

SENSOR SHIELD

INTERFACE EXTENSION BOARD FOR ARDUINO

order code	product name
2501000101291	Sensor Shield

VERSION 1.0

NOVEMBER 18, 2020

Revision history

Manual version	HW version	Notes	Date
1.0	2.2	Initial version	November 2020

Software revision history

Manual version	SW version	Notes	Date
1.0	1.0	Initial version	November 2020

 \star For detailed software version history see chapter <code>Software history</code>

Abbreviations and abstract

Abbreviation	Description
CS	SPI Chip select
GND	Ground
l ² C	Inter-Integrated Circuit
JTAG	Joint Test Action Group
MISO	Master in, slave out
MOSI	Master out, slave in
SCLK	Serial Clock
SDA	I ² C Serial data line
SPI	Serial Peripheral Interface
SWD	Serial Wire Debug
VDD	Supply voltage

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1 Supported products

The evaluation board described in this manual is a stackable extention board for the Arduino (UNO and DUE) board. It can be used to connect the following Sensor EVAL-Boards:

Sensor	Evaluation board Order code	Sensor order code
Temperature sensor IC	2521020222591	2521020222501
Humidity sensor with integrated temperature sensor	2525020210091	2525020210001
3 axis acceleration sensor	2533203301691	2533020201601
Absolute pressure sensor	2511223013391	2511020213301
Differential pressure sensor	2513254510091 2513254510191 2513254510291 2513254510391 2513254510491	2513130810001 2513130810101 2513130810201 2513130810301 2513130810401

Table 1: Sensor shield compatibility

The following interfaces are supported by the sensors: The corresponding sensors that can be evaluated with this sensor shield are:

Sensors & Sensor Eval Board	Interface			
Sensors & Sensor Eval Doard	3.3V I ² C	3.3V SPI	5V I ² C	5V SPI
Temperature sensor IC	х	Х		
Humidity sensor with integrated temperature sensor	х	х		
3 axis acceleration sensor	х	Х		
Absolute pressure sensor	х	Х		
Differential pressure sensor			х	

Table 2: Supported sensor interface



Figure 1: Sensor shield for Arduino

Order code:2501000101291 contents	Quantity
Sensor shield including needed jumpers	1
ESD safe packaging	1
Radio module with individualized firmware	0
Arduino board	0

Table 3: Contents sensor shield EV-kit

2 Overview

2.1 Block diagram



Figure 2: Block Diagramm

2.2 Functional description

The Sensor shield is an interface extension board for Arduino UNO and DUE. It offers the user the possibility to connect sensors with the two different logic levels of 3.3V or 5V to either an Arduino UNO or an Arduino DUE via SPI or I²C communication interface.

Software libraries for the Arduino platform are also provided for quick software applications. it implements the drivers and example codes to use the Sensor shield with the Würth Elektronik eiSos GmbH & Co. KG Sensor EV-Boards listed in chapter Supported products.

On demand there is also a possibility to add a radio module from the Proteus / Thyone family with individualized firmware instead of hosting the sensors with the Arduino. Additional information on the firmware individualisation can be found on the website *here*.

Feel free to check our YouTube channel: *www.youtube.com/user/WuerthElektronik/videos* for video tutorials, hands-ons and webina-rs relating to our products.

2.3 Taking into operation

Sensor shield can either be mounted on Arduino UNO or DUE. For easy orientation of the shield on the Ardiuino board, it follows Arduino board's shape. Match the diagonal bulge one

above the other as shown in Figure 12.

For the proper operation of the Sensor shield, place the jumper (P10) on the correct location based on the Arduino board variant in use (UNO or DUE). Further information can be found in the section 3.1

Connect external power supply to the Arduino board and make sure the VCC is stable and able to reliably supply the module's static and peak current consumption as specified by the Arduino UNO/DUE manual.

The next step is to connect the Arduino board along with the shield to the PC using a USBcable. In that way a COM port can be detected. Check the device manager to acquire the COM port number of the EV board.

Plug in the sensor evaluation boad that you need to take into operation to the appropriate 6-pin connector (CON1-CON4).



Figure 3: Sensor shield and WSEN-EVAL compatibility



Make sure to connect the sensor EVAL board to the correct connector on the Sensor shield according to the operating voltage and the communication interface of the sensor.



Connecting the sensor EVAL board to the wrong connector can cause permanent damage to the sensor.

2.4 Sensor libraries for Arduino

The Arduino libraries for I²C are delivered as a compressed zip-file. All codes related to a sensor supported by the Arduino libraries are placed under a sub directory named after the corresponding sensor. Each sensor directory contains three sub-directories, src, examples and Function_Test. The sub-directory src contain the Arduino platform dependent code. The examples folder contains sample applications that can run on the Arduino and the Function_test folder implements the functions to test the library.



The Arduino libraries are available for download at *https://www.we-online.de/katalog/de/wco/sensors/evaluation_boards_wsen*

2.5 Integration into Arduino IDE

The open-source Arduino IDE makes it easy to write code and upload it to the board. This software can be used with any Arduino board. For further information please refer to the installation guide on the Arduino official website: *https://www.arduino.cc/en/Guide*

The sensor libraries can be added in the Arduino IDE software directly as .ZIP file. Select the required sensor library from your PC.



Figure 4: Add sensor libraries to the Arduino software

Successfully included libraries could be found under 'contributed libraries'.

File Edit Sk	etch Tools Help			
Sketch	Verify/Compile Upload Upload Using Programmer Export compiled Binary	Ctrl+R Ctrl+U Ctrl+Shift+U Ctrl+Alt+S		
oid s	Show Sketch Folder	Ctrl+K		
p	Include Library	>	Δ	
	Add File		Manage Libraries	Ctrl+Shift+I
			Add .ZIP Library	
	- 0 (Arduino libraries	
	p() { your main code her		Bridge	
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			Ethernet	
			Firm ata	
			GSM	
			HID	
			Keyboard	
			LiquidCrystal	
			Mouse	
			Robot Control	
			Robot IR Remote	
			Robot Motor	
			SD	
			SPI	
			Servo	
			SpacebrewYun	
			Stepper	
			TFT	
			Temboo	
			WiFi	
ary adde	d to your libraries. Check "Incl	ude library" men	Wire	
			Contributed libraries	
			WSEN_HIDS	
			WSEN_ITDS	
			WSEN_PADS	
			WSEN TIDS	

Figure 5: Sensor libraries

The sensor libraries also include some examples for quick start. They are available under File>Examples>Examples from custom libraries.

New	Ctrl+N				
Open	Ctrl+O				
Open Recent	>				
Sketchbook	>				
Examples	>	A			
Close	Ctrl+W	01.Basics	>		
Save	Ctrl+S	02.Digital	2		
Save As	Ctrl+Shift+S	03.Analog 04.Communication	1		
Page Setup	Ctrl+Shift+P	04.communication 05.Control	(
Print	Ctrl+P	06.Sensors	(
		07.Display	(
Preferences	Ctrl+Comma	08.Strings	(
Quit	Ctrl+Q	09.USB	Ś		
		10.StarterKit_BasicKit	Ś		
		11.ArduinoISP	Ś		
		Examples for any board			
		Adafruit Circuit Playground	>		
		Bridge	>		
		Ethernet	>		
		Firmata	>		
		LiquidCrystal	>		
		SD	>		
		Servo	>		
		Stepper	>		
		Temboo	>		
		RETIRED	>		
		Examples for Arduino Due (Programming Port)			
		SPI	>		
	_	Wire	>		
ary added to y	our libraries. Ch	Examples from Custom Libraries	_		
		WSEN_HIDS	_	checking_communication	
		-	1		
		WSEN_ITDS	1	continous_mode	reset Test
		WSEN_PADS WSEN_TIDS	1	single_conversion Function_Test	temp_High_Low_To

Figure 6: Examples from the sensor libraries

An example code for the temperature sensor WSEN-TIDS (Part number: 2521020222501) in continuous mode is shown in Figure 7



Temperature sensor evaluation board (part no. 2521020222591) must be connected to 3.3V I^2C pin header.



Make sure to place the Sensor shield jumper on the correct position based on the Arduino board variant in use. Further information is given in the section 3.1

File Edit Sketch Tools Help	
continous_mode §	
#include "WSEN_TIDS.h"	
Sensor_TIDS sensor;	
<pre>//The Output Data Rate in Hz int ODR = 25;</pre>	
<pre>void setup() {</pre>	
Serial.begin(9600);	
<pre>// Initialize the I2C interface sensor.init(TIDS_ADDRESS_I2C_1);</pre>	
<pre>// Set the free run mode with given ODR sensor.set_continous_mode(ODR); }</pre>	
void loop()	
<pre>{ // Read and calculate the temperature int temperature = sensor.read_temperature();</pre>	
<pre>// Print the temperature on the serial monitor Serial.print(temperature); Serial.println(" Celsius");</pre>	
<pre>// Waiting time between measurement int waitMillis = 1000 / ODR;</pre>	
<pre>// Wait before continuing with the next measuremen delay(waitMillis); }</pre>	t
,	

Figure 7: WSEN-TIDS example code (continuous mode)

After the Arduino is connected to the PC through the USB, a connected Arduino device should be visible on a COM port. Select the correct Arduino board, corresponding COM port and upload the code. Once the code is successfully uploaded, the output can be observed on the serial monitor.



Figure 8: Select Arduino board, COM port and upload the code

3 Sensor shield



Figure 9: Evaluation board top view

The evaluation board is provided with an informative silkscreen to ease its use.

3.1 Jumpers

Only one jumper is needed to decide about connecting either an Arduino UNO, switching the multiplexer and level shifter in the accordingly function for 5V logic of the Arduino, or connecting an Arduino DUE, switching the multiplexer and level shifter accordingly for 3.3V logic on the Arduino connector. The following figure shows the jumper position to use an Arduino DUE.



Figure 10: Jumper setting connecting Arduino DUE

3.2 Connectors and pin headers

There are several connectors on the top and bottom side of the sensor shield. They serve to connect the Arduino board, to stack other Sensor shields and to connect sensors via 2.54mm headers or to connect directly the Würth Elektronik eiSos GmbH & Co. KG Sensor EV-Boards.



Figure 11: Connectors and pin headers top side



Figure 12: Connectors and pin headers bottom side

header / connector	Description
P2, P4, P6, P8	Socket to stack up another Sensor shield
CON1	I ² C 5V connector
CON2	I ² C 3.3V connector
CON3	SPI 5V connector
CON4	SPI 3.3V connector
P3, P5, P7, P9	header on bottom side to connect the Arduino board
P1	socket on bottom side to connect the Arduino board

Table 4: Connectors and pin headers



For easy orientation of the shield on the Ardiuino board, it follows Arduino board's shape. Match the diagonal bulge one above the other.

3.2.1 CON1 and CON2 I²C connectors

The pinning of connector CON1 and CON2 fits directly to the sensor evaluation boards mentioned in chapter Supported products. The connector on the shield is a 2.54mm pitch socket to have the possibility to connect any other I²C device with the most commenly used headers.

Pin	Description
1	GND
2	SCL
3	SDA
4	INT1
5	INTO
6	VDD

Table 5: Pinning I²C connector CON1 and CON2



Figure 13: Pinning I²C connector CON1 and CON2

3.2.2 CON3 and CON4 SPI connectors

The pinning of connector CON3 and CON4 fits directly to the sensor evaluation boards mentioned in chapter Supported products. The connector on the shield is a 2.54mm pitch socket to have the possibility to connect any other SPI device with the most commenly used headers.

Pin	Description
1	GND
2	SCLK
3	MOSI
4	CS
5	MISO
6	VDD

Table 6: Pinning SPI connector CON3 and CON4



Figure 14: Pinning SPI connector CON3 and CON4

3.3 Buttons

3.3.1 Reset button

The reset button pulls the reset line low to trigger a reset. It is connected to the Arduino header to trigger a reset of the Arduino processor.

3.4 Function blocks

3.4.1 Power supply

The Sensor Shield is powered from the Arduino board via the socket P5.



Powering the Sensor shield via an USB cable through on board USB connector (not mounted) will switch off the I²C/SPI signal lines between the sensor connectors (CON1-CON4) and the Arduino.

3.4.2 Level shifter

Two level shifters are used to change logic level between 5V logic and 3.3V logic. One IC is used for the SPI lines, the other for the I^2C lines.



Figure 15: Level shifter

3.4.3 Multiplexer

The multiplexers serve the purpose of splitting the 3.3V logic level signals from Arduino DUE towards connector CON2 and CON4 and through the level shifter towards CON1 and CON3. Similarly in case of Arduino UNO, the multiplexer split the 5V logic level signals from the Arduino UNO directly toward CON1 and CON3 and through level shifter towards CON2 and CON4.

By setting the jumper based on the Arduino variant (UNO or DUE) on the three pin header P10 (as already described in section 3.1), the logic level on P1 - P9 can be selected.



Figure 16: Multiplexer

3.4.4 Radio interface with firmware individualization on demand

There is a dedicated place holder for a radio module of the type Proteus or Thyone-I on the Sensor shield. With an individualized Firmware this radio module could independently collect sensor data and send them via radio protocol to a remote station. For this feature no Arduino board is used and the Sensor shield operates stand alone.



Figure 17: Radio module



The modules Proteus-I, Proteus-II, Proteus-III and Thyone-I standard firmware does not support this independent solution.



Please contact your local field sales engineer (FSE) or wireless-sales@we-online.com for further information.

3.4.4.1 Switching SPI and I²C interface to radio module

When connecting an USB cable directly to the Sensor shield, 5V from the USB is used to switch on the IC2 and IC3 multiplexers to connect the interface from the sensor connectors to the radio module. Without USB connection, pull down resistors switch off the multiplexers so that the sensor connectors are connected to the Arduino.



Figure 18: Radio module connection

3.4.4.2 Programming interface

The evaluation board provides a 2×10 pin connector to connect directly a JTAG or SWD flash adapter used for development. Please take care of the correct mounting of the flash adapter (Pin 1 is marked as such). Depending on your flash tool an additional adapter may be required.

The recommended flash adapter is one from the "Segger J-Link" family.

Debugging Interface	 CON6
3.97. UB) [SW02] [SW22] [REST]	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
	GND

Figure 19: Debugging interface of the optional radio module

3.5 Schematic









3.6 Full layout



Figure 21: Assembly diagram







4 Software history

Arduino library software history

Version 1.0.0 "Release"

- First released version of the Arduino library.
- I²C drivers and examples for: WSEN-PADS, WSEN-PDUS, WSEN-HIDS, WSEN-TIDS and WSEN-ITDS

5 Regulatory compliance information

Pursuant to Article 1 (2.) of the EU directive 2014/53/EU, Article 1 (2.) the directive does not apply to equipment listed in Annex I (4.): custom-built evaluation kits destined for professionals to be used solely at research and development facilities for such purposes.

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Relevant regulation requirements are subject to change. Würth Elektronik eiSos does not guarantee the accuracy of the before mentioned information. Directives, technical standards, procedural descriptions and the like may be interpreted differently by the national authorities. Equally, the national laws and restrictions may vary with the country. In case of doubt or uncertainty, we recommend that you consult with the authorities or official certification organizations of the relevant countries. Würth Elektronik eiSos is exempt from any responsibilities or liabilities related to regulatory compliance.

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more than you expect



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