

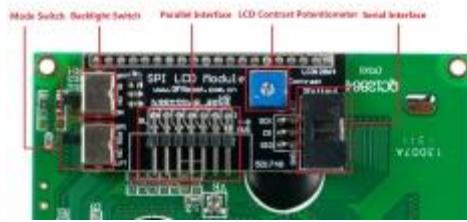


3-wire Serial LCD Module (Arduino Compatible) (SKU:DFR0091)

Introduction

This LCD module uses a 128x64 liquid crystal display that support Chinese character , English characters and even graphics. It can exhibit 4 lines and 12 English characters/6 Chinese characters per line. It is suitable for interactive work with [Arduino](#).

It features a backlit control, parallel or serial control, contrast adjust. It can be connect to our interface shield via IDC6 socket and cables.



connection diagram for LCD Module

Mode Selection

The LCD is shipped in Parallel mode by default. The PSB_ON switch is used to set the interface mode. To switch to 3-Wire mode, Set the switch to SPI.

Code

This sample is working under Parallel mode. You will need Arduino library which can be download [here](#).

Connection in Parallel mode:

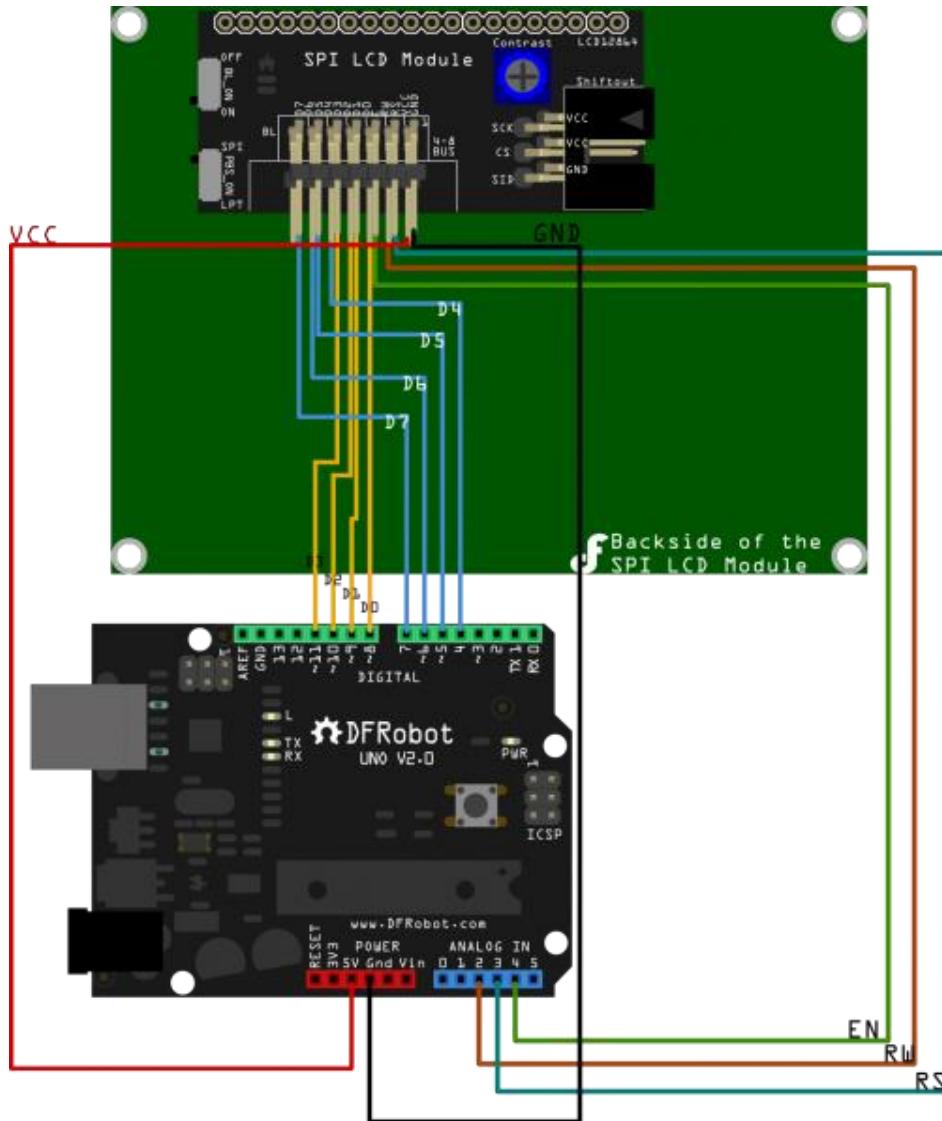


Fig1: Parallel_Mode

```

/*
LCD Arduino

RS = 17; Analog Pin3
RW = 16; Analog Pin2
EN = 18; Analog Pin4

D0 = 8;
D1 = 9;
D2 = 10;
D3 = 11;
D4 = 4;
D5 = 5;
D6 = 6;
D7 = 7;

PIN15 PSB = 5V;

*/



#include "LCD12864R.h"

#define AR_SIZE( a ) sizeof( a ) / sizeof( a[0] )



unsigned char show0[]={0xBB,0xFA,0xC6,0xF7,0xC8,0xCB,0xC3,0xCE,0xB9,0xA4,0xB3
,0xA7}; //DFRobot

unsigned char show1[]{"www.dfrobot.com"}; //



void setup()
{
LCDA.Initialise(); // INIT SCREEN
delay(100);
}

void loop()
{
LCDA.CLEAR(); //Clear the screen
delay(100);
LCDA.DisplaySig(0,0,0x20); //Display space
}

```

```

delay(100);

LCDA.DisplayString(0,1,show0,AR_SIZE(show0)); //LOGO

delay(100);

LCDA.DisplayString(2,0,show1,AR_SIZE(show1)); //LOGO

while(1);

}

```

The following sample is working under 3-Wire mode. You will need the Arduino Library which can be downloaded [here](#).

Connection in 3-Wire mode:(2 Methods)

Method1:

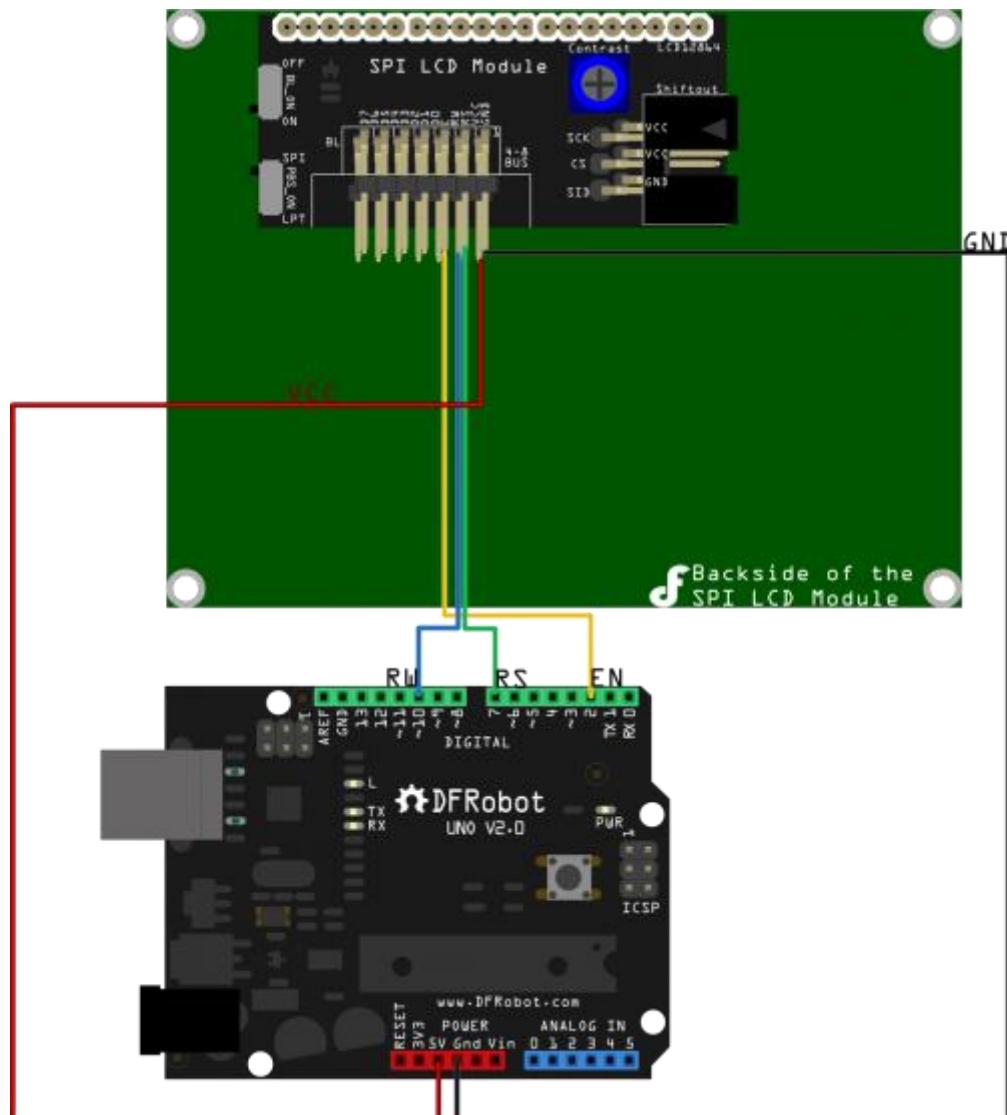


Fig2: 3-Wire Mode_1

Method2:

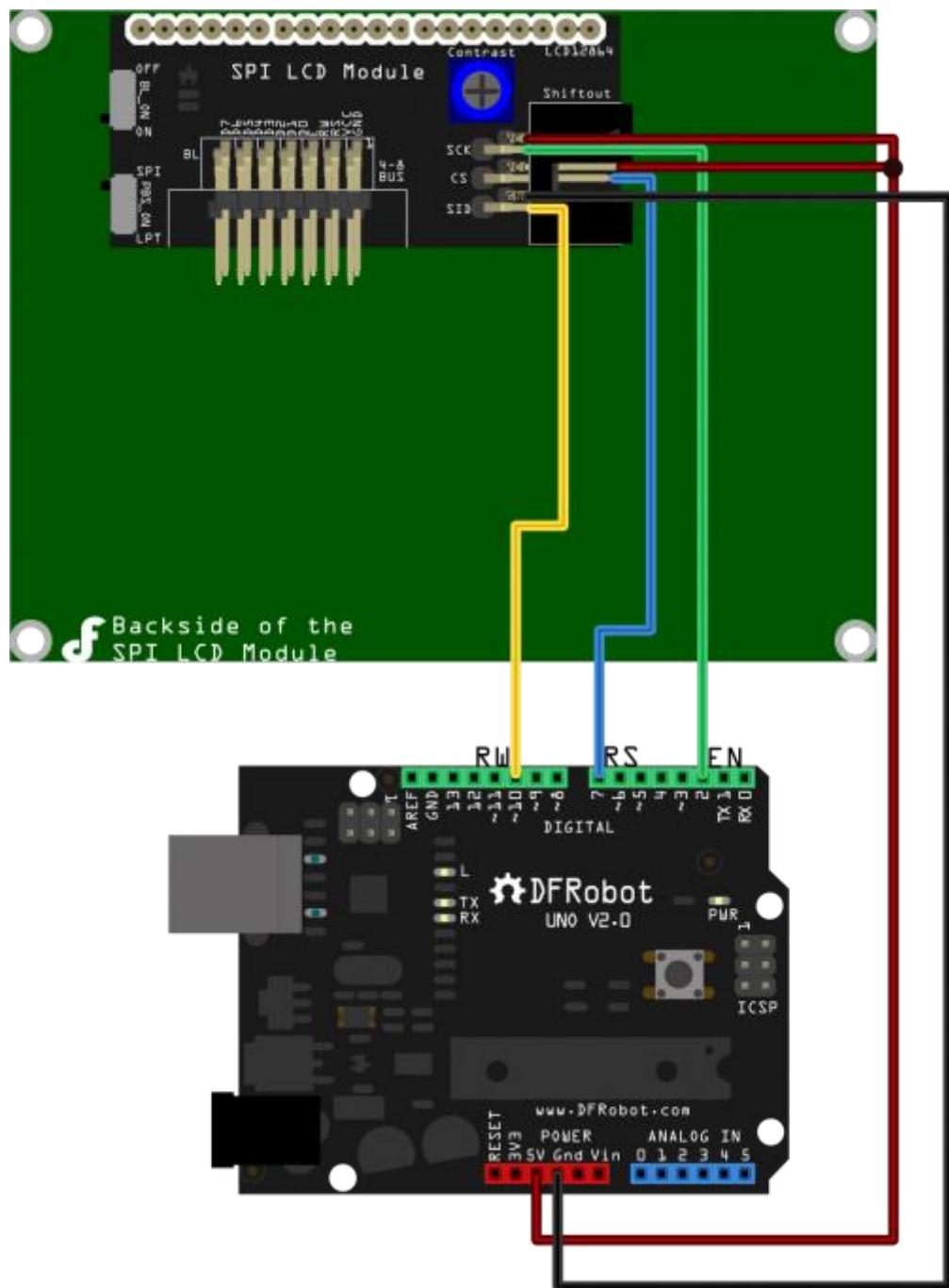


Fig2: 3-Wire Mode_2

```
/*
1. SPI Interface Instruction
    clockPin --> SCK(EN)
```

```
latchPin --> CS (RS)
dataPin --> SID (RW)
```

2. Connection:

- 1) Turn the BL_ON Switch to the "ON" side;
- 2) Turn the PBS_ON Switch to the "SPI" side

Method1:

| | |
|-----|----------------|
| LCD | Arduino |
| EN | Digital Pin 2 |
| RS | Digital Pin 7 |
| RW | Digital Pin 10 |
| VCC | 5V |
| GND | GND; |

Method2:

| | |
|-----|--|
| LCD | Arduino |
| SCK | clockPin (defined in the "initDriverPin" function) |
| CS | latchPin (defined in the "initDriverPin" function) |
| SID | dataPin (defined in the "initDriverPin" function) |
| VCC | 5V |
| GND | GND |

*/

```
#include "LCD12864RSPI.h"
#include "DFrobot_bmp.h"
#include "DFrobot_char.h"

#define AR_SIZE( a ) sizeof( a ) / sizeof( a[0] )

unsigned char wangzhi[]=" www.DFRobot.com ";
unsigned char en_char1[]="ST7920 LCD12864 ";
```

```
unsigned char en_char2[]{"Test, Copyright "};

unsigned char en_char3[]{"by DFRobot ---> ";

void setup()
{
    LCDA.initDriverPin(2,7,10); //INIT SPI Interface
    LCDA.Initialise(); // INIT SCREEN
    delay(100);
    LCDA.DrawFullScreen(logo); //LOGO
    delay(5000);

}

void loop()
{
    LCDA.CLEAR(); //Clear Screen
    delay(100);
    LCDA.DisplayString(0,0,en_char1,16);
    delay(10);
    LCDA.DisplayString(1,0,en_char2,16);
    delay(10);
    LCDA.DisplayString(2,0,en_char3,16);
    delay(10);
    LCDA.DisplayString(3,0,wangzhi,16);
    delay(5000);
    LCDA.CLEAR(); //Clear Screen
    delay(100);
    LCDA.DisplayString(0,0,show1,16);
    delay(10);
    LCDA.DisplayString(1,0,show2,16);
    delay(10);
    LCDA.DisplayString(2,0,show3,16);
    delay(10);
    LCDA.DisplayString(3,0,wangzhi,16); //LOGO
```

```
delay(5000);  
}
```

The following sample is working under 3-Wire mode. It demonstrates how to display integers on the LCD screen. You will need the Arduino Library which can be downloaded [here](#).

```
/*  
  
1. SPI Interface Inatruction  
    clockPin --> SCK(EN)  
    latchPin --> CS(RS)  
    dataPin --> SID(RW)  
  
2. Connection:  
    1) Turn the BL_ON Switch to the "ON" side;  
    2) Turn the PBS_ON Switch to the "SPI" side
```

Method1:

| | |
|-----|----------------|
| LCD | Arduino |
| EN | Digital Pin 2 |
| RS | Digital Pin 7 |
| RW | Digital Pin 10 |
| VCC | 5V |
| GND | GND; |

Method2:

| | |
|-----|--|
| LCD | Arduino |
| SCK | clockPin (defined in the "initDriverPin" function) |
| CS | latchPin (defined in the "initDriverPin" function) |
| SID | dataPin (defined in the "initDriverPin" function) |
| VCC | 5V |
| GND | GND |

This sample shows how to use LCD12864 to display integer on the screen, and it uses function itoa() from library stdlib.h

```
*/
```

```
#include "LCD12864RSPI.h"
```

```
#include "DFrobot_bmp.h"
#include "DFrobot_char.h"
#include "stdlib.h"

#define AR_SIZE( a ) sizeof( a ) / sizeof( a[0] )

int i=0; //counter, initial value is 0

unsigned char wangzhi[]=" www.DFRobot.cn ";
unsigned char en_char1[]="ST7920 LCD12864 ";
unsigned char en_char2[]="Test, Copyright ";
unsigned char en_char3[]="by DFRobot ---> ";

void setup()
{
    LCDA.initDriverPin(2,7,10); //INIT SPI Interface
    LCDA.Initialise(); // INIT SCREEN
    delay(100);
    LCDA.DrawFullScreen(logo); //LOGO
    delay(2000);
    randomSeed(0);
    LCDA.CLEAR();
    delay(100);
    LCDA.DisplayString(0,0,en_char1,16);
    delay(10);
    LCDA.DisplayString(1,0,en_char2,16);
    delay(10);
    LCDA.DisplayString(2,0,en_char3,16);
    delay(10);
    LCDA.DisplayString(3,0,wangzhi,16);
    delay(2000);
}
```

```

}

void loop()
{
LCDA.CLEAR(); //clear the screen
delay(100);

int number= i; // the interger should be in the range from -32768 ~ 32767
char buf [16];
itoa(number,buf,10); //transform integer into string
unsigned char temp[16];

for (int i=0;i<=15;i++)
{
    if(buf[i]!='0'&&buf[i]!='1'&&buf[i]!='2'&&buf[i]!='3'&&buf[i]!='4'&&buf[i]!='5'&&buf[i]!='6'&&buf[i]!='7'&&buf[i]!='8'&&buf[i]!='9'&&buf[i]!='-')
        {temp[i]=' ';} // put space into those where no values are assigned initially
    else
        {temp[i]=buf[i];}
}
LCDA.DisplayString(0,0,temp,16); //display the counter on the screen

delay(1000);
i++; // counter works every 1 second
}

```