## **MAGNETIC FIELD SENSOR**

### **DESCRIPTION**

The ZMY20 is an extremely sensitive magnetic sensor employing the magneto-resistive effect of thin film permalloy. It allows the measurement of magnetic fields or the detection of magnetic parts. The highly sensitive and small size magnetoresistive sensors consist of a chip covered with thin film permalloy stripes. These stripes form a Wheatstone bridge, whose output voltage is proportional to the magnetic field component Hy. A perpendicular field Hx is necessary to stabilize sensor operation. This can be done by using a small permanent magnet.

# **FEATURES**

- · Output voltage proportional to magnetic field Hy
- Adjustment of sensitivity and suppression of hysteresis by the auxiliary magnetic field Hx
- Magnetic fields vertical to the chip level are not effective

## **APPLICATIONS**

- Linear position sensors for process control, door interlocks, proximity detectors, machine tool sensing
- Scalar measurement for compassing
- Automotive door switches, engine position & speed sensing
- · Metering of fluids by sensing rotation of impeller
- Traffic counting & vehicle-type sensing

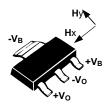
## **ORDERING INFORMATION**

DEVICE	REEL SIZE	TAPE WIDTH	QUANTITY PER REEL
ZMY20TA	7″	12mm	1000 units
ZMY20TC	13"	12mm	4000 units

Measurement of current in a conductor without connection

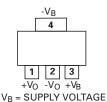
## **DEVICE MARKING**

ZMY20



**SOT223S** 

## **PINOUT**



V<sub>O</sub> = OUTPUT VOLTAGE

Top View



# **ABSOLUTE MAXIMUM RATINGS.**

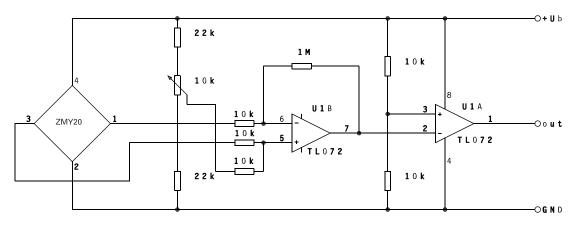
PARAMETER	SYMBOL	LIMIT	UNIT
Supply Voltage	V <sub>B</sub>	12	V
Total power dissipation	P <sub>TOT</sub>	120	mW
Operating Temperature Range	T <sub>amb</sub>	-40 to +150	°C
Storage Temperature Range	T <sub>stg</sub>	-65 to +150	°C

# ELECTRICAL CHARACTERISTICS.(at $T_{amb}$ =25°C and $H_X$ =3 kA/m unless otherwise stated)

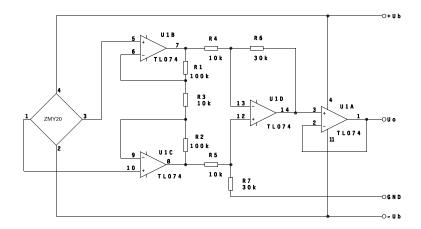
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNIT	TEST CONDITIONS
Bridge resistance	R <sub>br</sub>	1.2	1.7	2.2	kΩ	
Output voltage range	V <sub>O</sub> /V <sub>B</sub>	16	20	24	mV/V	
Open circuit sensitivity	S	3.7	4.7	5.7	(mV/V)/ (kA/m)	No disturbing field H <sub>d</sub> allowed
Hysteresis of output voltage	V <sub>OH</sub> /V <sub>B</sub>	-	-	50	μV/V	Hy≤ 2kA/m
Offset Voltage	V <sub>off</sub> /V <sub>B</sub>	-1.0	-	+1.0	mV/V	
Operating Frequency	f <sub>max</sub>	0	-	1	MHz	
Temp. Coeff. of offset voltage	TCV <sub>off</sub>	-3	-	+3	(µV/V)/K	T <sub>amb</sub> = -25 to +125°C
Temp. Coeff. Of bridge resistance	TCR <sub>br</sub>	0.25	0.3	0.35	%/K	T <sub>amb</sub> = -25 to +125°C
Temp. Coeff. of open circuit sensitivity V <sub>B</sub> =5V	TCS <sub>V</sub>	-0.25	-0.3	-0.35	%/K	T <sub>amb</sub> = -25 to +125°C
Temp. Coeff. of open circuit sensitivity I <sub>B</sub> =3mA	TCS <sub>I</sub>	-	-0.1	-	%/K	T <sub>amb</sub> = -25 to +125°C



# Application 1 (digital output)

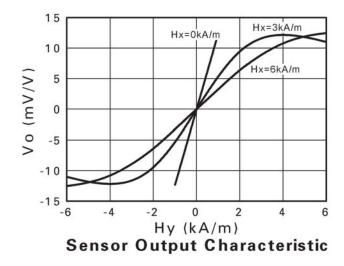


# Application 2 (analog output)

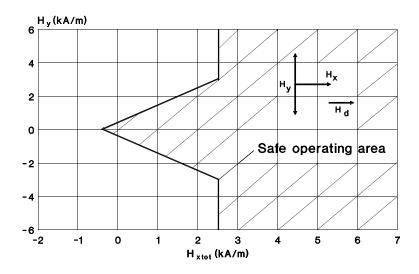




Sensor output characteristic  $V_{O}=f(H_{y})$ ;  $H_{x}$ -parameter  $V_{b}$ =const;  $T_{amb}$ =25°C



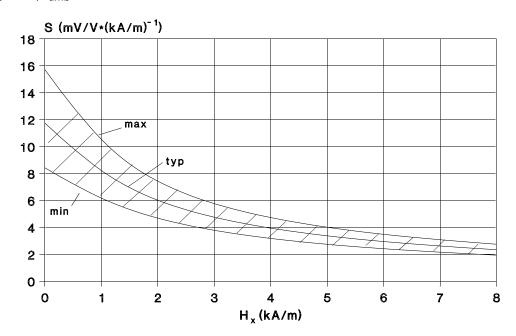
Safe operating area  $H_{xtot}=H_x+H_d$ ;  $T_{amb}=25^{\circ}C$ ; ( $H_d=disturbing\ field$ )



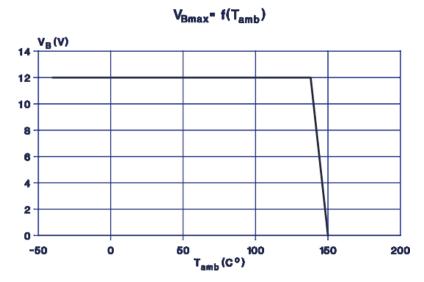
The sensor has to be reset after leaving the safe operating area by an auxiliary field of H<sub>X</sub>=3kA/m



Sensor sensitivity characteristic  $S=f(H_X)$  $V_b=const; T_{amb}=25^{\circ}C$ 



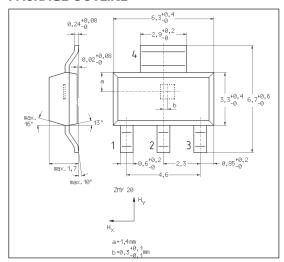
Supply voltage (maximum) derating curve  $VBmax = f(T_{amb})$ 



Device mounted on 40 x 40 mm<sup>2</sup> board (copper area 600mm<sup>2</sup>)



# **PACKAGE OUTLINE**



CONTROLLING DIMENSIONS IN MILLIMETRES APPROX CONVERSIONS INCHES.



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