



# 5.5" HDMI OLED-Display with Capacitive Touchscreen V1.0 SKU:DFR0524

This is a 5.5" HDMI OLED-Display with Capacitive Touchscreen. It has 1920×1080 HDMI highdefinition output and comes with a capacitive touch panel on its screen. The touch panel supports multi-touch which can simultaneously identify 5 touch points at most. Besides, the USB touchscreen adopts DFRobot driver-free technology. So without the special requirement of installing drivers, the touchscreen can be used as easy as a keyboard or a mouse. It can be directly plugged into a computer for touching control, which is able to replace the mouse. In combination with an HDMI display screen, the display device turns into a tablet PC in seconds!

The screen supports three mainstream operating system: Windows, Linux, and MACOS. It can work with Lattepanda, Raspberry Pi and other devices with HDMI output, which can truly be totally compatible with all platforms. The design of the special hole on the back of the screen is convenient for the direct installation of the product in Raspberry PI's controller. There is no need to provide an external power supply for the screen as it can be powered by USB port. In addition, the display supports hardware backlight adjustment. The function can be easily realized by turning the potentiometer on the back of the display.



NOTE: Please guarantee the external power supply current is above 1.5A@5V when it is driven by raspberry Pi.

The lower current will darken the screen and reduce the touching sensitivity.

## **Features**

- Capacitive Touchscreen, Support 5 Touch Points
- HDMI Interface
- USB Power Supply, Driver-free Installation

## **Specification**

- Operating Voltage: 5V
- Operating Current: 700mA
- Refresh Frequency: 60Hz
- Screen Resolution: 1920 x 1080
- Viewing Angle: 160°
- Video Interface: MINI-HDMI
- Touch Interface: Micro-USB
- Dimension: 130mm x 71mm
- Mounting Hole Size: M2.5
- Outside Mounting Hole Position: 123mm x 64mm
- Inside Mounting Hole Position: 58mm x 49mm
- Weight :150g

## **Board Overview**



The back of the 5.5" touchscreen

- 1. Standard MINI-HDMI
- 2. Standard Micro USB(Touch&Power Supply)

# **Tutorial**

The screen supports Windows, Linux and MACOS. You can configure the output resolution through setup on Windows and MAC, and through command on Linux.

### **Touchscreen with Raspberry Pi**

You need to reset resolution to avoid touch deviation caused by resolution difference between Raspberry Pi and the Touchscreen when you use 5.5" FHD touchscreen. (The lower current will affect the touching sensitivity.)

#### • Screen display resolution configuration

In the terminal, enter /boot/config.txt, add the following code to the end:

```
hdmi_ignore_edid=0xa5000080
config_hdmi_boost=4
#hdmi_timings=1080 0 1 2 2 1920 0 32 2 28 0 0 0 48 0 99532800 3
hdmi_cvt=1080 1920 48 3 0 0 0
hdmi_driver=2
hdmi_group=2
hdmi_mode=87
max_framebuffer_width=1080
max_framebuffer_height=1920
display_rotate=1
```

display\_rotate=0, 1, 2, 3 (represent to rotate the screen 0°, 90°, 180°, 270° respectively)

#### Touchscreen Configuration

Download **DFRobot\_RaspberryPi\_TouchScreen\_Firmware** to the host, default to the file **Downloads**. Press **Ctrl+Alt+T** simultaneously to open the terminal as shown below:

P → → ☆ A /home/pi/( pi × Downloads ×	oom iloads	
Directory Tree Directory Tree Direct	DFRobot_R aspberryPi_ TouchScre_	
File Edit Tabs Help pi@raspberrypi:~/Downloads \$ 1s DFRobot_RaspberryPi_TouchScreen_Fire pi@raspberrypi:~/Downloads \$ ]	pi@raspberrypi:~/Downloads ware-master.zip	- • ×

Enter/home/pi/Downloads, then input the command unzip DFRobot\_RaspberryPi\_TouchScreen\_Firmware-master.zip to extract the file as shown below:



Enter the folder **DFRobot\_RaspberryPi\_TouchScreen\_Firmware-master/5.5 HDMI\_DISPLAY**, then input **sudo python touch\_rotate.py** and the value of **display-rotate** in **config.txt**. Now you just need to wait for the restart of the Raspberry Pi.

## **Firmware Update**

#### The firmware update method of 5.5" FHD touchscreen is same as 7" touchscreen.

**Dfu-util** (Device Firmware Upgrade Utilities) is a free, open-source, cross-platform firmware update program. Without platform limitations, it is easy to update firmware for devices with microcontrollers.

Please check the official web: http://dfu-util.sourceforge.net for more details.

### **In Windows**

- 1. Download USB driver installation tools zadig.exe
- Address:http://zadig.akeo.ie/downloads/zadig\_2.2.exe
  - 2. Enter dfu mode

Short-circuit the boot's two pins, and then connect it to the computer via USB (Short-circuit first and connect).



3. Install winUSB driver in Zadig

		List All Devices	11
	~	Ignore Hubs or Composite Parents	- Edi
Driver	✓ ✓	Create a Catalog File Sign Catalog & Install Autogenerated Certificate	More Information WinUSB (libusb-1.0)
USB ID		Advanced Mode Log Verbosity	libusb-win32 libusbK WinUSB (Microsoft)

evice	Options Help	2
STM32	)FU	T Edi
Driver	WinUSB (v6. 1. 200. 163 5)	600.16385) More Information WinUSB (ibusb-1.0)
USB ID		libusb-win32
	× 4 Reinstall Dr	river libusbK WinUSB (Microsoft)

- Click Options, select List All Devices (1)
- Select "STM32 DFU" in the drop-down box (2)
- Select "WinUSB" in Driver (3)
- Click Install Driver (4)

Click continue to install if a dialog box pops-up.

• When it fails to install winUSB driver with zadig , the following interface will appear, which prompts that the file msvcr100d.dll is missing. (Win10 systems already has the file msvcr100d.dll and won't report errors)

river WinUSB (v6.1.76	The installation process can take up to 5 minutes	
SB ID 0483 DF11		More Information WinUSB (libusb-1.0) libusb-win32
CID <sup>2</sup> installer_x64.	exe - 系统错误	
	法启动此程序,因为计算机中丢失 MSVCR100D.d 程序以解决此问题。	III。尝试重新安装

• Win7(32 bit/64 bit)

Download **msvcr100d.dll**, place it in the C:\Windows\System32 directory, and re-install the driver, then it won't report errors.

https://github.com/DFRobot/binaryfiles/blob/master/DFR0506/32bits/msvcr100d.dll

- Win8
- 32 bit

Download **msvcr100d.dll**, place it in the C:\Windows\System32 directory, and re-install the driver, then it won't report errors.

https://github.com/DFRobot/binaryfiles/blob/master/DFR0506/32bits/msvcr100d.dll

• 64 bit

Download **msvcr100d.dll**, place it in the same level directory of zadig.exe.(if you place it in the C:\Windows\System32 directory, there will be a new error report.) https://github.com/DFRobot/binaryfiles/blob/master/DFR0506/32bits/msvcr100d.dll

🛃 zadig.exe	2012/5/30 18:12	应用程序	6,203 KB
🚳 msvcr100d.dll	2010/3/18 9:36	应用程序扩展	1,816 KB

#### 4. Download dfu-uti tool

- Click to download dfu-util for 32bit https://github.com/DFRobot/binaryfiles/raw/master/DFR0506/dfu-util-0.6.rar
- Click to download dfu-util for 64bit
   https://github.com/DFRobot/binaryfiles/raw/master/DFR0506/dfu-util-0.9-win64.zip

5. Unzip the file to you computer, such as "desktop>dfu-util-0.9-win64", and uyos can ue it directly without installation.

6. **Click to download** files for a firmware update, then unzip the file and copy the xxxx.dfu, erase.bin, upload.py in the /5.5"HMDI\_DISPLY/windows directory to the directory "desktop>dfu-util-0.9-win64".

https://codeload.github.com/DFRobot/DFRobot\_RaspberryPi\_TouchScreen\_Firmware/zip/m aster

7. Run upload.py (Windows needs to install python firstly.**Click to download python**) https://www.python.org/downloads/release/python-2714/

8. The following interface indicates that the program is being burned. The progress is finished when the progress bar goes to 100%.



9. After the burning is finished, re-plug USB device.

### In Linux

1. Enter dfu mode

Short-circuit the boot's two pins, and then connect it to the computer via USB (Short-circuit first and connect).



2. Use apt-get to install dfu-util

apt-get install dfu-util

3. Upgrade firmware through upload.py(root privileges are required)

4. Click to download files for firmware update.

https://codeload.github.com/DFRobot/DFRobot\_RaspberryPi\_TouchScreen\_Firmware/zip/m aster

- Open the terminal to enter the newly downloaded firmware directory DFRobot\_RaspberryPi\_TouchScreen\_Firmware/5.5"HMDI\_DISPLY/linux
- Use the command: sudo python upload.py to run the program
  - 5. Re-plug USB device

#### In Mac

1. Enter dfu mode

Short-circuit the boot's two pins, and then connect it to the computer via USB (Short-circuit first and connect).



- 2. Open the command terminal
- Open launcpad



• Search for "terminal" on the top of the screen.



• Open the terminal

00	☆ jfwl — bash — 80×24	R.
Last login: Wed May	6 08:33:18 on console	1
jfwldeMac-mini:~ jf	wis	
-bash: : co	mmand not found	
jfwldeMac-mini:~ jf	w15	
-bash: : col		
jfwldeMac-mini:~ jf	w15	
-bash: : comm		
jfwldeMac-mini:~ jfr	w15	
-bash: : comm	and not found	
jfwldeMac-mini:~ jfr	wis .	
-bash: . : command	not found	
jfwldeMac-mini:~ jf	wis .	
-bash: . : command		
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-bash: . : command		
jfwldeMac-mini:~ jf		

3. Install dfu-util

• brew install dfu-util

4. Use upload.py for firmware upgrade (root privileges are required.)

- 5. <u>Click to download</u> files for a firmware update.
- Open the terminal to enter the newly downloaded directory DFRobot\_RaspberryPi\_TouchScreen\_Firmware/5.5"HMDI\_DISPLY/linux
- Use the command: sudo python upload.py to run the program.

6. Re-plug USB device

## **Dimension Diagram**



5.5" Touchscreen's dimensional drawing

 $https://www.dfrobot.com/wiki/index.php/5.5\%22\_HDMI\_OLEDDisplay\_with\_Capacitive\_Touchscreen\_V1.0\_SKU:DFR0524\ 9-11-18$