

**Data Sheet** 

# ADAU1861

# Three ADCs, One DAC, Low Power Codec with Audio DSPs

#### **FEATURES**

- Programmable FastDSP audio processing engine
  - Up to 768 kHz sample rate
  - Biquad filters, limiters, volume controls, mixing
- ► Tensilica HiFi 3z DSP core
  - Quad MAC per cycle: 24 × 24-bit multiplier and 64-bit accumulator
  - Flexible power operation mode: 24.576 MHz, 49.152 MHz, 73.728 MHz, and 98.304 MHz
  - 336 kB total memory
  - ▶ JTAG debug and trace
- ▶ Low latency, 24-bit ADCs, and DAC
  - 106 dB SNR (signal through ADC with A-weighted filter)
  - 110 dB combined SNR (signal through DAC and headphone with A-weighted filter)
- Programmable double precision MAC engine for maximum 24stage equalizer
- ▶ Serial-port sample rates from 8 kHz to 768 kHz
- ▶ 5 µs group delay (f<sub>S</sub> = 768 kHz) analog in to analog out with FastDSP bypass (zero instructions)
- 3 differential or single-ended analog inputs, configurable as microphone or line inputs
- ▶ 8 digital microphone inputs
- Analog differential audio output, configurable as either line output or headphone driver
- 2 PDM output channels
- ▶ PLL supporting any input clock rate from 30 kHz to 36 MHz
- ▶ 4 channel asynchronous sample rate converters (ASRCs)
- ▶ 2, 16-channel serial audio ports supporting I<sup>2</sup>S, left-justified, right-justified, or up to TDM16 (TDM12 in turbo mode)
- ▶ 8 interpolators and 8 decimators with flexible routing
- Power supplies
  - ► Analog AVDD at 1.8 V typical
  - ▶ Digital I/O IOVDD at 1.1 V to 1.98 V
  - ▶ Digital DVDD at 0.85 V to 1.21 V
  - ▶ Headphone HPVDD L at 1.2 V to AVDD
- ► Control/communication interfaces
  - ▶ I<sup>2</sup>C, SPI, or UART control ports
  - Main quad SPI (QSPI)
  - ► UART communication port
- Self-boot from QSPI flash
- ▶ Flexible GPIO and IRQ
- 64-lead lead frame chip scale package [LFCSP], 9 mm × 9 mm and 0.85 mm package height

#### Rev. 0

#### DOCUMENT FEEDBACK

#### TECHNICAL SUPPORT

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#### APPLICATIONS

- Automotive audio systems
- Digital audio effects processors

#### **GENERAL DESCRIPTION**

The ADAU1861 is a codec with three inputs and one output that incorporates two digital-signal processors (DSPs). The path from the analog input to the DSP core to the analog output is optimized for low latency.

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#### FUNCTIONAL BLOCK DIAGRAM



Figure 1. Functional Block Diagram

Main clock = 24.576 MHz, Hibernate 1 mode, serial input sample rate = 48 kHz, measurement bandwidth = 20 Hz to 20 kHz, word width = 24 bits, ambient temperature =  $25^{\circ}$ C, and outputs line loaded with 10 k $\Omega$ , unless otherwise noted.

#### ANALOG PERFORMANCE SPECIFICATIONS

Supply voltages: AVDD = IOVDD = 1.8 V, and DVDD = 0.9 V, unless otherwise noted.

#### Table 1. Analog Performance Specifications

Parameter	Test Conditions/Comments	Min	Тур	Мах	Unit
ANALOG-TO-DIGITAL CONVERTERS (ADCs)					
ADC Resolution	All ADCs		24		Bits
Digital Gain Step			0.375		dB
Digital Gain Range		-71.25		+24	dB
NPUT RESISTANCE (R <sub>IN</sub> )					
Single-Ended Line Input	Nonvoice wake-up mode		9		kΩ
	Voice wake-up mode		18		kΩ
Differential Line Input	Nonvoice wake-up mode		36		kΩ
	Voice wake-up mode		36		kΩ
Programmable-Gain Amplifier (PGA) Single-Ended Inputs	PGA high R <sub>IN</sub> , normal, 0 dB gain		20.6		kΩ
	PGA high R <sub>IN</sub> , normal, 24 dB gain		2.4		kΩ
	PGA low R <sub>IN</sub> , enhanced, 0 dB gain		10.3		kΩ
	PGA low R <sub>IN</sub> , enhanced, 24 dB gain		1.2		kΩ
	PGA high R <sub>IN</sub> , enhanced, 0 dB gain		20.6		kΩ
	PGA high R <sub>IN</sub> , enhanced, 24 dB gain		2.4		kΩ
PGA Differential Inputs	PGA high R <sub>IN</sub> , normal, 0 dB gain		41.2		kΩ
	PGA high R <sub>IN</sub> , normal, 24 dB gain		4.8		kΩ
	PGA low R <sub>IN</sub> , enhanced, 0 dB gain		20.6		kΩ
	PGA low R <sub>IN</sub> , enhanced, 24 dB gain		2.4		kΩ
	PGA high R <sub>IN</sub> , enhanced, 0 dB gain		41.2		kΩ
	PGA high R <sub>IN</sub> , enhanced, 24 dB gain		4.8		kΩ
SINGLE-ENDED LINE INPUT	PGAx_EN = 0 and PGAx_SLEW_DIS = 1				
Full-Scale Input Voltage	0 dBFS		0.49		V rms
	0 dBFS		1.39		V p-p
Dynamic Range <sup>1</sup>	20 Hz to 20 kHz, -60 dB input				
With A-Weighted Filter (RMS)	Enhanced performance		103		dB
	Normal performance		103		dB
	Power saving		102		dB
	Voice wake-up		99		dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		98		dB
	Normal performance		98		dB
	Power saving		98		dB
	Voice wake-up		96		dB
Signal-to-Noise Ratio (SNR) <sup>2</sup>					
With A-Weighted Filter (RMS)	Enhanced performance		102		dB
	Normal performance		102		dB
	Power saving		102		dB
	Voice wake-up		98		dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		98		dB
	Normal performance		98		dB
	Power saving		98		dB
	Voice wake-up		95		dB

#### Table 1. Analog Performance Specifications (Continued)

Parameter	Test Conditions/Comments	Min T	yp Max	Unit
Interchannel Gain Mismatch		4	0	mdB
Total Harmonic Distortion + Noise (THD + N)	20 Hz to 20 kHz, -1 dB full-scale output			
	Enhanced performance	-	-78	dBFS
	Normal performance	-	-78	dBFS
	Power saving	-	-78	dBFS
	Voice wake-up	-	-78	dBFS
Offset Error		±	0.3	mV
Gain Error		±	0.2	dB
Interchannel Isolation	CM capacitor = 1 µF	1	00	dB
Power-Supply Rejection Ratio (PSRR)	CM capacitor = 1 µF			
	100 mV p-p at 1 kHz	6	0	dB
	100 mV p-p at 10 kHz	4	0	dB
DIFFERENTIAL LINE INPUT	PGAx_EN = 0, PGAx_SLEW_DIS = 1			
Full-Scale Input Voltage	0 dBFS	0	.98	V rms
	0 dBFS	2	78	V р-р
Dynamic Range <sup>1</sup>	20 Hz to 20 kHz, -60 dB input			
With A-Weighted Filter (RMS)	Enhanced performance	1	06	dB
	Normal performance	1	06	dB
	Power saving	1	05	dB
	Voice wake-up	1	00	dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance	1	04	dB
	Normal performance	1	04	dB
	Power saving	1	03	dB
	Voice wake-up	g	8	dB
SNR <sup>2</sup>				
With A-Weighted Filter (RMS)	Enhanced performance	1	06	dB
	Normal performance	1	06	dB
	Power saving	1	04	dB
	Voice wake-up	9	9	dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance	1	03	dB
	Normal performance	1	03	dB
	Power saving	1	02	dB
	Voice wake-up	9	8	dB
Interchannel Gain Mismatch		4	.0	mdB
THD + N	20 Hz to 20 kHz, -1 dB full-scale output			
	Enhanced performance	-	95	dBFS
	Normal performance	-	95	dBFS
	Power saving	-	95	dBFS
	Voice wake-up	-	95	dBFS
Offset Error		±	0.2	mV
Gain Error		±	0.2	dB
Interchannel Isolation	CM capacitor = 1 µF	1	00	dB
PSRR	CM capacitor = 1 µF			
	100 mV p-p at 1 kHz	7	0	dB
	100 mV p-p at 10 kHz	7	0	dB
SINGLE-ENDED PGA INPUT	PGAx_EN = 1			
Full-Scale Input Voltage	0 dBFS	0	.49	V rms
	0 dBFS	1	.39	V р-р

## Table 1. Analog Performance Specifications (Continued)

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit	
Dynamic Range <sup>1</sup>	20 Hz to 20 kHz, -60 dB input					
With A-Weighted Filter (RMS)	Enhanced performance		100		dB	
5	Normal performance		100		dB	
	Power saving		99		dB	
	Voice wake-up		97		dB	
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		96		dB	
	Normal performance		96		dB	
	Power saving		96		dB	
	Voice wake-up		94		dB	
SNR <sup>2</sup>			01		<sup>ub</sup>	
With A-Weighted Filter (RMS)	Enhanced performance		100		dB	
	Normal performance		100		dB	
	Power saving		99		dB	
	Voice wake-up		99 97		dB	
					dВ	
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		96			
	Normal performance		96		dB	
	Power saving		96		dB	
	Voice wake-up		94		dB	
THD + N	20 Hz to 20 kHz, -1 dBFS				dBFS	
	Enhanced performance		-78			
	Normal performance		-78			
	Power saving		-78		dBFS	
	Voice wake-up		-78		dBFS	
PGA Gain Range		0		24	dB	
PGA Gain Variation						
With 0 dB Setting	Standard deviation		0.05		dB	
With 24 dB Setting	Standard deviation		0.15		dB	
Interchannel Gain Mismatch			40		mdB	
Offset Error			0.3		mV	
Gain Error			±0.2		dB	
Interchannel Isolation	CM capacitor = 1 µF		83		dB	
PSRR	CM capacitor = 1 µF					
	100 mV p-p at 1 kHz		70		dB	
	100 mV p-p at 10 kHz		50		dB	
IFFERENTIAL PGA INPUT	PGAx EN = 1					
Full-Scale Input Voltage	0 dBFS		0.98		V rm	
i di-oodie input voltage	0 dBFS		2.78		V p-p	
Dynamic Range <sup>1</sup>	20 Hz to 20 kHz, -60 dB input		2.10		V P-P	
With A-Weighted Filter (RMS)	Enhanced performance		103		dB	
With A-Weighted Filler (RWS)						
	Normal performance		103		dB	
	Power saving		103		dB	
	Voice wake-up		97		dB	
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		101		dB	
	Normal performance		101		dB	
	Power saving		100		dB	
	Voice wake-up		96		dB	
SNR <sup>2</sup>						
With A-Weighted Filter (RMS)	Enhanced performance		102		dB	
	Normal performance		102		dB	

#### Table 1. Analog Performance Specifications (Continued)

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
	Power saving		102		dB
	Voice wake-up		97		dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		100		dB
	Normal performance		100		dB
	Power saving		100		dB
	Voice wake-up		95		dB
THD + N	20 Hz to 20 kHz, -1 dBFS				
	Enhanced performance		-95		dBFS
	Normal performance		-95		dBFS
	Power saving		-95		dBFS
	Voice wake-up		-95		dBFS
PGA Gain Range		0		24	dB
PGA Gain Variation					
With 0 dB Setting	Standard deviation		0.05		dB
With 24 dB Setting	Standard deviation		0.15		dB
Interchannel Gain Mismatch			40		mdB
Offset Error			±0.2		mV
Gain Error			±0.2		dB
Interchannel Isolation	CM capacitor = 1 µF		100		dB
PSRR	$CM$ capacitor = 1 $\mu$ F		100		uD
	100 mV p-p at 1 kHz		70		dB
	100 mV p-p at 10 kHz		70		dB
DIGITAL-TO-ANALOG CONVERTERS (DACs)			10		
Internal Converter Resolution	All DACs		24		Bits
Digital Gain	All DACS		24		Dits
Step			0.375		dB
-		-71.25	0.375	+24	dB
Range		-/1.25	4 5	724	dB/m
Ramp Rate	Differential encertion		4.5		UD/III
	Differential operation		4.0		
Full-Scale Output Voltage	0 dBFS to DAC		1.0		V rms
Dynamic Range <sup>1</sup>	20 Hz to 20 kHz, -60 dB input				
With A-Weighted Filter (RMS)	Enhanced performance		110		dB
	Normal performance		106		dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		107		dB
	Normal performance		103		dB
SNR <sup>2</sup>	20 Hz to 20 kHz				
With A-Weighted Filter (RMS)	Enhanced performance		110		dB
	Normal performance		106		dB
With Flat 20 Hz to 20 kHz Filter	Enhanced performance		106		dB
	Normal performance		103		dB
Output Noise	20 Hz to 20 kHz				
With A-Weighted Filter (RMS)			3.15		μV
THD + N Level	Line out mode				
10 kΩ Load	-1 dBFS input, normal performance		-93		dBV
	Headphone mode				
32 Ω Load	-15 dBFS input, output power (P <sub>OUT</sub> ) = 1 mW, enhanced performance		-96		dBV
	-15 dBFS input, P <sub>OUT</sub> = 1 mW, normal performance		-85		dBV
	-1 dBFS input, enhanced performance		-82		dBV

Table 1. Analog Performance S	Specifications	(Continued)
Table 1. Analog I chornance	pecifications	(Continueu)

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
	-1 dBFS input, normal performance		-80		dBV
24 Ω Load	-2 dBFS input, enhanced performance		-82		dBV
	-2 dBFS input, normal performance		-80		dBV
16 Ω Load	-3 dBFS input, enhanced performance		-82		dBV
	-3 dBFS input, normal performance		-80		dBV
Headphone Output Power					
32 Ω Load	AVDD = 1.8 V, <0.1% THD + N		30		mW
24 Ω Load	AVDD = 1.8 V, <0.1% THD + N		40		mW
16 Ω Load	AVDD = 1.8 V, <0.1% THD + N		50		mW
Gain Error			±2.5		%
DC Offset			±0.1		mV
PSRR	CM capacitor = 1 µF				
AVDD	100 mV p-p at 1 kHz		85		dB
	100 mV p-p at 10 kHz		85		dB
HPVDD_L (Low-Dropout (LDO) Bypass)	100 mV p-p at 1 kHz		90		dB
	100 mV p-p at 10 kHz		90		dB
AVDD Undervoltage Trip Point			1.5		V
CM REFERENCE	CM pin				
Output			0.85		V
Source Impedance			5		kΩ
PHASED-LOCKED LOOP (PLL)					
Input Frequency	After input prescale	0.03		36	MHz
Output Frequency		24	49.152	100	MHz
Fractional Limits	Fractional mode, fraction part (numerator (N)/denominator (M))	0.1		0.9	
Integer Limits	Fractional mode, integer part	2		3072	
Lock Time	32 kHz input		6.5		ms
	24.576 MHz input		0.46	0.55	ms
REGULATOR					
Line Regulation			1		mV/V
Load Regulation			0.5		mV/m

<sup>1</sup> Dynamic range is the ratio of the sum of noise and harmonic power in the band of interest with a -60 dBFS signal present to the full-scale power level in decibels.

<sup>2</sup> SNR is the ratio of the sum of all noise power in the band of interest with no signal present to the full-scale power level in decibels.

#### **CRYSTAL AMPLIFIER SPECIFICATIONS**

Supply voltages: AVDD = IOVDD = 1.8 V, and DVDD = 0.9 V, unless otherwise noted.

Table 2.							
Parameter	Min	Тур	Max	Unit			
JITTER		270	500	ps			
FREQUENCY RANGE	1		36	MHz			
LOAD CAPACITANCE			20	pF			

#### DIGITAL INPUT AND OUTPUT SPECIFICATIONS

 $-40^{\circ}\text{C}$  < T\_A < +85^{\circ}\text{C}, and IOVDD = 1.1 V to 1.98 V, unless otherwise noted.

Table 3.

Parameter	Symbols	Test Conditions/Comments	Min	Тур	Max	Unit
INPUT VOLTAGE						
High	VIH		0.7 × IOVDD			V
Low	VIL				0.3 × IOVDD	V
	I <sub>IH</sub>	IOVDD = 1.8 V, input high current ( $I_{IH}$ ) at $V_{IH}$ = 1.1 V			10	μA
	I <sub>IL</sub>	Input low current ( $I_{IL}$ ) at $V_{IL}$ = 0.45 V			10	μA
OUTPUT VOLTAGE HIGH	V <sub>OH</sub>					
Drive Strength						
Low		Output high current (I <sub>OH</sub> ) = 1 mA	0.7 × IOVDD	0.83 × IOVDD		V
High		I <sub>OH</sub> = 3 mA	0.7 × IOVDD	0.83 × IOVDD		V
OUTPUT VOLTAGE LOW	V <sub>OL</sub>					
Drive Strength						
Low		Output low current (I <sub>OL</sub> ) = 1 mA		0.1 × IOVDD	0.3 × IOVDD	V
High		Output low current (I <sub>OL</sub> ) = 3 mA		0.1 × IOVDD	0.3 × IOVDD	V
INPUT CAPACITANCE					5	pF

### POWER SUPPLY SPECIFICATIONS

Supply voltages: AVDD = IOVDD = 1.8 V and DVDD = 0.9 V, unless otherwise noted. PLL disabled, direct main clock. Digital input/output (I/O) lines loaded with 25 pF.

#### Table 4. Power Supply Specifications

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
SUPPLIES					
AVDD Voltage		1.7	1.8	1.98	V
DVDD Voltage		0.85	0.9	1.21	V
IOVDD Voltage		1.1	1.8	1.98	V
HPVDD_L Voltage		1.2		AVDD	V

#### **POWER-DOWN CURRENT**

Supply voltages: AVDD = IOVDD = 1.8 V and DVDD = 0.9 V and was externally supplied. PLL and crystal oscillator was disabled and bypassed.

#### Table 5. Power-Down Current

		AVDD Cur	Current DVDD Current IOVDD Current				rrent	HPVDD_L Current					
Parameter	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Min	Тур	Мах	Unit
POWER-DOWN CURRENT													
PD Pin Low (Hardware Power Down)		6.6			56.9			2.6			3		μA
PWR_MODE = 00													
CM_KEEP_ALIVE = 0		11			258			21			3		μA
CM_KEEP_ALIVE = 1		588			258			21			3		μA

Table 6. Typical Power Consumption

#### **TYPICAL POWER CONSUMPTION**

PLL bypassed with a main clock = 24.576 MHz (external oscillator). DVDD = 0.9 V, and AVDD = IOVDD = 1.8 V was supplied externally. Where applicable, ADC0 and ADC1 were run at 192 kHz, and ADC2 was run at 48 kHz. FastDSP<sup>TM</sup> was run at 192 kHz (biquad filters with 27-bit precision), and Tensilica DSP was run at 48 kHz. DAC was run at 192 kHz, and DAC\_LPM = 0. One serial port input and output, configured as a subordinate, with a headphone load of 32  $\Omega$  was used. The DAC headphone amplifier (HPAMP) was in normal voltage mode. Quiescent current had no signal.

In Table 6, ASRCI and ASRCO are the input and output ports of the asynchronous sample rate converters, FIFO is first in, first out, DMIC is the digital microphone, and PDM is the pulse density modulation.

ADC + PGA Channels	DAC Channels	ASRCI/ ASRCO Channels	FIFO and SRAM2	FastDSP Instruction s	Equalizer Filters	DMIC/PDM Channels	Interpolator /Decimator Channels	AVDD Current (mA)	DVDD Current (mA)	IOVDD Current (mA)	HPVDD_L Current (mA)
0	1	1/0	N	0	13	0	0	0.99	1.09	0.15	0.003
2	1	0	N	32	13	0	0	2.18	1.87	0.15	0.003
2	1	1/0	N	32	13	0	0	2.18	2.54	0.15	0.003
1	1	1/1	N	0	13	0	0	1.76	1.30	0.22	0.003
3	1	1/3	N	32	13	0	0	2.58	3.04	0.315	0.003
1 <sub>(Voice Wake</sub> Up)	0	0	Y	0	0	0	0	1.46	1.56	0.15	0.003

Typical active noise canceling (ANC) settings (phone call with ANC). Main clock = 24.576 MHz (external oscillator and PLL bypassed). DVDD = 0.9 V, and AVDD = IOVDD = 1.8 V was supplied externally. The three ADCs were PGA enabled and configured for headphone input. The DAC was configured for differential headphone operation, and the DAC output was loaded with  $32 \Omega$ , and DAC\_LPM = 0. One serial port input and output, configured as subordinate, was used. One input and three output ASRCs were used. FastDSP was run at 24.576 MHz, 32 instructions (biquad filters with 27-bit precision) at 192 kHz. Tensilica DSP was bypassed, quiescent current had no signal, and the input signal level was -15 dBFS.

#### Typical Current (mA) Typical Head-**Typical ADC** phone Output **Total Power** THD + N, THD + N (dBV), Operating Performance Consumption Differential DVDD 1 mW Output Voltage Setting **Power Mode** AVDD IOVDD HPVDD\_L (mW) Mode (dB FS) High 3.04 3.06 0.316 0.003 8.8 -95 AVDD = IOVDD Normal voltage Not applicable = 1.8 V, DVDD No load = 0.9 V 7.87 3.06 0.315 0.003 17.49 -95 -96 2.76 0.316 8.63 -95 Low voltage 3.06 0.286 Not applicable No load 2.76 -95 -96 3.06 0.316 5.093 14.4 -95 Normal 2.58 3.06 0.316 0.003 7.97 Normal voltage Not applicable No load 7.41 -95 -85 3.06 0.316 0.003 16.66 Low voltage 2.32 3.06 0.316 0.257 7.8 -95 Not applicable No load 2.32 3.06 0.316 5.071 13.58 -95 -85

#### Table 7. Typical ANC Power Consumption

### **DIGITAL FILTERS**

Table 8. Digital Filters

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
ADC INPUT TO DAC OUTPUT PATH					
Pass-Band Ripple	DC to 20 kHz, sampling frequency (f <sub>S</sub> ) = 192 kHz			±0.02	dB
	(ADCx_FCOMP = 1, and DAC_FCOMP = 1)				
Group Delay	f <sub>S</sub> = 192 kHz		12.9		μs
	f <sub>S</sub> = 384 kHz		7.5		μs
	f <sub>S</sub> = 768 kHz		5		μs
SAMPLE RATE CONVERTER					
Pass Band	FSYNC_x < 63 kHz			0.475 × f <sub>S</sub>	kHz
	63 kHz < FSYNC_x < 112 kHz			0.4286 × f <sub>S</sub>	kHz
	FSYNC_x > 112 kHz		0.2383 × f <sub>S</sub>		kHz
Audio Band Ripple	20 Hz to 20 kHz	-0.1		+0.1	dB
Input and Output Sample Frequency Range		7		224	kHz
Dynamic Range	ASRCx_LPM = 0		130		dB
	ASRCx_LPM = 1		130		dB
	ASRCx_LPM_II = 1		130		dB
THD + Noise	20 Hz to 20 kHz, input is typical at 1 kHz and				
	maximum at 20 kHz				
	ASCRx_LPM = 0		-130	-120	dBFS
	ASCRx_LPM = 1		-120	-110	dBFS
	ASCRx_LPM_II = 1		-115	-90	
Start-Up Time to Lock				25	ms
PDM OUTPUTS					
Dynamic Range	20 Hz to 20 kHz, with A-weighted filter		126		dBFS
THD + N	20 Hz to 20 kHz, –6 dBFS input		-125		dBFS

## DIGITAL TIMING SPECIFICATIONS

-40°C < T<sub>A</sub> < +85°C, IOVDD = 1.1 V to 1.8 V, and DVDD = 0.9 V to 1.1 V, unless otherwise noted.

#### Table 9. Digital Timing Specifications

		Limit		
Parameter	Min	Max	Unit	Description
MAIN CLOCK				MCLKIN period
t <sub>MPI</sub>	0.037	33.3	μs	30 kHz to 36 MHz input clock using PLL in integer mode
t <sub>MPF</sub>	0.037	1.0	μs	30 kHz to 36 MHz input clock using PLL in fractional mode
SERIAL PORT				
t <sub>BL</sub>	18		ns	BCLK_x low pulse width (main and subordinate modes)
t <sub>BH</sub>	18		ns	BCLK_x high pulse width (main and subordinate modes)
f <sub>BCLK</sub>	0.512	24.576	MHz	BCLK_x frequency
t <sub>LS</sub>	3		ns	FSYNC_x setup, time to BCLK_x rising (subordinate mode)
t <sub>LH</sub>	5		ns	FSYNC_x hold, time from BCLK_x rising (subordinate mode)
f <sub>SYNC</sub>	8	768 <sup>1</sup>	kHz	FSYNC_x frequency
t <sub>SS</sub>	3		ns	SDATAI_x setup, time to BCLK_x rising (main and subordinate modes)
t <sub>SH</sub>	10		ns	SDATAI_x hold, time from BCLK_x rising (main and subordinate modes)
t <sub>TS</sub>		6	ns	BCLK_x falling to FSYNC_x timing skew (main mode)
tsod	0	16	ns	SDATAO_x delay, time from BCLK_x falling (main and subordinate modes), IOVDD at 1.62 V minimum

## Table 9. Digital Timing Specifications (Continued)

		Limit	_	
Parameter	Min	Max	Unit	Description
	0	32	ns	SDATAO_x delay, time from BCLK_x falling (main and subordinate modes), IOVDD at 1.1 V minimum
t <sub>SOTD</sub>	0	16	ns	BCLK_x falling to SDATAO_x driven in three-state mode
t <sub>SOTX</sub>	0	16	ns	BCLK_x falling to SDATAO_x three-stated in three-state mode
SERIAL-PERIPHERAL INTERFACE (SPI) PORT				
f <sub>SCLK</sub>		24	MHz	SCLK frequency
t <sub>CCPL</sub>	15		ns	SCLK pulse width low
t <sub>CCPH</sub>	15		ns	SCLK pulse width high
t <sub>CLS</sub>	4		ns	SS setup, time to SCLK rising
t <sub>CLH</sub>	18		ns	SS hold, time from SCLK rising
t <sub>CLPH</sub>	10		ns	SS pulse width high
t <sub>CDS</sub>	8		ns	MOSI setup, time to SCLK rising
t <sub>CDH</sub>	6		ns	MOSI hold, time from SCLK rising
t <sub>COD</sub>	-	17	ns	MISO delay, time from SCLK falling
t <sub>COTS</sub>		24	ns	MISO high-Z, time from SS rising
<sup>2</sup> C PORT				
f <sub>SCL</sub>		1	MHz	SCL frequency
t <sub>SCLH</sub>	0.26	·	μs	SCL high
t <sub>SCLL</sub>	0.5		μs	SCL low
	0.26		μs	SCL rise setup time (to SDA falling), relevant for repeated START condition
t <sub>SCS</sub>	0.20	120	ns	SCL and SDA rise time, $C_{LOAD} = 400 \text{ pF}$
t <sub>SCR</sub>	0.26	120		SCL fall hold time (from SDA falling), relevant for START condition
t <sub>SCH</sub>	50		μs	SDE setup time (to SCL rising)
t <sub>DS</sub> ≁	50	100	ns	
t <sub>SCF</sub>	0.5	120	ns	SCL and SDA fall time, C <sub>LOAD</sub> = 400 pF
	0.5		μs	SCL rise setup time (to SDA rising), relevant for STOP condition
QSPI		502		
f <sub>QCLK</sub>		50 <sup>2</sup>	MHz	QSPIM_CLK frequency
JART				
		1.152	Mbps	Baud rate
GENERAL-PURPOSE INPUT/OUTPUT GPIO) PINS				
t <sub>GIL</sub>		1.5 × 1/f <sub>S</sub>	μs	MPx input latency, time until high or low value is read by core
t <sub>RLPW</sub>	20		ns	PD low pulse width
DIGITAL MICROPHONE				
t <sub>CF</sub> <sup>3</sup>		12	ns	Digital microphone clock fall time
t <sub>CR</sub> <sup>3</sup>		14	ns	Digital microphone clock rise time
t <sub>SETUP</sub>	10		ns	Digital microphone data-setup time
t <sub>HOLD</sub>	3		ns	Digital microphone data-hold time
PDM OUTPUT				
f <sub>PDM_CLK</sub>				PDM clock frequency
		3.072	MHz	3 MHz setting
		6.144	MHz	6 MHz setting
t <sub>CF</sub> <sup>3</sup>		12	ns	Digital PDM clock output fall time
t <sub>CR</sub> <sup>3</sup>		14	ns	Digital PDM clock output rise time
t <sub>HOLD</sub>	35	46	ns	PDM data-hold time

- <sup>1</sup> Stereo, 16 bit per channel only at 768 kHz.
- <sup>2</sup> Measured when IOVDD = 1.8 V house temperature.
- <sup>3</sup> Digital microphone clock rise and fall times are measured at 2 mA drive strength with 25 pF load.

## **Digital Timing Diagrams**



Figure 2. Serial Input Port Timing Diagram



Figure 3. Serial Output Port Timing Diagram



Figure 4. SPI Port Timing Diagram



Figure 5. I<sup>2</sup>C Port Timing Diagram



Figure 6. Digital Microphone Timing Diagram



Figure 7. PDM Output Timing Diagram

## **ABSOLUTE MAXIMUM RATINGS**

#### Table 10. Absolute Maximum Ratings

Parameter	Rating
Power Supply (AVDD, IOVDD, and HPVDD_L)	–0.3 V to +1.98 V
Digital Supply (DVDD)	–0.3 V to +1.21 V
Input Current (Except Supply Pins)	±20 mA
Analog Input Voltage (Signal Pins)	-0.3 V to AVDD + 0.3 V
Digital Input Voltage (Signal Pins)	-0.3 to IOVDD + 0.3 V
Temperature	
Operating Range (Case)	-40°C to +85°C
Storage Range	-65°C to +150°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

#### THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.

 $\theta_{JA}$  and  $\theta_{JC}$  are determined according to JESD-51-9 on a 4-layer PCB with natural convection cooling.

#### Table 11. Thermal Resistance

Package Type	θ <sub>JA</sub> 1	θ <sub>JC</sub> 1	Unit
CS-64-2	38.5	8.7	°C/W

<sup>1</sup> Thermal impedance simulated values are based on a JEDEC 2S2P thermal test board with two thermal vias. See JEDEC JESD-51.

## **ELECTROSTATIC DISCHARGE (ESD) RATINGS**

The following ESD information is provided for handling of ESD-sensitive devices in an ESD protected area only.

Human body model (HBM) per ANSI/ESDA/JEDEC JS-001.

Charged device model (CDM) per ANSI/ESDA/JEDEC JS-002.

#### ESD Ratings for the ADAU1861

#### Table 12. ADAU1861, 64-Lead LFCSP

ESD Model	Withstand Threshold (V)	Class
HBM	1000	1C
CDM	500	C2A

#### ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

#### PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



800

#### Figure 8. Pin Configuration (Top View)

#### Ball No. Mnemonic Type<sup>1</sup> Description 1 DMIC01/MP1 D IO Digital Microphone Stereo Input 0 and Digital Microphone Stereo Input 1 (DMIC01). Multipurpose I/O 1 (MP1). 2 SDA/MISO/ D\_IO I<sup>2</sup>C Data (SDA). The SDA pin is a bidirectional open-collector. The line connected to SDA must have a 2.0 k $\Omega$ UART CTRL TX pull-up resistor. SPI Data Output (MISO). This SPI data output is used for reading back registers and memory locations. MISO is three-stated when an SPI read is not active. UART Control Port Data Transmit and Output (UART CTRL TX). D\_IO Quad Main SPI Clock (QSPIM\_CLK). 3 QSPIM CLK/MP11 Multipurpose I/O 11 (MP11). D IO I<sup>2</sup>C Clock (SCL). The SCL pin is always an open-collector input when the device is in I<sup>2</sup>C control mode. The line 4 SCL/SCLK connected to the SCL pin must have a 2.0 kΩ pull-up resistor. SPI Clock (SCLK). The SCLK pin can either run continuously or be gated off between SPI transactions. 5 ADDR0/SS D IN I<sup>2</sup>C Address 0 (ADDR0) SPI Latch Signal (SS). SS must go low at the beginning of an SPI transaction and high at the end of a transaction. Each SPI transaction can take a different number of SCLK cycles to complete, depending on the address and read/write bit that are sent at the beginning of the SPI transaction. D IO 6 QSPIM SDIO0/MP13 Quad Main SPI Data I/O 0 (QSPIM SDIO0). Multipurpose I/O 13 (MP13). 7 D IO DMIC CLK/MP0 Digital Microphone Clock Output (DMIC CLK). Multipurpose I/O 0 (MP0). 8 DMIC23/MP2 D IO Digital Microphone Stereo Input 2 and Digital Microphone Stereo Input 3 (DMIC23). Multipurpose I/O 2 (MP2). 9 ADDR1/MOSI/ D IN I<sup>2</sup>C Address 1 (ADDR1). UART CTRL RX SPI Data Input (MOSI). UART Control Port Data Receiver/Input (UART CTRL RX). D IO Quad Main SPI Data Input/Output 1 (QSPIM SDIO1). 10 QSPIM SDIO1/MP14 Multipurpose I/O 14 (MP14). 11 SELFBOOT/MP19 D 10 Self Boot (SELFBOOT). Set SELFBOOT up to IOVDD at power-up to enable self-boot mode. Otherwise, set SELFBOOT to GND at start-up. Multipurpose I/O 19 (MP19). D\_IO 12 QSPIM\_SDIO3/MP16 Quad Main SPI Data Input/Output 3 (QSPIM\_SDIO3). Multipurpose I/O 16 (MP16).

#### Table 13. Pin Function Descriptions

#### PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

#### Table 13. Pin Function Descriptions (Continued)

Ball No.	Mnemonic	Type <sup>1</sup>	Description
13	QSPIM_SDIO2/MP15	D_IO	Quad Main SPI Data Input/Output 2 (QSPIM_SDIO2).
			Multipurpose I/O 15 (MP15).
14	QSPIM_CS/MP12	D_IO	Quad Main SPI Chip Select (QSPIM_CS).
			Multipurpose I/O 12 (MP12).
15	AVDD	PWR	1.8 V Analog Supply. Decouple AVDD to AGND with a 10 μF capacitor.
16	AGND	PWR	Analog Ground. The AGND and DGND pins can be tied together in a common ground plane.
17, 18, 29 to 34, 47, 48	NC		No Connect. Do not connect to this pin.
19	AINN0	A_IN	ADC0 Inverting Input.
20	AINP0	A_IN	ADC0 Noninverting Input.
21	AINN1	A_IN	ADC1 Inverting Input.
22	AINP1	A_IN	ADC1 Noninverting Input.
23	AINN2	A_IN	ADC2 Inverting Input.
24	AINP2	A_IN	ADC2 Noninverting Input.
25	СМ	A_OUT	Common-Mode Reference Fixed at 0.85 V Nominal. A 1 $\mu$ F decoupling capacitor must be connected between CM and ground to reduce crosstalk between the ADCs and DACs. The material of the capacitors is not critical. CM can be used to bias external analog circuits as long as these circuits are not drawing current from CM (for example, the noninverting input of an op amp).
26	AGND	PWR	Analog Ground. The AGND and DGND pins can be tied together in a common ground plane.
27	AVDD	PWR	1.8 V Analog Supply. Decouple AVDD to AGND with a 10 μF capacitor.
28	REG_EN	A_IN	Regulator Enable. Tie to AVDD to enable the internal regulator, and tie to ground to disable.
35	HPOUTN	A_OUT	Headphone Output Inverted.
36	HPOUTP	A_OUT	Headphone Output Noninverted.
37	AGND	PWR	Analog Ground. The AGND and DGND pins can be tied together in a common ground plane.
38	AVDD	PWR	1.8 V Analog Supply. Decouple AVDD to AGND with a 10 μF capacitor.
39	HPVDD_L	PWR	Power Supply for the Internal LDO Regulator and Headphone Amplifier Power. Decouple HPVDD_L to HPGND with a 10 $\mu$ F capacitor.
40	UART_COMM_RX/MP18	D_IO	Communication UART Port Data Receiver/Input (UART_COMM_RX). Multipurpose I/O 18 (MP18).
41	SDATAI_0/MP6	D_IO	Serial Audio Port 0 Input Data (SDATAI_0).
11		D_10	Multipurpose I/O 6 (MP6).
42	UART_COMM_TX/MP17	D_IO	Communication UART Port Data Transmit/Output (UART_COMM_TX).
72		D_10	Multipurpose I/O 17 (MP17).
43	IRQ/MP20	D_IO	Interrupt Input/Output (IRQ).
10		<u> </u>	Multipurpose I/O 20 (MP20).
44	SDATAO_0/MP5	D_IO	Serial Audio Port 0 Output Data (SDATAO_0).
			Multipurpose I/O 5 (MP5).
45	PD	D_10	Active-Low Power Down. All digital and analog circuits are powered down. There is an internal pull-down resistor on the PD pin; therefore, the ADAU1861 is held in power-down mode if its input signal is floating while power is applied to the supply pins.
46	ROM_BOOT_MODE/MP21	D_10	ROM Boot_Up Mode (ROM_BOOT_MODE). Use Boot-Up Mode 1 when connecting to IOVDD and use Boot-Up Mode 2 when connecting to ground.
4.0			Multipurpose IO 21 (MP21).
49	FSYNC_0/MP4	D_10	Serial Audio Port 0 Frame Sync/Left Right Clock (FSYNC_0).
50			Multipurpose I/O 4 (MP4).
50	BCLK_0/MP3	D_IO	Serial Audio Port 0 Bit Clock (BCLK_0).
51	HPVDD_L	PWR	Multipurpose I/O 3 (MP3). Power Supply for the Internal LDO Regulator and Headphone Amplifier Power. Decouple HPVDD_L to HPGND with
50			a 10 µF capacitor.
52	FSYNC_1/MP8	D_IO	Serial Audio Port 1 Frame Sync/Left Right Clock (FSYNC_1).

#### PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

#### Table 13. Pin Function Descriptions (Continued)

Ball No.	Mnemonic	Type <sup>1</sup>	Description
			Multipurpose I/O 8 (MP8).
53	SDATAO_1/MP9	D_IO	Serial Audio Port 1 Output Data (SDATAO_1).
			Multipurpose I/O 9 (MP9).
54	DVDD	PWR	Digital Core Supply. The digital supply can be generated from an on-board regulator or supplied directly from an external supply. In each case, decouple DVDD to DGND with a 1 uF and 0.1 µF capacitor.
55	DGND	PWR	Digital Ground. The AGND and DGND pins can be tied together in a common ground plane.
56	IOVDD	PWR	Supply for Digital Input and Output Pins. The digital output pins are supplied from IOVDD, and this sets the highest input voltage that can be seen on the digital-input pins. The current draw of IOVDD is variable because it is dependent on the loads of the digital outputs. Decouple IOVDD to DGND with a 0.1 µF capacitor at least.
57	TCK/MP22	D_IO	JTAG Port Clock Input (TCK).
			Multipurpose I/O 22 (MP22).
58	SDATAI_1/MP10	D_IO	Serial Audio Port 1 Input Data (SDATAI_1).
			Multipurpose I/O 10 (MP10).
59	BCLK_1/MP7	D_IO	Serial Audio Port 1 Bit Clock (BCLK_1).
			Multipurpose I/O 7 (MP7).
60	TMS/MP23	D_IO	JTAG Port Mode Selection (TMS).
			Multipurpose I/O 23 (MP23).
61	TDO/MP24	D_IO	JTAG Port Data Output (TDO).
			Multipurpose I/O 24 (MP24).
62	XTALO	A_OUT	Crystal Clock Output. The XTALO pin is the output of the crystal amplifier and must not be used to provide a clock to other ICs in the system.
63	XTALI/MCLKIN	D_IN	Crystal Clock Input (XTALI).
			Main Clock Input (MCLKIN).
64	TDI/MP25	D_IO	JTAG Port Data Input (TDI).
			Multipurpose I/O 25 (MP25).
	EPAD		Exposed Pad. Exposed pad must be connected to GND.

<sup>1</sup> D\_IO means digital input/output, D\_IN means digital input, PWR means power, A\_IN means analog input, and A\_OUT means analog output.



Figure 9. Frequency Response, f<sub>S</sub> = 48 kHz, -20 dBV Input, Signal Path = AINxx to SDATAO\_x, Differential Mode, No PGA



Figure 10. Frequency Response, f<sub>S</sub> = 48 kHz, -20 dBV Input, Signal Path = AINxx to SDATAO x, Single-End Mode, No PGA



Figure 11. Frequency Response, f<sub>S</sub> = 48 kHz, Signal Path = AlNxx to SDATAO\_x, Differential Mode, Output Relative to PGA Gain Settings (0 dB, 10 dB, and 24 dB), ADCx\_FCOMP Off



Figure 12. Frequency Response, f<sub>S</sub> = 48 kHz, Signal Path = AlNxx to SDATAO\_x, Single-End Mode, Output Relative to PGA Gain Settings (0 dB, 10 dB, and 24 dB), ADCx\_FCOMP Off



Figure 13. Fast Fourier Transform (FFT), No Signal, f<sub>S</sub> = 48 kHz, Signal Path = AINxx to SDATAO x, Differential Mode, No PGA, and 10 dB PGAx GAIN



Figure 14. FFT, -1 dBV Input, -1 dBFS Output, f<sub>S</sub> = 48 kHz, Signal Path = AINxx to SDATAO x, Differential Mode, No PGA



Figure 15. THD + N Level vs. Amplitude, f<sub>S</sub> = 48 kHz, Signal Path = AINxx to SDATAO\_x



Figure 16. Frequency Response, f<sub>S</sub> = 48 kHz, Signal Path = SDATAI\_x to PDM Output



Figure 17. FFT, No Signal, f<sub>S</sub> = 48 kHz Throughout, Signal Path = SDATAI\_x to FastDSP to PDM Output



Figure 18. FFT, -7 dBFS, f<sub>S</sub> = 48 kHz Throughout, Signal Path = SDATAI\_x to FastDSP to PDM Output



Figure 19. PSRR, Signal Path = AINxx to SDATAO\_x, f<sub>S</sub> = 48 kHz, 100 mV p-p Ripple Input on AVDD, No PGA



Figure 20. PSRR, Signal Path = AINxx to SDATAO\_x, f<sub>S</sub> = 48 kHz, 100 mV p-p Ripple Input on AVDD, PGA = 0 dB



Figure 21. PSRR, Signal Path = AINxx to SDATAO\_x, f<sub>S</sub> = 48 kHz, 100 mV p-p Ripple Input on AVDD, PGA = 10 dB



Figure 22. PSRR, Signal Path = SDATAI\_x to HPOUT, f<sub>S</sub> = 48 kHz, 100 mV p-p Ripple Input on AVDD or HPVDD L (LDO Bypass)



Figure 23. FFT, No Signal,  $f_S$  = 48 kHz, Signal Path = SDATAI\_x to HPOUT, Headphone Mode, Load = 32  $\Omega$ 



Figure 24. FFT, No Signal,  $f_S$  = 48 kHz, Signal Path = SDATAI\_x to the Output of the DAC Working in Line Output Mode (LOUT), Load = 10 k $\Omega$ 



Figure 25. FFT, -1 dBFS, f<sub>S</sub> = 48 kHz, Signal Path = SDATAI\_x to the Output of the DAC Working in Headphone Mode (HPOUT), Load = 32  $\Omega$ 



Figure 26. FFT, -1 dBFS, f<sub>S</sub> = 48 kHz, Signal Path = SDATAI\_x to LOUT Line Output Mode, Load = 10 kΩ



Figure 27. FFT, No Signal,  $f_S$  = 768 kHz, Signal Path = SDATAI\_x to Interpolator to FastDSP to HPOUT, Headphone Mode, Load = 32  $\Omega$ 



Figure 28. FFT, No Signal,  $f_S$  = 768 kHz, Signal Path = SDATAI\_x to Interpolator to FastDSP to LOUT, Line Output Mode, Load = 32  $\Omega$ 



Figure 29. FFT, -1 dBFS, f<sub>S</sub> = 768 kHz, Signal Path = SDATAI\_x to Interpolator to FastDSP to HPOUT, Headphone Mode, Load = 32 Ω



Figure 30. FFT, -1 dBFS,  $f_S$  = 768 kHz, Signal Path = SDATAI\_x to Interpolator to FastDSP to LOUT, Line Output Mode, Load = 10 k $\Omega$ 



Figure 31. THD + N Level vs. Input Amplitude,  $f_S$  = 48 kHz, 16  $\Omega$ , 24  $\Omega$ , 32  $\Omega$ , or 10 k $\Omega$  (Normal), Signal Path = SDATAL x to HPOUT/LOUT



Figure 32. Relative Level vs. Frequency,  $f_S$  = 48 kHz, Signal Path = SDATALx to HPOUT/LOUT, 16  $\Omega$ , 24  $\Omega$ , 32  $\Omega$ , or 10 k $\Omega$ 







Figure 34. Relative Level vs. Frequency, f<sub>S</sub> = 48 kHz Throughout Except FastDSP = 768 kHz, Signal Path = SDATAI\_x to ASRCI to Equalizer to Interpolator to FastDSP to Decimator to ASRCO to SDATAO x



Figure 35. FFT, No Signal, f<sub>S</sub> = 48 kHz Throughout Except FastDSP = 768 kHz, Signal Path = SDATAL\_x to ASRCI to Equalizer to Interpolator to FastDSP to Decimator to ASRCO to SDATAO\_x



Figure 36. FFT, No Signal, f<sub>S</sub> = 48 kHz Throughout Except FastDSP = 768 kHz, Signal Path = SDATAI\_x to Equalizer to Interpolator to FastDSP to Decimator to SDATAO\_x



Figure 37. FFT, -1 dBFS Input, f<sub>S</sub> = 48 kHz Throughout Except FastDSP = 768 kHz, Signal Path = SDATAI\_x to ASRCI to Equalizer to Interpolator to FastDSP to Decimator to ASRCO to SDATAO\_x



Figure 38. FFT, –1 dBFS Input, f<sub>S</sub> = 48 kHz Throughout Except FastDSP = 768 kHz, Signal Path = SDATAL\_x to Equalizer to Interpolator to FastDSP to Decimator to SDATAO\_x



Figure 39. Group Delay (Smooth) vs. Frequency, f<sub>S</sub> = 48 kHz to 768 kHz, Differential Mode, Signal Path = AINxx to FastDSP to HPOUT/LOUT



Figure 40. Group Delay (Smooth) vs. Frequency, f<sub>S</sub> = 48 kHz to 768 kHz, Single-End Mode, Signal Path = AINxx to FastDSP to HPOUT/LOUT



Figure 41. FFT, No Signal, DMIC\_CLK\_RATE = 3.072 MHz and 6.144 MHz, Signal Path = DMICxx to SDATAO\_x



Figure 42. Relative Level vs. Frequency, DMIC\_CLK\_RATE = 3.072 MHz and 6.144 MHz, Signal Path = DMICxx to SDATAO\_x, FCOMP = EN



Figure 43. FFT, -10 dBFS Input, DMIC\_CLK\_RATE = 3.072 MHz, Signal Path = DMICxx to SDATAO\_x



Figure 44. FFT, -10 dBFS Input, DMIC\_CLK\_RATE = 6.144 MHz, Signal Path = DMICxx to SDATAO\_x



Figure 45. THD + N Level vs. Amplitude, -10 dBFS, DMIC\_CLK\_RATE = 3.072 MHz and 6.144 MHz (Fifth-Order), Signal Path = DMICxx to SDATAO\_x



Figure 46. Relative Level vs. Frequency, Differential and Single-End Mode, Headphone and Line Output Mode, Load = 16  $\Omega$  to 10 k $\Omega$ , f<sub>S</sub> = 48 kHz and 768 kHz, Signal Path = AIN0 to DAC



Figure 47. THD + N Level vs. Amplitude,  $f_S$  = 48 kHz to 768 kHz, Load = 10 k $\Omega$ , Signal Path = AINx to HPOUT/LOUT



Figure 48. FFT, -1 dBV Input, Differential Mode, Line Output Mode, Load = 10  $k\Omega$ ,  $f_S$  = 48 kHz to 768 kHz, Signal Path = AINx to LOUT



Figure 49. FFT, No Signal, Differential Mode, Load = 32  $\Omega$  to 10 k $\Omega$ , f<sub>S</sub> = 48 kHz to 768 kHz, Signal Path = AINx to HPOUT/LOUT

## THEORY OF OPERATION

The ADAU1861 is a low-power audio codec with an optimized audio processing core, making it ideal for noise canceling applications that require high quality audio, low-power, small size, and low latency. The two serial audio ports are compatible with I<sup>2</sup>S, left-justified, right-justified, and time division multiplexing (TDM) modes, with three-state for interfacing to digital audio data. The analog operating voltage is 1.8 V, and an optional internal regulator can be used to generate the digital supply voltage. If required, the regulator can be powered down, and the digital supply voltage can be supplied externally, which is determined by the REG EN pin.

The input signal path includes flexible configurations that can accept differential or single-ended analog microphone inputs as well as up to eight digital microphone inputs. Each input signal has its own PGA for volume adjustment.

The ADCs and DAC are high quality, 24-bit  $\Sigma$ - $\Delta$  converters that operate at a selectable sampling rate, and the ADCs also support an 8 kHz or a 16 kHz sampling rate in voice wake-up mode. The ADCs and DAC have an optional high-pass filter with a cutoff frequency and fine step digital soft volume controls.

The DAC output is capable of differentially driving a headphone earpiece speaker with 16  $\Omega$  impedance or higher. There is also the option to change to LOUT mode when the output is lightly loaded.

The Tensilica HiFi 3z DSP core is optimized for low-power audio processing. In addition, the Tensilica HiFi 3z DSP core allows the ADAU1861 to provide flexible solutions to meet more complicated applications.

The FastDSP core has a reduced instruction set that optimizes this codec for noise cancellation. The program and parameter random access memories (RAMs) can be loaded with custom audio processing signal flow built using the Lark Studio graphical user interface (GUI). The values stored in the parameter RAM control individual signal processing blocks.

The ADAU1861 also has a self boot function that can load the program and parameter RAMs of both cores along with the register settings on power-up using an external flash memory over the quad SPI. The external flash memory is fully memory mapped to the HiFi 3z DSP core bus fabric.

Use the Lark Studio GUI to program and control the cores through the control port. Along with designing and tuning a signal flow, the GUI can configure all of the ADAU1861 registers. The GUI allows anyone with digital or analog audio processing knowledge to design the DSP signal flow and export the flow to a target application. The interface also provides enough flexibility and programmability for an experienced DSP programmer to have control of the design. In the Lark Studio GUI, the user can connect graphical blocks (such as biquad filters, volume controls, and arithmetic operations), compile the design, and load the program and parameter files into the ADAU1861 memory through the control port. The tool also allows the user to download the design to an external flash memory for self boot operation. The ADAU1861 can generate the internal clocks from a wide range of input clocks by using the on-board bypassable fractional PLL. The PLL accepts inputs from 30 kHz to 36 MHz. For standalone operation, the clock can be generated using the on-board crystal oscillator.

The ADAU1861 is provided in Figure 51.

## **APPLICATIONS INFORMATION**

#### **POWER-SUPPLY BYPASS CAPACITORS**

Bypass each analog and digital power-supply pin to its nearest appropriate ground pin with a single 0.1  $\mu$ F capacitor. In Figure 50, VDD refers to all power supplies (DVDD, IOVDD, AVDD, and HPVDD\_L). Keep the connections to each side of the capacitor as short as possible, and route the trace on a single layer with no vias. For maximum effectiveness, place the capacitor equidistant from the power and ground pins or slightly closer to the power pin if equidistant placement is not possible. Make thermal connections to the ground planes on the far side of the capacitor.

Bypass each supply signal on the PCB with a single bulk capacitor (10  $\mu$ F to 47  $\mu$ F).



Figure 50. Recommended Power-Supply Bypass Capacitor Layout

## LAYOUT

The AVDD and HPVDD\_L supplies are for the headphone amplifiers. If the headphone amplifiers are enabled, the PCB traces to the AVDD and HPVDD\_L pins must be wider than the traces to the other pins to increase the current carrying capacity. Use a wider trace for the headphone output lines.

#### GROUNDING

Use a single ground plane in the application layout. Place components in an analog signal path away from digital signals.

#### **OUTLINE DIMENSIONS**



RECOMMENDED SOLDER PAD LAYOUT APPLY SOLDER MASK TO AREAS THAT ARE NOT SOLDERED



Dimensions shown in millimeters

Updated: October 12, 2022

#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Packing Quantity	Package Option
ADAU1861BCSZ-RL	-40°C to +105°C	64-Lead Lead Frame Chip Scale Package [LFCSP_SS]	Reel, 2500	CS-64-2

<sup>1</sup> Z = RoHS Compliant Part.

#### **EVALUATION BOARDS**

Model <sup>1</sup>	Description
EVAL-ADAU1861EBZ	Evaluation Board

<sup>1</sup> Z = RoHS Compliant Part.

I<sup>2</sup>C refers to a communications protocol originally developed by Philips Semiconductors (now NXP Semiconductors).

