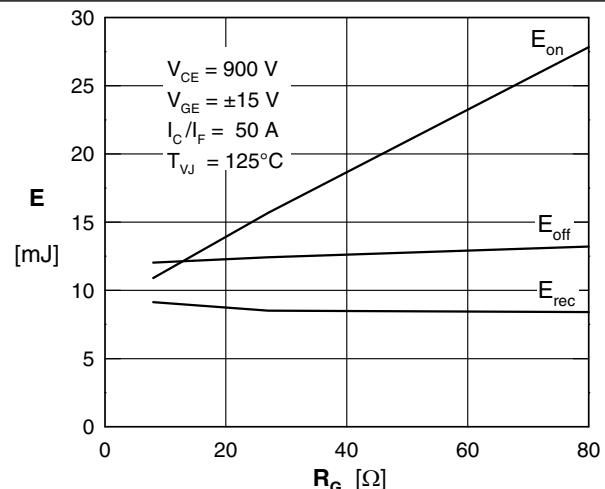


Fig. 14 Typ. turn off energy and switching times  
versus collector current

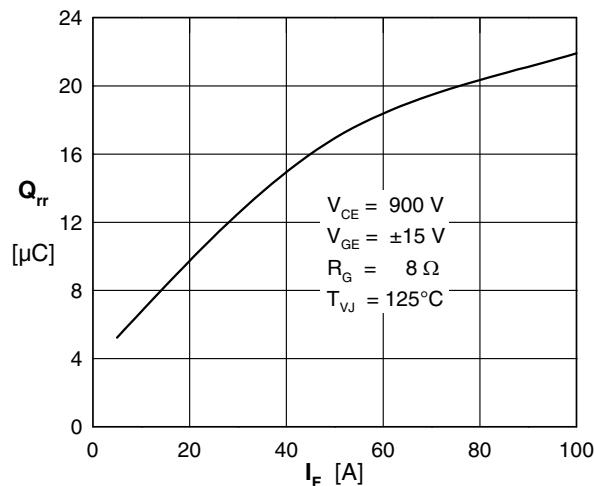


Fig. 15 Typical turn-off characteristics  
of free wheeling diode

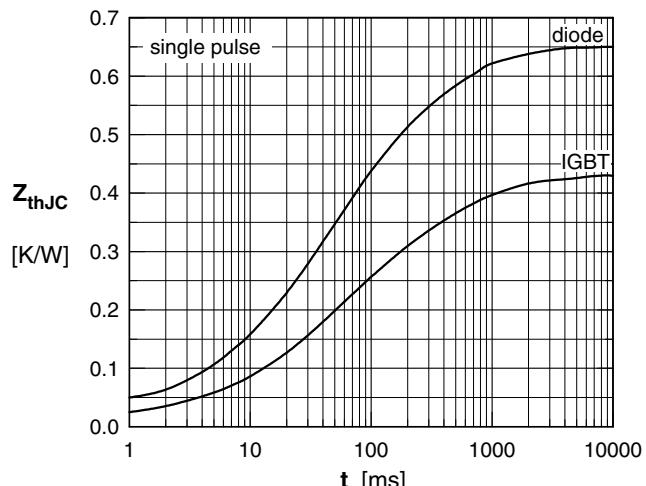


Fig. 16 Transient thermal impedance  
junction to case

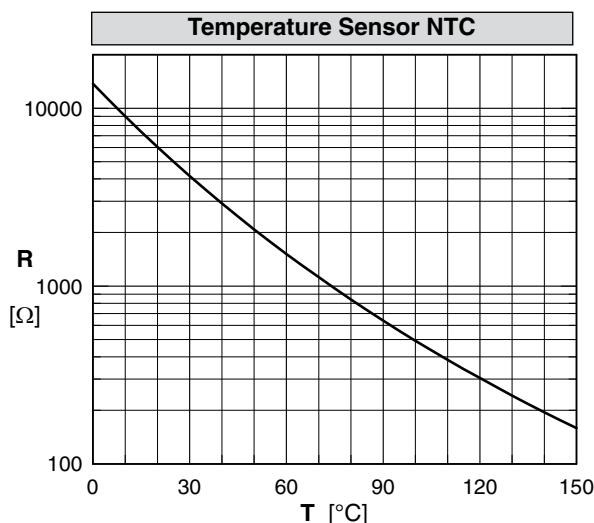
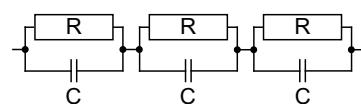


Fig. 17 Typ. NTC resistance vs. temperature

IGBT		Diode		
	$R_i$	$\tau_i$	$R_i$	$\tau_i$
1	0.0326	0.0014	0.1941	0.0206
2	0.1311	0.0258	0.0542	0.0016
3	0.1492	0.1099	0.2549	0.0930
4	0.1169	0.6361	0.1461	0.5958



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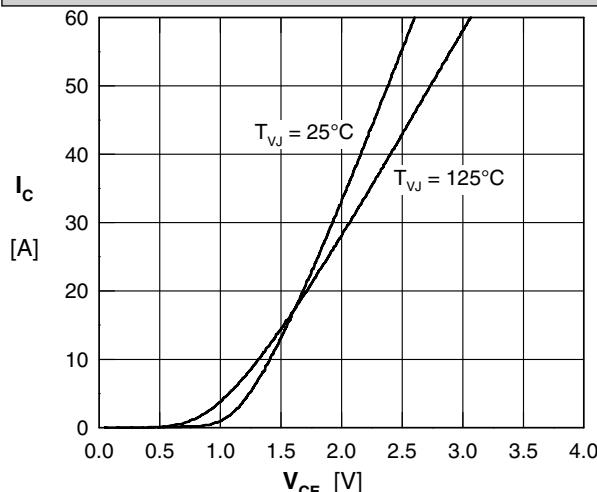
**Brake Chopper T7 / D7**


Fig. 18 Typical output characteristic

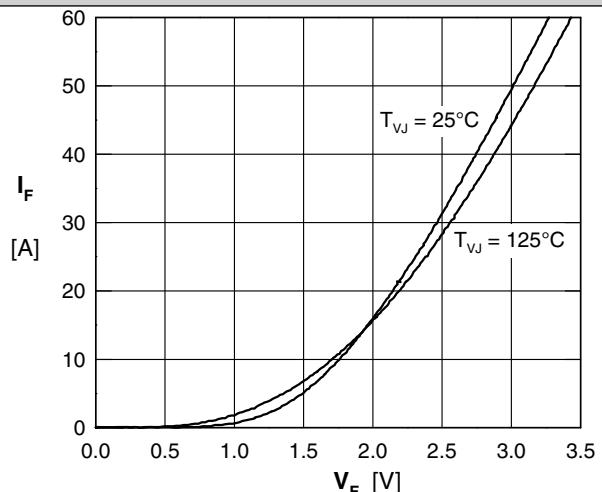


Fig. 19 Typ. forward characteristics of brake diode

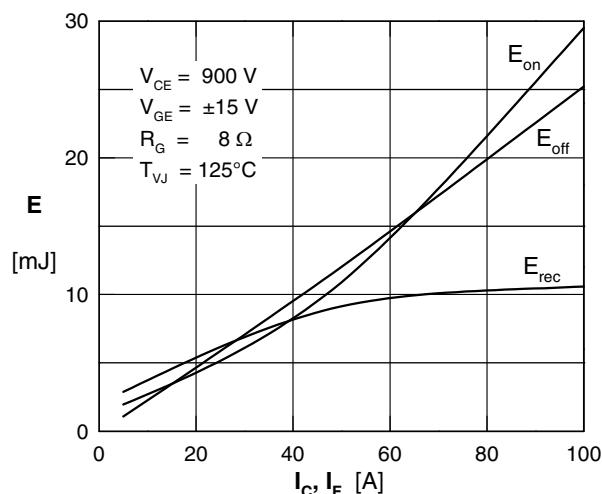


Fig. 20 Typ. turn on energy &amp; switching times versus collector current

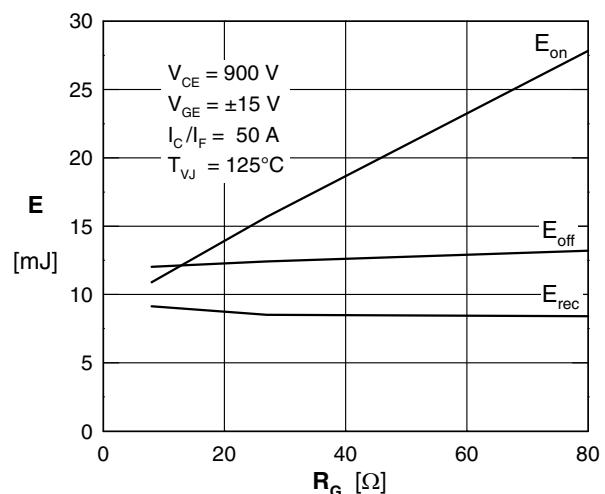


Fig. 21 Typ. turn off energy and switching times versus collector current

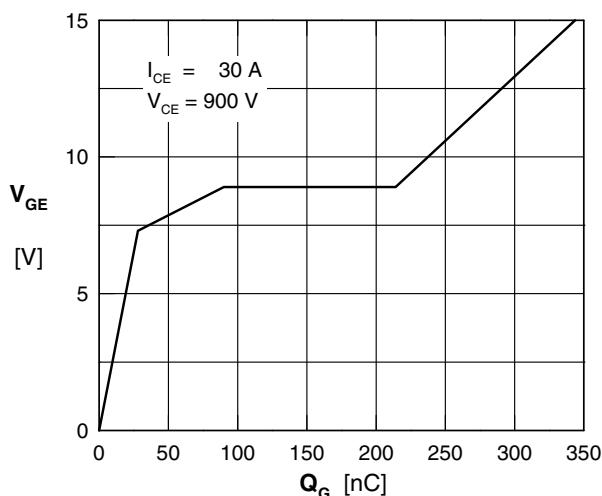


Fig. 22 Typ. turn on gate charge

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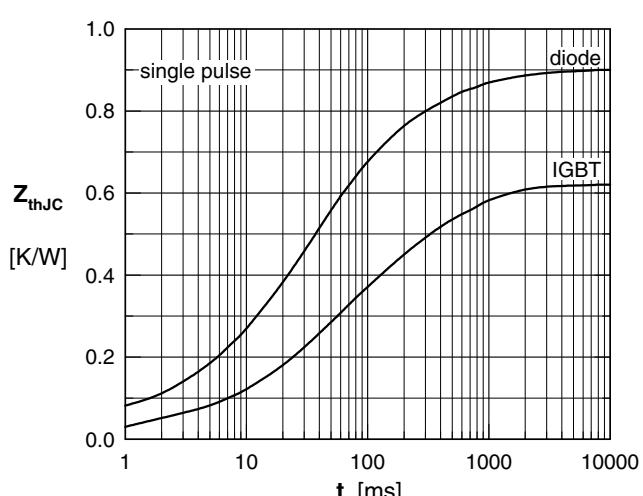


Fig. 23 Transient thermal impedance junction to case

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