LV8774Q

ON Semiconductor®

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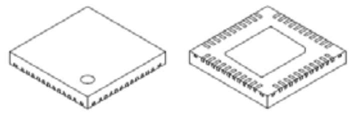
Bi-CDMOS LSI

PWM Constant-Current Control Stepper Motor Driver

Overview

The LV8774 is a 2-channel H-bridge driver IC, and can drive a stepper motor or two brushed DC motors.
A stepper motor driver supports micro-step drive with 1/16-step resolution, and two brushed motor drivers support forward, reverse, brake, and standby functions. It is ideally suited for driving brushed DC motors and stepper motors used in office equipment and amusement applications.



VQFN44L (6x6)

Feature

- Single-channel PWM current control stepper motor driver
  (or two DC motor driver)
- BiCDMOS process IC
- Low on resistance (upper side : 0.3Ω ; lower side : 0.25Ω ;total of upper and lower : 0.55Ω ; Ta = 25°C, I_O = 2A)
- Micro-step mode can be set to Full-step, Half-step, Quarter-step , or 1/16-step
- Excitation step proceeds only by step signal input with stepper motor
- Motor current selectable in four steps
- Output short-circuit protection circuit (selectable from latch-type or auto-reset-type)
- Unusual condition warning output pins
- No control power supply required

Typical Applications

- Stepper/Brush DC Motors , Computing & Peripherals , Industrial
- Printers , Document Scanner , PoE Security Camera , Slot Machine , Vending Machine ,etc

Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VM max	VM , VM1 , VM2	36	V
Output peak current	I_O peak	Tw ≤ 10ms , duty 20% , Per 1ch	2.5	A
Output current	I_O max	Per 1ch	2	A
Logic input voltage	V_{IN}	ATT1, ATT2, EMM, RST/BLK, STEP/DC22, FR/DC21, MD2/DC12, MD1/DC11, DM, OE, ST	-0.3 to +6	V
MONI/EMO input voltage	Vmoni/Vemo		-0.3 to +6	V
Allowable power dissipation	Pd max	*	3.60	W
Operating temperature	Topr		-20 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

*Specified circuit board : 57.0mmx57.0mmx1.6mm, glass epoxy 4-layer board, with backside mounting.

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

ORDERING INFORMATION

See detailed ordering and shipping information on page 28 of this data sheet.

Recommended Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage range	VM	VM , VM1 , VM2	9 to 32	V
Logic input voltage	V_{IN}	ATT1 , ATT2 , EMM , RST/BLK , STEP/DC22 , FR/DC21 , MD2/DC12 , MD1/DC11 , DM , OE , ST	0 to 5.5	V
VREF input voltage range	VREF		0 to 3	V

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Electrical Characteristics at Ta = 25°C, VM = 24V, VREF = 1.5V

Parameter		Symbol	Conditions	Ratings			Unit
				min	typ	max	
Standby mode current drain		IMst	ST = “L” , I(VM)+I(VM1)+I(VM2)		100	400	μA
Current drain		IM	ST = “H”, OE = “L”, with no load I(VM)+I(VM1)+I(VM2)		3.2	5	mA
VREG5 output voltage		Vreg5	I_O = -1mA	4.5	5	5.5	V
Thermal shutdown temperature		TSD	Design guarantee	150	180	200	°C
Thermal hysteresis width		ΔTSD	Design guarantee		40		°C
Motor driver							
Output on resistance		Ronu	I_O = 2A, Upper-side on resistance		0.3	0.4	Ω
		Rond	I_O = 2A, Lower-side on resistance		0.25	0.33	Ω
Output leakage current		$I_O$leak				50	μA
Diode forward voltage		VD	ID = -2A		1.2	1.4	V
Logic pin input current		I_{IN}L	ATT1 , ATT2 , EMM , RST/BLK , STEP/DC22 , FR/DC21 , MD2/DC12 , MD1/DC11 , DM , OE , ST , V_{IN} = 0.8V	4	8	12	μA
		I_{IN}H	ATT1 , ATT2 , EMM , RST/BLK , STEP/DC22 , FR/DC21 , MD2/DC12 , MD1/DC11 , DM , OE , ST , V_{IN} = 5V	30	50	70	μA
Logic input voltage	High	V_{IN}h	ATT1 , ATT2 , EMM , RST/BLK , STEP/DC22 , FR/DC21 , MD2/DC12 , MD1/DC11 , DM , OE , ST	2.0		5.5	V
	Low	V_{IN}l		0		0.8	V
Current setting comparator threshold voltage (current step switching)	1/16 step resolution	Vtdac0_4W	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac1_4W	Step 1 (Initial state+1)	0.291	0.3	0.309	V
		Vtdac2_4W	Step 2 (Initial state+2)	0.285	0.294	0.303	V
		Vtdac3_4W	Step 3 (Initial state+3)	0.279	0.288	0.297	V
		Vtdac4_4W	Step 4 (Initial state+4)	0.267	0.276	0.285	V
		Vtdac5_4W	Step 5 (Initial state+5)	0.255	0.264	0.273	V
		Vtdac6_4W	Step 6 (Initial state+6)	0.240	0.249	0.258	V
		Vtdac7_4W	Step 7 (Initial state+7)	0.222	0.231	0.240	V
		Vtdac8_4W	Step 8 (Initial state+8)	0.201	0.21	0.219	V
		Vtdac9_4W	Step 9 (Initial state+9)	0.180	0.189	0.198	V
		Vtdac10_4W	Step 10 (Initial state+10)	0.157	0.165	0.173	V
		Vtdac11_4W	Step 11 (Initial state+11)	0.134	0.141	0.148	V
		Vtdac12_4W	Step 12 (Initial state+12)	0.107	0.114	0.121	V
		Vtdac13_4W	Step 13 (Initial state+13)	0.080	0.087	0.094	V
		Vtdac14_4W	Step 14 (Initial state+14)	0.053	0.06	0.067	V
		Vtdac15_4W	Step 15 (Initial state+15)	0.023	0.03	0.037	V
	Quarter step resolution	Vtdac0_W	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac4_W	Step 4 (Initial state+1)	0.267	0.276	0.285	V
		Vtdac8_W	Step 8 (Initial state+2)	0.201	0.21	0.219	V
		Vtdac12_W	Step 12 (Initial state+3)	0.107	0.114	0.121	V

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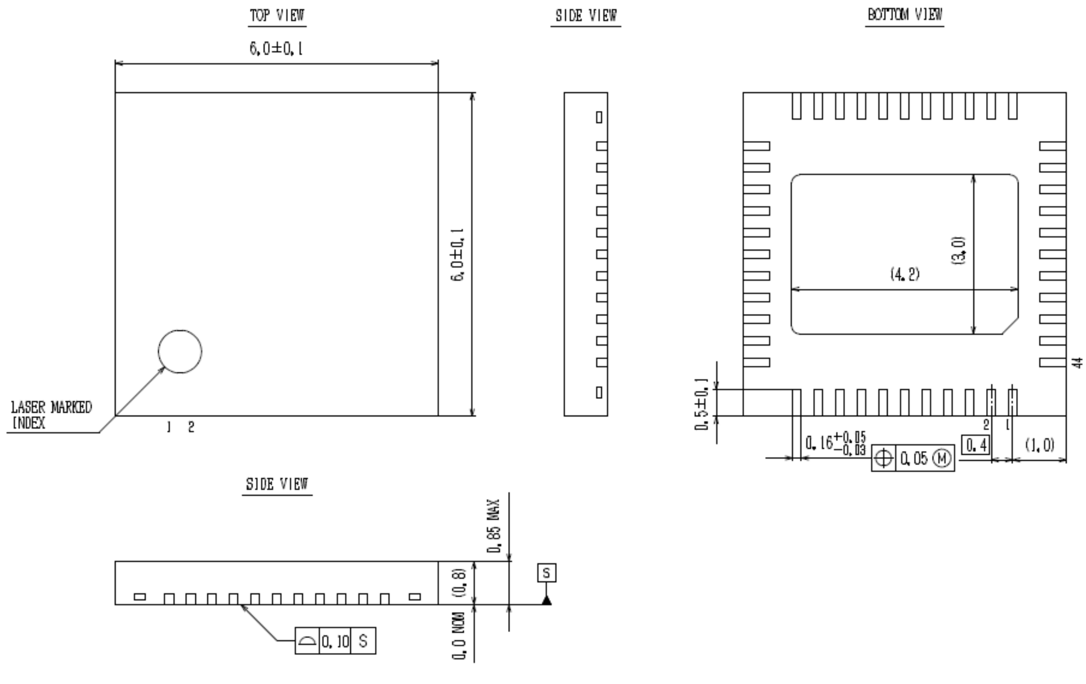
Parameter		Symbol	Conditions	Ratings			Unit
				min	typ	max	
Current setting comparator threshold voltage (current step switching)	Half step resolution	Vtdac0_H	Step 0 (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
		Vtdac8_H	Step 8 (Initial state+1)	0.201	0.21	0.219	V
	Full step resolution	Vtdac8_F	Step 8' (When initialized : channel 1 comparator level)	0.291	0.3	0.309	V
Current setting comparator threshold voltage (current attenuation rate switching)		Vtatt00	ATT1 = L, ATT2 = L	0.291	0.3	0.309	V
		Vtatt01	ATT1 = H, ATT2 = L	0.232	0.24	0.248	V
		Vtatt10	ATT1 = L, ATT2 = H	0.143	0.15	0.157	V
		Vtatt11	ATT1 = H, ATT2 = H	0.053	0.06	0.067	V
Chopping frequency		Fchop	Cchop = 200pF	40	50	60	kHz
CHOP pin charge/discharge current		Ichop		7	10	13	μA
Chopping oscillation circuit threshold voltage		Vtup		0.8	1	1.2	V
		Vtdown		0.4	0.5	0.6	V
VREF pin input current		Iref	VREF = 1.5V	-0.5			μA
MONI pin saturation voltage		Vsatmon	Imoni = 1mA			400	mV
Charge pump							
VG output voltage		VG		28	28.7	29.8	V
Rise time		tONG	VG = 0.1μF , Between CP1-CP2 0.1uF ST="H" →VG=VM+4V		200	500	μS
Oscillator frequency		Fosc		90	125	150	kHz
Output short-circuit protection							
EMO pin saturation voltage		Vsatemo	Iemo = 1mA			400	mV
CEM pin charge current		Icem	Vcem = 0V	7	10	13	μA
CEM pin threshold voltage		Vtcem		0.8	1	1.2	V

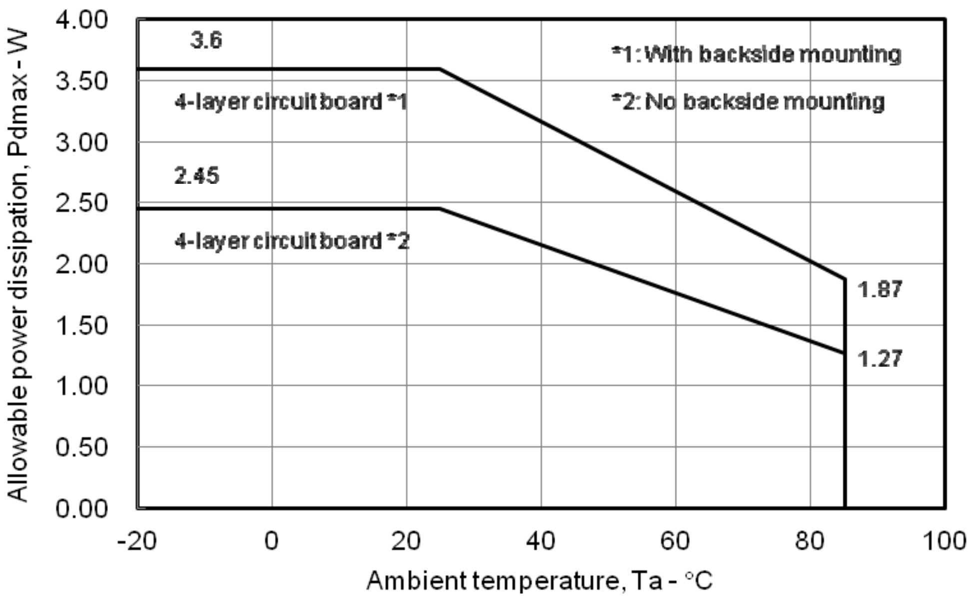
Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

Package Dimensions
unit : mm (typ)

VQFN44L(6mm x 6mm)

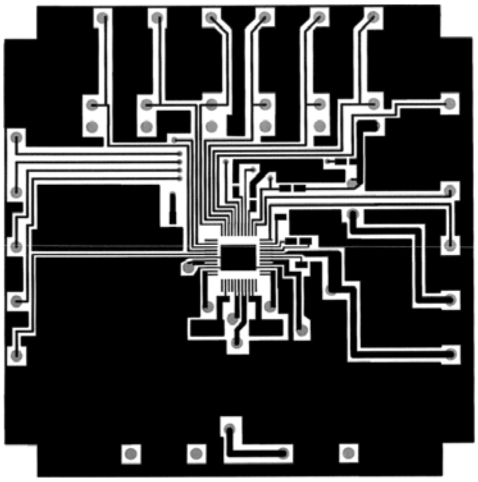


Pdmax-Ta

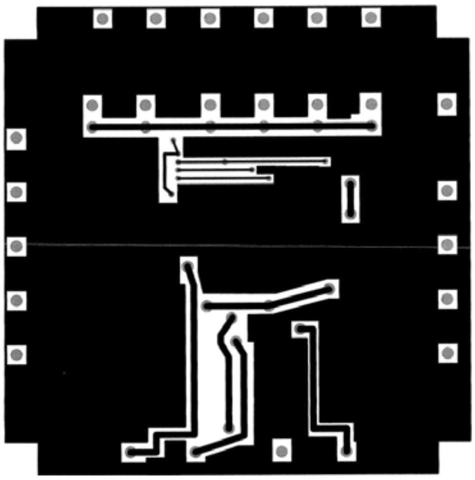


Substrate Specifications (Substrate recommended for operation of LV8774Q)

Size : 57mm × 57mm × 1.6mm (four-layer substrate)
Material : Glass epoxy
Copper wiring density : L1 = 75% / L4 = 85%



L1 : Copper wiring pattern diagram



L4 : Copper wiring pattern diagram

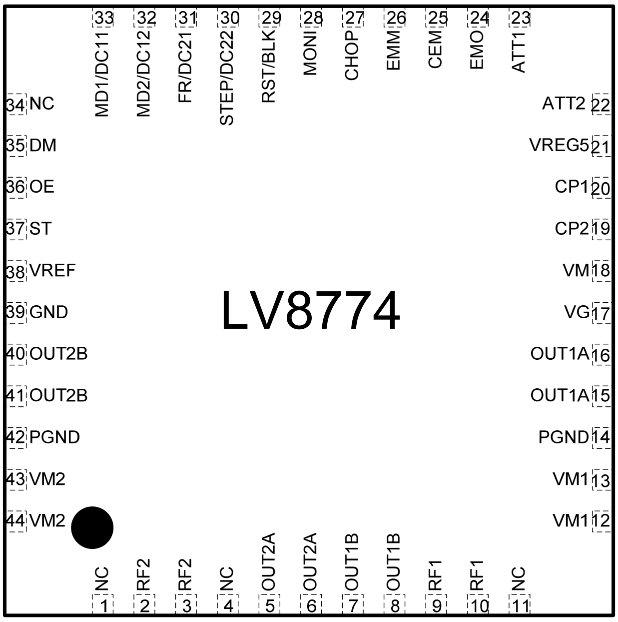
Cautions

1) The data for the case with the back side mounted shows the values when 90% or more of the Exposed Die-Pad is wet.
2) For the set design, employ the derating design with sufficient margin.
Stresses to be derated include the voltage, current, junction temperature, power loss, and mechanical stresses such as vibration, impact, and tension.
Accordingly, the design must ensure these stresses to be as low or small as possible.
The guideline for ordinary derating is shown below :
(1)Maximum value 80% or less for the voltage rating
(2)Maximum value 80% or less for the current rating
(3)Maximum value 80% or less for the temperature rating

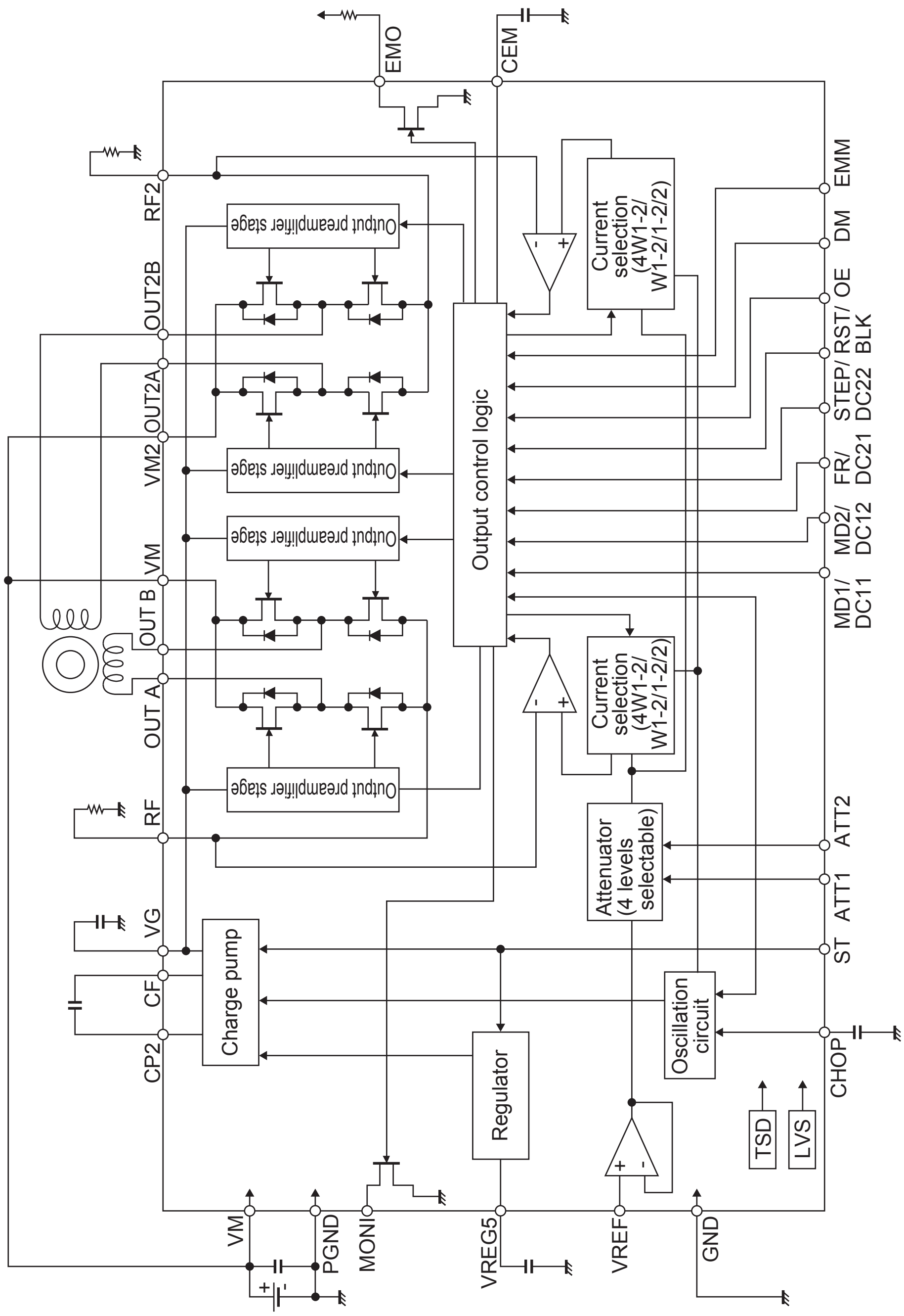
3) After the set design, be sure to verify the design with the actual product.
Confirm the solder joint state and verify also the reliability of solder joint for the Exposed Die-Pad, etc.
Any void or deterioration, if observed in the solder joint of these parts, causes deteriorated thermal conduction, possibly resulting in thermal destruction of IC.

Pin Assignment

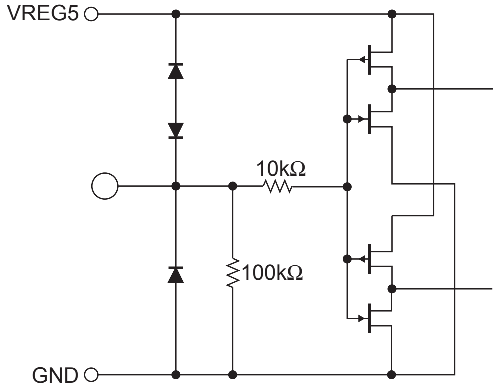
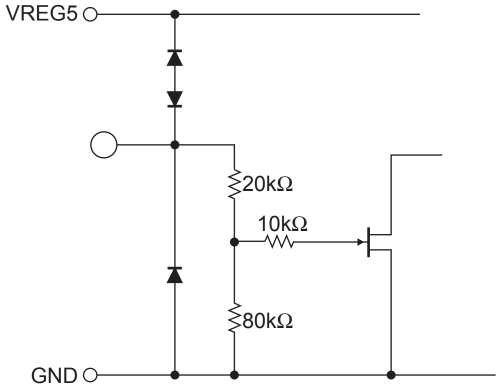
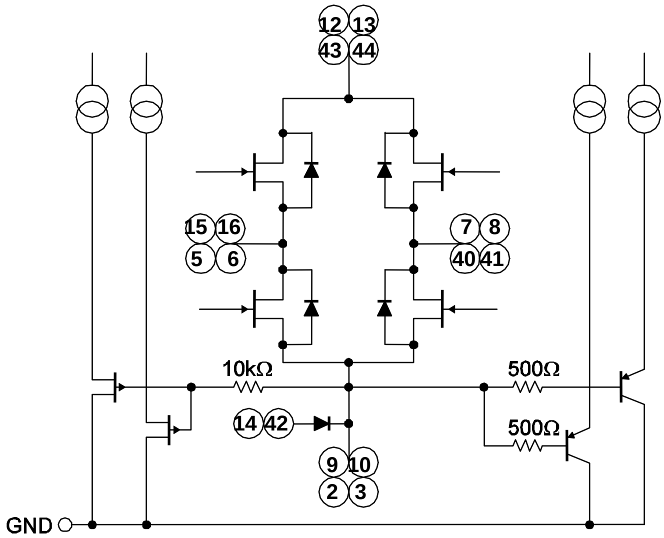
VQFN44L(6mm×6mm)



Block Diagram



Pin Functions

Pin No.	Pin Name	Pin Function	Equivalent Circuit
22	ATT2	Motor holding current switching pin.	
23	ATT1	Motor holding current switching pin.	
26	EMM	Output short-circuit protection mode switching pin.	
29	RST/BLK	RESET input pin (STM) / Blanking time switching pin (DCM).	
30	STEP/DC22	STEP signal input pin (STM) / Channel 2 output control input pin 2 (DCM).	
31	FR/DC21	CW / CCW signal input pin (STM) / Channel 2 output control input pin 1 (DCM).	
32	MD2/DC12	Excitation mode switching pin 2 (STM) / Channel 1 output control input pin 2 (DCM).	
33	MD1/DC11	Excitation mode switching pin 1 (STM) / Channel 1 output control input pin 1 (DCM).	
35	DM	Drive mode (STM/DCM) switching pin.	
36	OE	Output enable signal input pin.	
37	ST	Chip enable pin.	
40, 41	OUT2B	Channel 2 OUTB output pin.	
14, 42	PGND	Power system ground.	
43, 44	VM2	Channel 2 motor power supply connection pin.	
2, 3	RF2	Channel 2 current-sense resistor connection pin.	
5, 6	OUT2A	Channel 2 OUTA output pin.	
7, 8	OUT1B	Channel 1 OUTB output pin.	
9, 10	RF1	Channel 1 current-sense resistor connection pin.	
12, 13	VM1	Channel 1 motor power supply pin.	
15, 16	OUT1A	Channel 1 OUTA output pin.	

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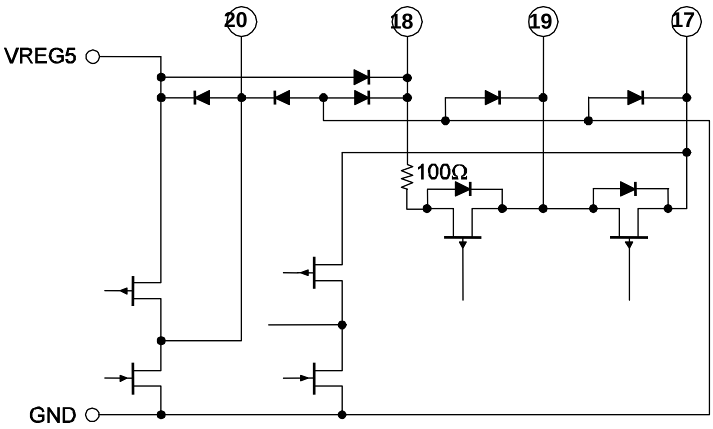
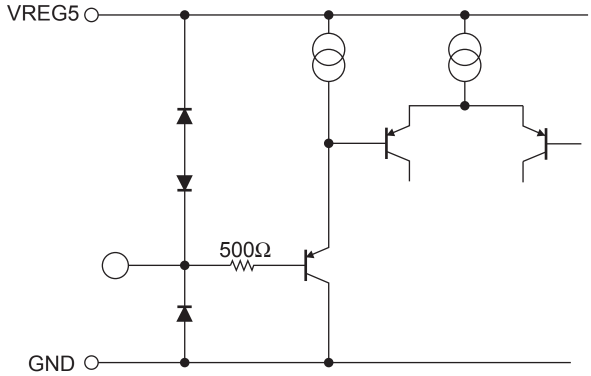
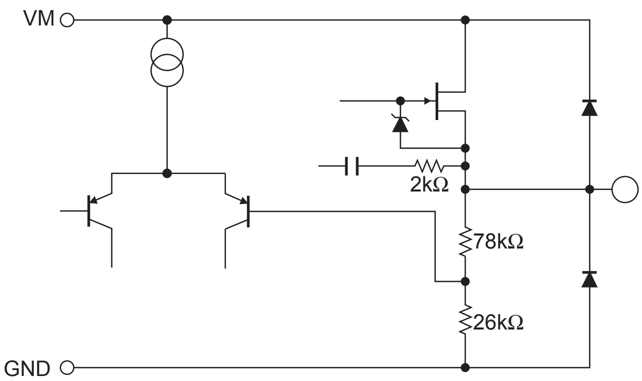
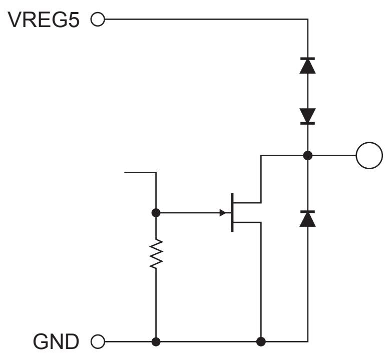
Pin No.	Pin Name	Pin Function	Equivalent Circuit
17 18 19 20	VG VM CP2 CP1	Charge pump capacitor connection pin. Motor power supply connection pin. Charge pump capacitor connection pin. Charge pump capacitor connection pin.	
38	VREF	Constant current control reference voltage input pin.	
21	VREG5	Internal power supply capacitor connection pin.	
24 28	EMO MONI	Output short-circuit state warning output pin. Position detection monitor pin.	

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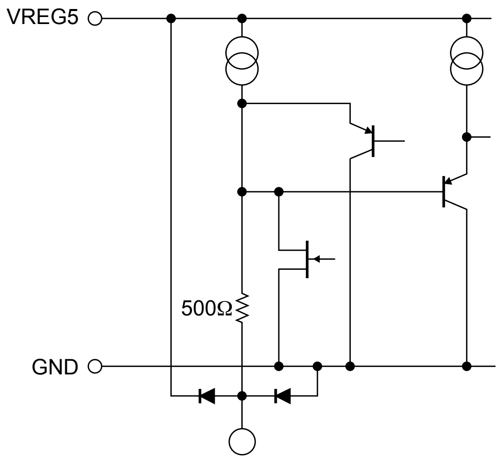
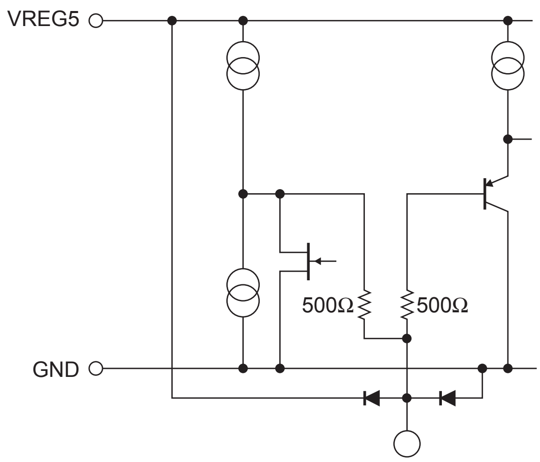
Pin No.	Pin Name	Pin Function	Equivalent Circuit
25	CEM	Pin to connect the output short-circuit state detection time setting capacitor.	
27	CHOP	Chopping frequency setting capacitor connection pin.	
39	GND	Ground.	
1,4,11, 34	NC	No Connection (No internal connection to the IC)	
Exposed-Pad		Exposed-Pad connects signal GND or floating.*	

*Recommendation is to connect Exposed-pad to signal GND.

Since IC may generate heat when using it by floating, be careful of a thermal design enough.

Description of operation

1. Input Pin Function

Each input terminal has the function to prevent the flow of the current from an input to a power supply. Therefore, Even if a power supply (VM) is turned off in the state that applied voltage to an input terminal, the electric current does not flow into the power supply.

1-1) Chip enable function

This IC is switched between standby and operating mode by setting the ST pin. In standby mode, the IC is set to power-save mode and all logic is reset. In addition, the internal regulator circuit and charge pump circuit do not operate in standby mode.

ST	Mode	Internal regulator	Charge pump
Low or Open	Standby mode	Standby	Standby
High	Operating mode	Operating	Operating

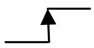
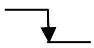
1-2) Drive mode switching pin function

The IC drive mode is switched by setting the DM pin. In STM mode, stepper motor channel 1 can be controlled by the CLK-IN input. In DCM mode, DC motor channel 2 or stepper motor channel 1 can be controlled by parallel input. Stepper motor control using parallel input is Full-step or Half-step full torque.

DM	Drive mode	Application
Low or Open	STM mode	Stepper motor channel 1 (CLK-IN)
High	DCM mode	DC motor channel 2 or stepper motor channel 1 (parallel)

2. STM mode (DM = Low or Open)

2-1) STEP pin function

Input		Operating mode
ST	STP	
Low	*	Standby mode
High		Excitation step proceeds
High		Excitation step is kept

2-2) Excitation mode setting function

MD1	MD2	Micro-step resolution (Excitation mode)	Initial position	
			Channel 1	Channel 2
Low	Low	Full step(2 phase excitation)	100%	-100%
High	Low	Half step(1-2 phase excitation)	100%	0%
Low	High	Quarter step (W1-2 phase excitation)	100%	0%
High	High	1/16 step(4W1-2 phase excitation)	100%	0%

This is the initial position of each excitation mode in the initial state after power-on and when the counter is reset.

2-3) Position detection monitoring function

The MONI position detection monitoring pin is of an open drain type.
When the excitation position is in the initial position, the MONI output is placed in the ON state.
(Refer to "2-12.Examples of current waveforms in each micro-step mode.")

2-4) Setting constant-current control reference current

This IC is designed to automatically exercise PWM constant-current chopping control for the motor current by setting the output current. Based on the voltage input to the VREF pin and the resistance connected between RF and GND, the output current that is subject to the constant-current control is set using the calculation formula below :

I_{OUT} = (VREF/5)/RF resistance

* The above setting is the output current at 100% of each excitation mode.

The voltage input to the VREF pin can be switched to four-step settings depending on the statuses of the two inputs, ATT1 and ATT2. This is effective for reducing power consumption when motor holding current is supplied.

Attenuation function for VREF input voltage

ATT1	ATT2	Current setting reference voltage attenuation ratio
Low	Low	100%
High	Low	80%
Low	High	50%
High	High	20%

The formula used to calculate the output current when using the function for attenuating the VREF input voltage is given below.

I_{OUT} = (VREF/5) × (attenuation ratio)/RF resistance

Example : At VREF of 1.5V, a reference voltage setting of 100% [(ATT1, ATT2) = (L, L)] and an RF resistance of 0.3Ω, the output current is set as shown below.

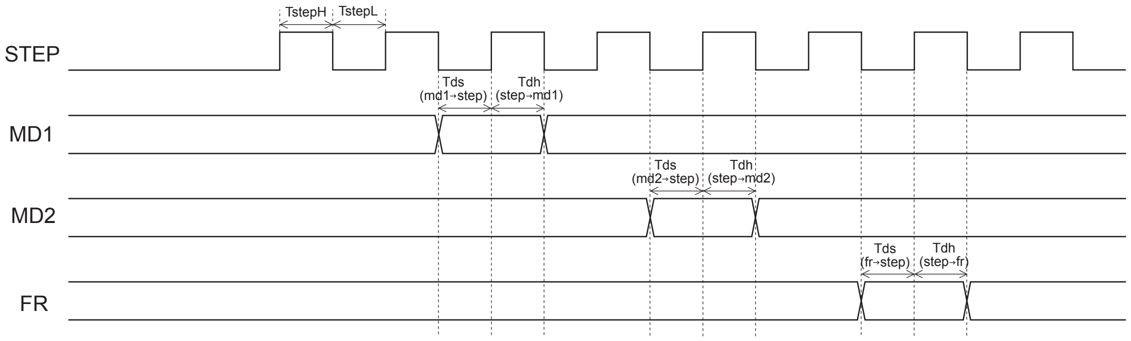
I_{OUT} = 1.5V/5 × 100%/0.3Ω = 1.0A

If, in this state, (ATT1, ATT2) is set to (H, H), IOUT will be as follows :

I_{OUT} = 1.0A × 20% = 200mA

In this way, the output current is attenuated when the motor holding current is supplied so that power can be conserved.

2-5) Input Timing



TstepH/TstepL : Clock H/L pulse width (min 500ns)
Tds : Data set-up time (min 500ns)
Tdh : Data hold time (min 500ns)

2-6) Blanking period

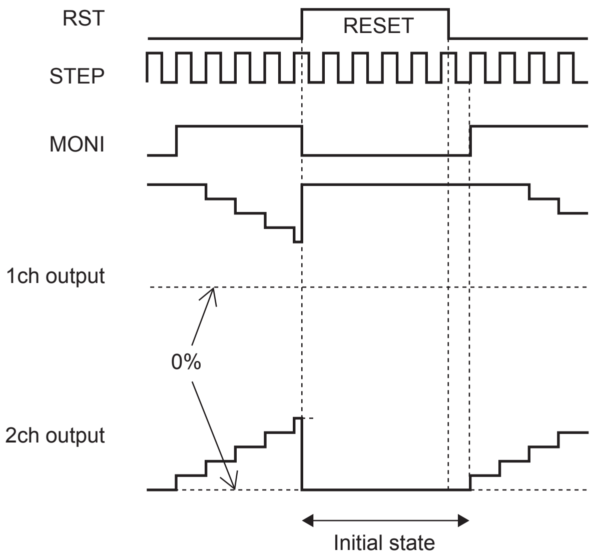
During normal operation switching transient noise from the parasitic diode may flow to the current sensing resistance, resulting in erroneous detection. To prevent this erroneous detection, a blanking period is provided to prevent the noise from being received.

In the stepper motor driver mode (DM = Low or Open) of this IC, the blanking time is fixed at approximately 1μs.

In the DC motor driver mode (DM = High), the blanking time can be switched to one of two levels using the RST/BLK pin. (Refer to "Blanking time switching function.")

2-7) Reset function

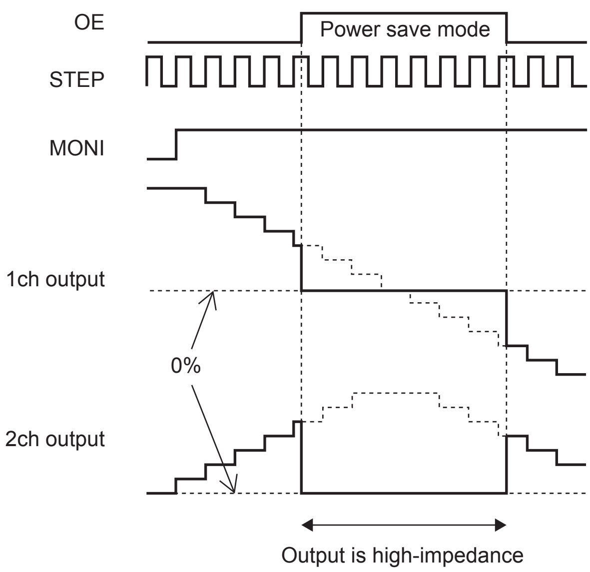
RST	Operating mode
Low	Normal operation
High	Reset state



When the RST pin is set to High, the excitation position of the output is forcibly set to the initial state, and the MONI output is placed in the ON state. When RST is then set to Low, the excitation position is advanced by the next STEP input.

2-8) Output enable function

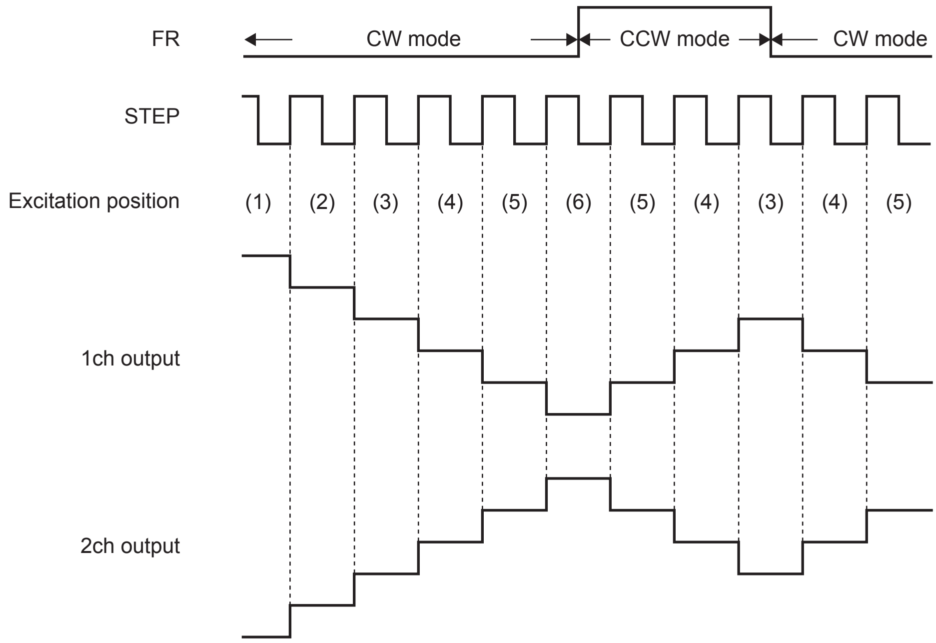
OE	Operating mode
Low	Output ON
High	Output OFF



When the OE pin is set High, the output is forced OFF and goes to high impedance.
The internal logic circuits remain operating, and the excitation position proceeds when the STEP signal is inputted.

2-9) Forward/reverse switching function

FR	Operating mode
Low	Clockwise (CW)
High	Counter-clockwise (CCW)



The internal D/A converter proceeds by one bit at the rising edge of the input STEP pulse.
In addition, CW and CCW mode are switched by setting the FR pin.
In CW mode, the channel 2 current phase is delayed by 90° relative to the channel 1 current.
In CCW mode, the channel 2 current phase is advanced by 90° relative to the channel 1 current.

2-10) Chopping frequency setting

For constant-current control, this IC performs chopping operations at the frequency determined by the capacitor (Cchop) connected between the CHOP pin and GND.
The chopping frequency is set as shown below by the capacitor (Cchop) connected between the CHOP pin and GND.

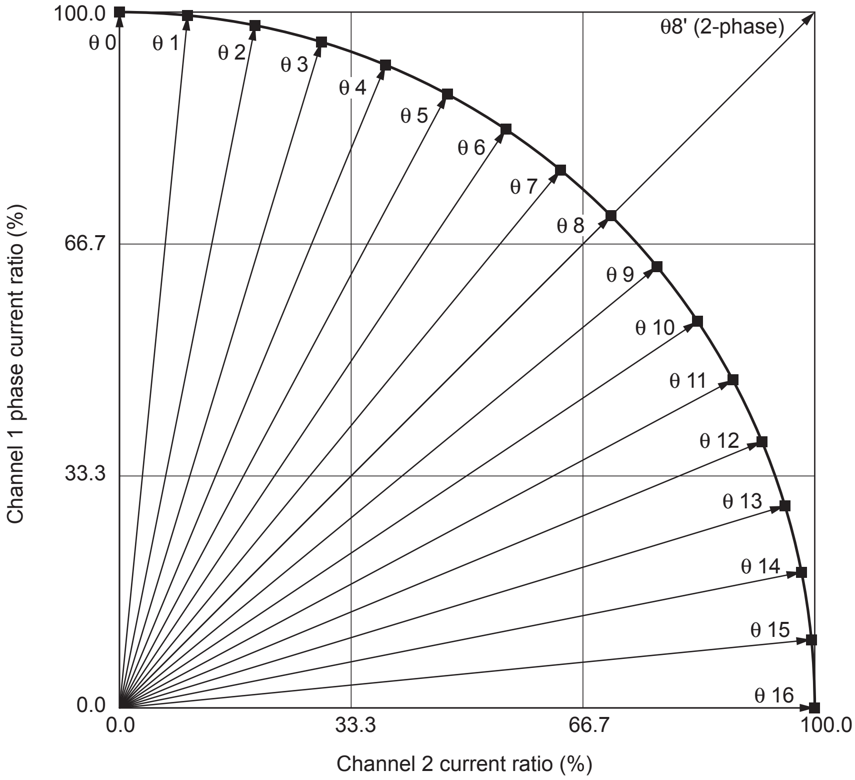
Fchop = Ichop/ (Cchop × Vtchop × 2) (Hz)

Ichop : Capacitor charge/discharge current, typ 10μA
Vtchop : Charge/discharge hysteresis voltage (Vtup-Vtdown), typ 0.5V

For instance, when Cchop is 200pF, the chopping frequency will be as follows :

Fchop = 10μA/ (200pF × 0.5V × 2) = 50kHz

2-11) Output current vector locus (one step is normalized to 90 degrees)

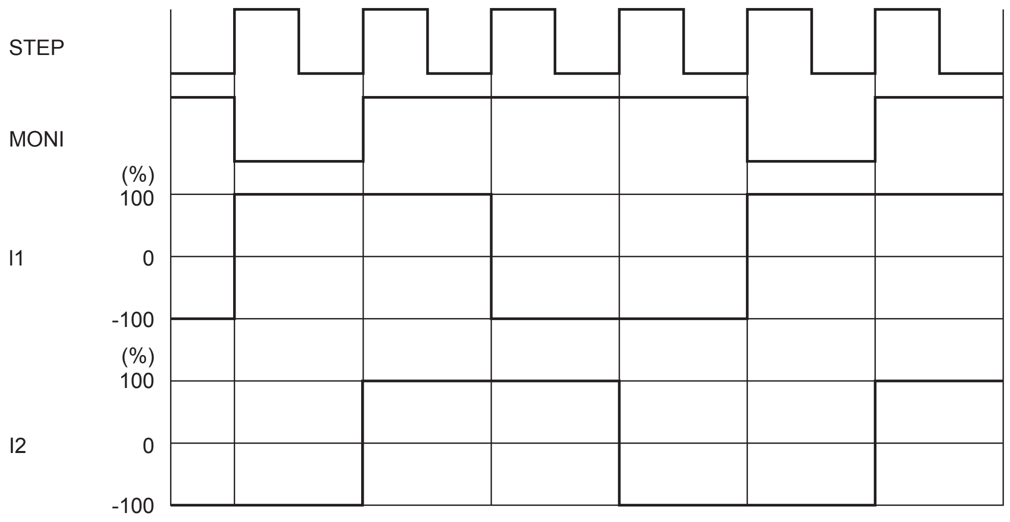


Setting current ration in each micro-step mode

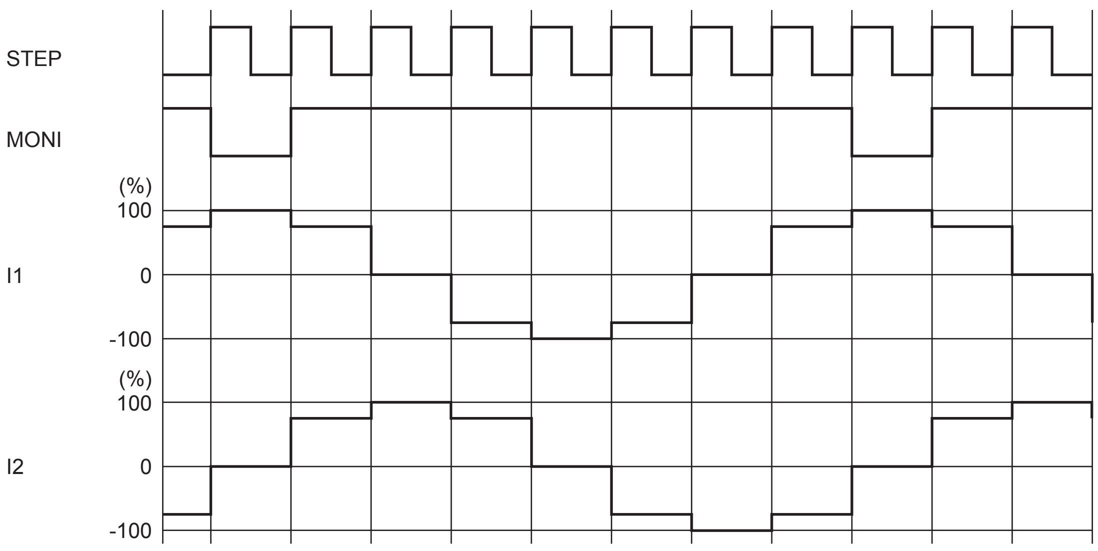
STEP	1/16 step (%)		Quarter step (%)		Half step (%)		Full step (%)	
	Channel 1	Channel 2	Channel 1	Channel 2	Channel 1	Channel 2	Channel 1	Channel 2
θ0	100	0	100	0	100	0		
θ1	100	10						
θ2	98	20						
θ3	96	29						
θ4	92	38	92	38				
θ5	88	47						
θ6	83	55						
θ7	77	63						
θ8	70	70	70	70	70	70	100	100
θ9	63	77						
θ10	55	83						
θ11	47	88						
θ12	38	92	38	92				
θ13	29	96						
θ14	20	98						
θ15	10	100						
θ16	0	100	0	100	0	100		

2-12) Examples of current waveforms in each micro-step mode

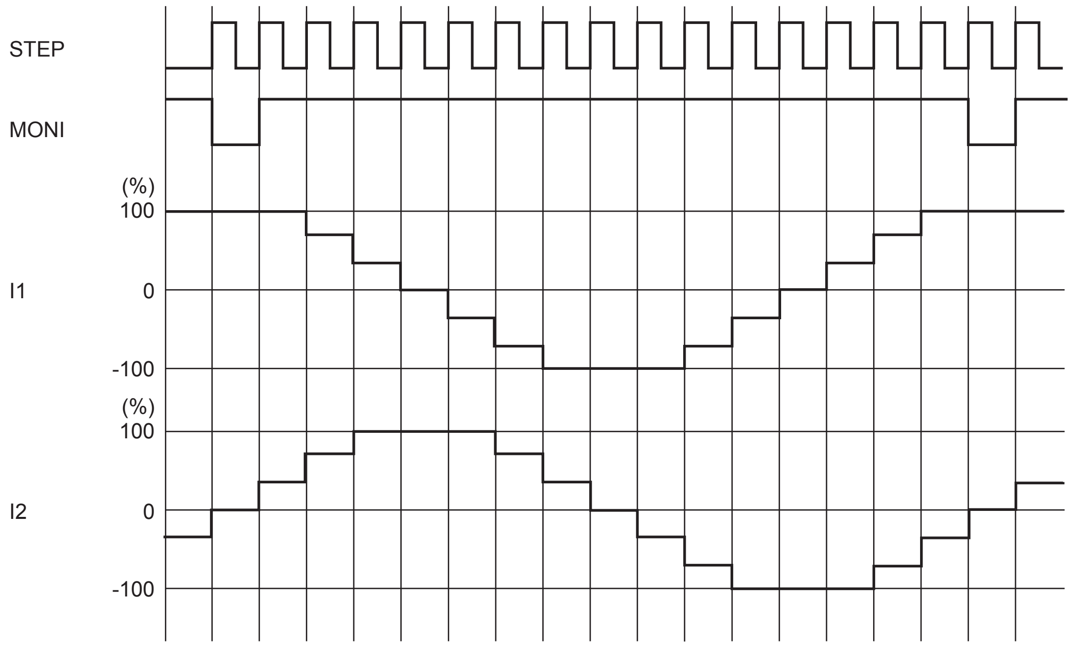
Full step (CW mode)



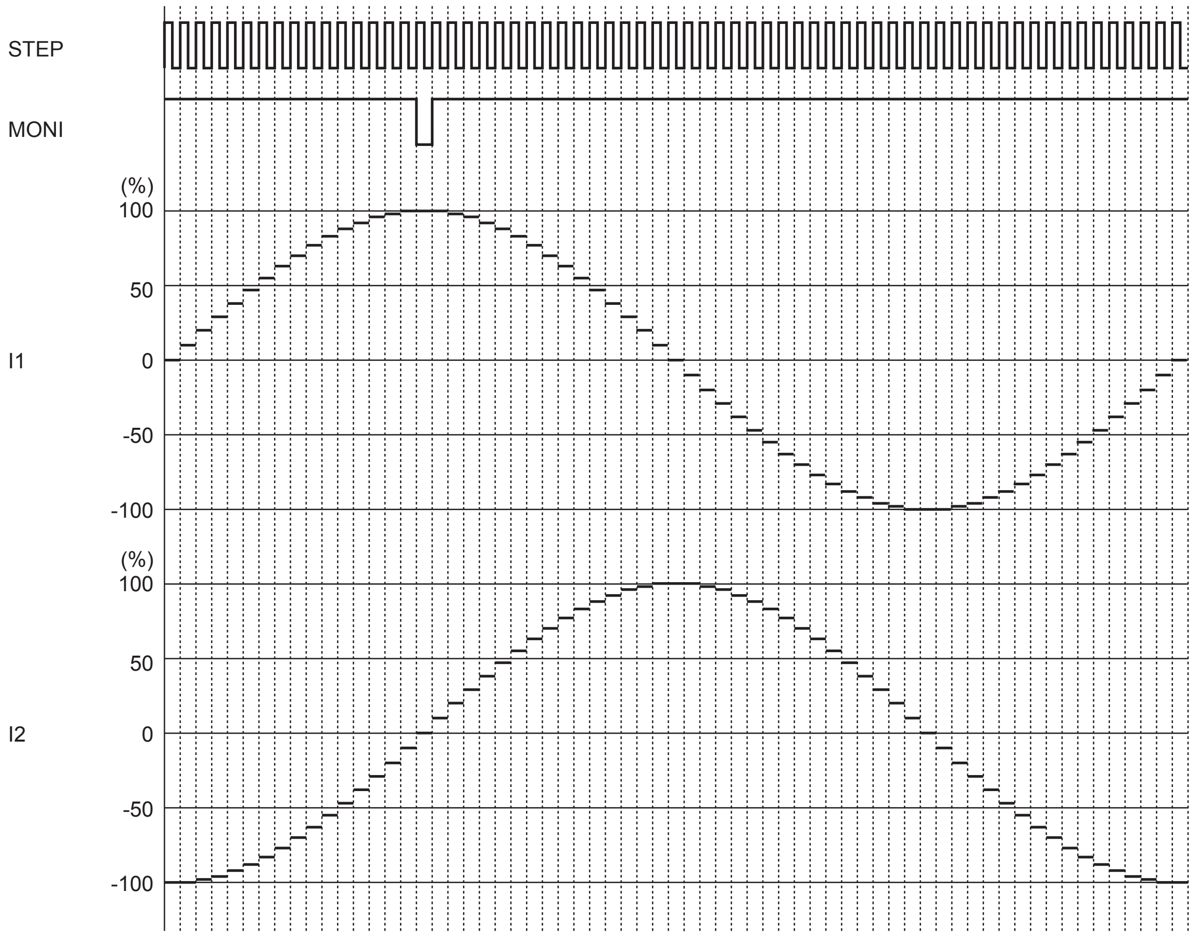
Half step (CW mode)



Quarter step (CW mode)

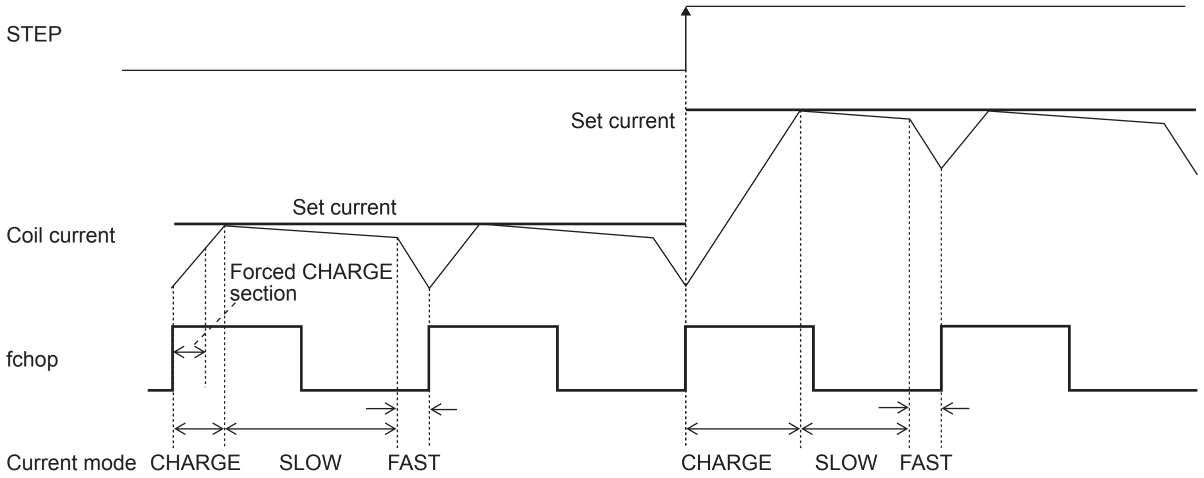


1/16 step (CW mode)

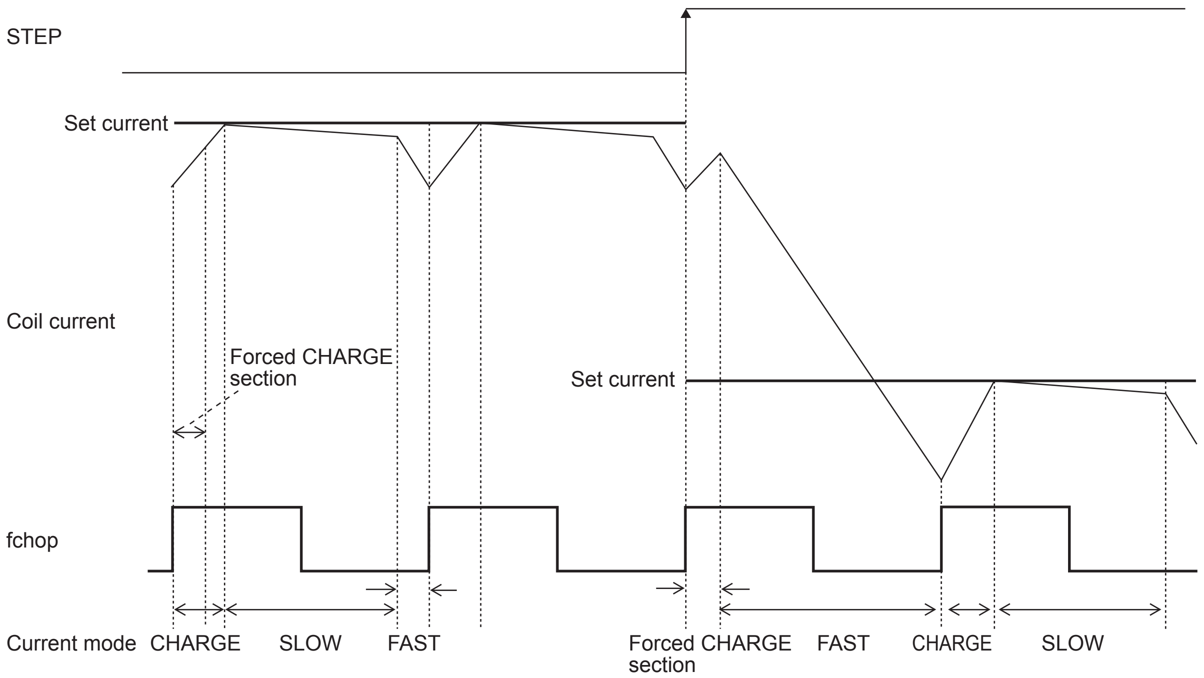


2-13) Current control operation specification

(Sine wave increasing direction)



(Sine wave decreasing direction)



For current mode control, the operation sequence is as described below :

- At rise of chopping frequency, the CHARGE mode begins. (During blanking time the CHARGE mode is forced regardless of the magnitude of the coil current (ICOIL) and set current (IREF).)
- The coil current (ICOIL) and set current (IREF) are compared in this blanking time.

  When (ICOIL < IREF)

  the winding is charged until ICOIL ≥ IREF, then changed to the SLOW DECAY mode, and finally to the FAST DECAY mode for approximately 1μs.

  When (ICOIL ≥ IREF)

  the FAST DECAY mode begins immediately. The coil current is attenuated in the FAST DECAY for one cycle.

Above operations are repeated. Normally, the SLOW (+FAST) DECAY mode continues in the sine wave increasing direction, then entering the FAST DECAY mode till the current is attenuated to the set level, followed by the SLOW DECAY mode.

3. DCM Mode (DM=High)

3-1) DCM mode output control logic

Parallel input		Output		Mode
DC11 (21)	DC12 (22)	OUT1 (2) A	OUT1 (2) B	
Low	Low	OFF	OFF	Standby
High	Low	High	Low	CW (Forward)
Low	High	Low	High	CCW (Reverse)
High	High	Low	Low	Brake

3-2) Blanking time switching function

BLK	Blanking time
Low	2μs
High	3μs

3-3) Output enable function

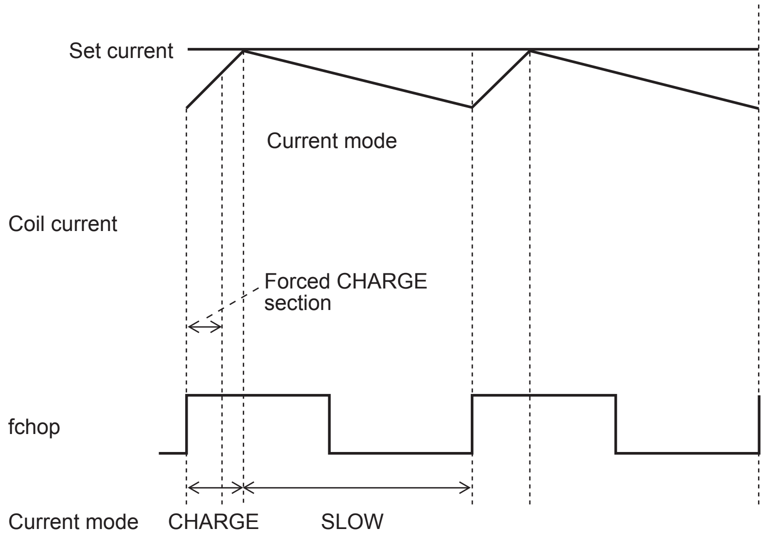
OE	Operating mode
Low	Output ON
High	Output OFF

When the OE pin is set High, the output is forced OFF and goes to high impedance. When the OE pin is set Low, output conforms to the control logic.

3-4) Current limit reference voltage setting function

By setting a current limit, this IC automatically exercises shorted braking control to ensure that the motor current cannot exceed this limit.

(Current limit control time chart)



The limit current is set as calculated on the basis of the voltage input to the VREF pin and the resistance between the RF pin and GND using the formula given below.

Ilimit = (VREF/5) /RF resistance

The voltage applied to the VREF pin can be switched to any of the four setting levels depending on the statuses of the two inputs, ATT1 and ATT2.

Function for attenuating VREF input voltage

ATT1	ATT2	Current setting reference voltage attenuation ratio
Low	Low	100%
High	Low	80%
Low	High	50%
High	High	20%

The formula used to calculate the output current when using the function for attenuating the VREF input voltage is given below.

Ilimit = (VREF/5) × (attenuation ratio) /RF resistance

Example : At VREF of 1.5V, a reference voltage setting of 100% [(ATT1, ATT2) = (L, L)] and an RF resistance of 0.3Ω, the output current is set as shown below.

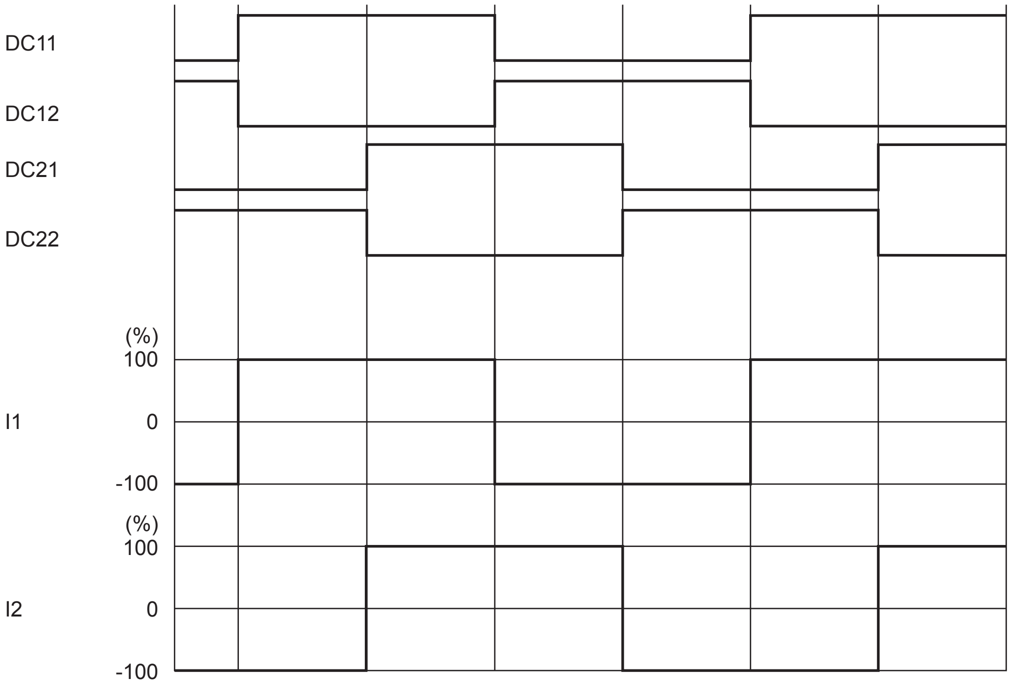
Ilimit = 1.5V/5 × 100%/0.3Ω = 1.0A

If, in this state, (ATT1, ATT2) has been set to (H, H), Ilimit will be as follows :

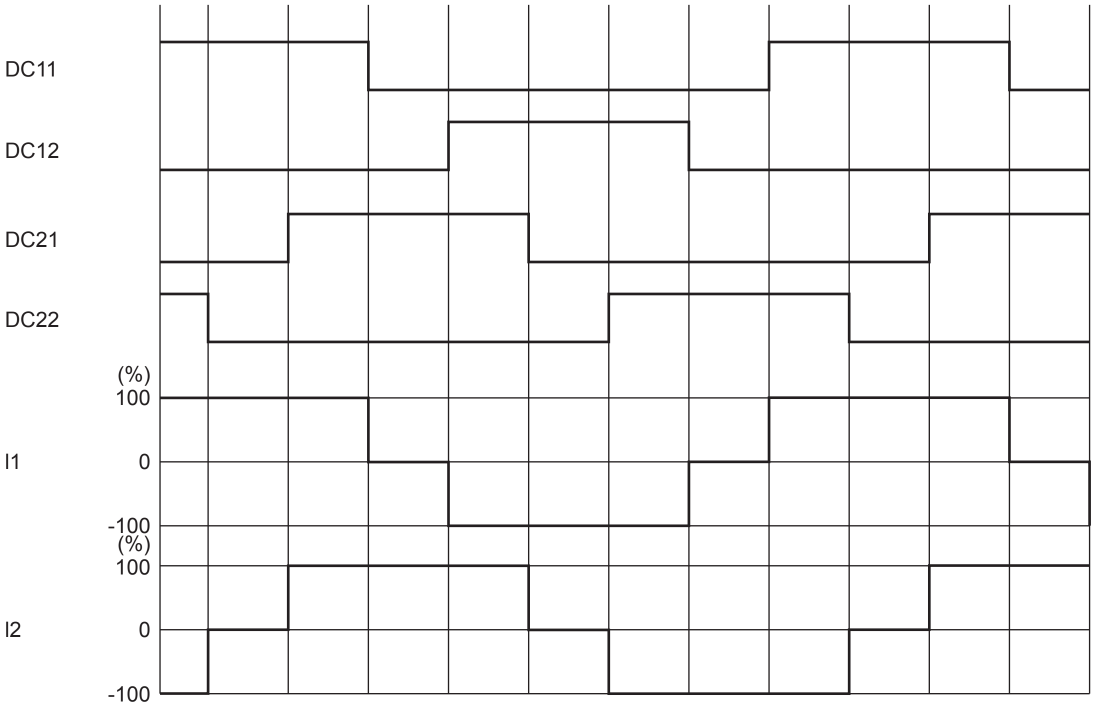
Ilimit = 1.0A × 20% = 200mA

3-5) Examples of current waveform in each micro-step mode with stepper motor parallel input control

Full step (CW mode)



Half step full torque (CW mode)



4. Output short-circuit protection function

This IC incorporates an output short-circuit protection circuit that, when the output has been shorted by an event such as shorting to power or shorting to ground, sets the output to the standby mode and turns on the warning output in order to prevent the IC from being damaged. In the stepper motor driver (STM) mode (DM = Low), this function sets the output to the standby mode for both channels by detecting the short-circuiting in one of the channels. In the DC motor driver mode (DM = High), channels 1 and 2 operate independently. (Even if the output of channel 1 has been short-circuited, channel 2 will operate normally.)

4-1) Output short-circuit protection mode switching function

Output short-circuit protection mode of IC can be switched by the setting of EMM pin.

EMM	State
Low or Open	Latch method
High	Auto reset method

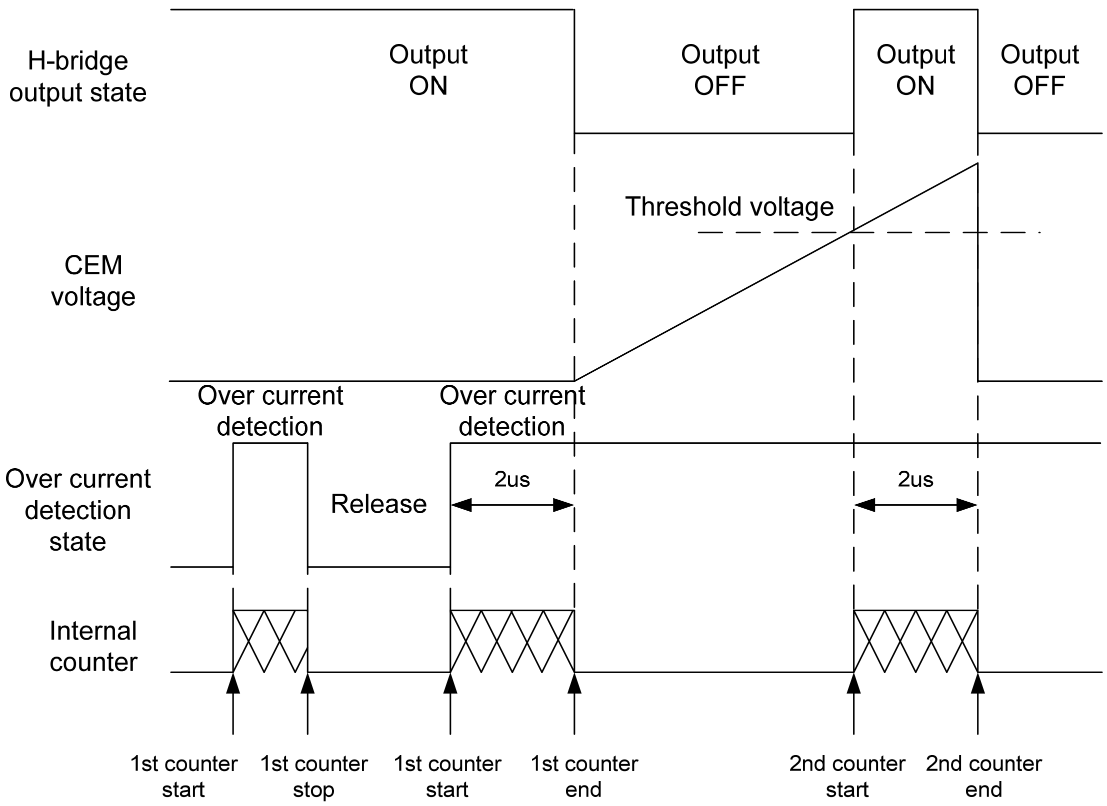
4-2) Latch type

In the latch mode, when the output current exceeds the detection current level, the output is turned OFF, and this state is held.

The detection of the output short-circuited state by the IC causes the output short-circuit protection circuit to be activated.

When the short-circuited state continues for the period of time set using the internal timer (approximately 2μs), the output in which the short-circuiting has been detected is first set to OFF. After this, the output is set to ON again as soon as the timer latch time (Tcem) described later has been exceeded, and if the short-circuited state is still detected, all the outputs of the channel concerned are switched to the standby mode, and this state is held.

This state is released by setting ST to low.



4-3) Auto reset type

In the automatic reset mode, when the output current exceeds the detection current level, the output waveform changes to the switching waveform.

As with the latch system, when the output short-circuited state is detected, the short-circuit protection circuit is activated. When the operation of the short-circuit detection circuit exceeds the timer latch time (Tcem) described later, the output is changed over to the standby mode and is reset to the ON mode again in 2ms (typ). In this event, if the over current mode still continues, the switching mode described above is repeated until the over current mode is canceled.

4-4) Unusual condition warning output pins (EMO, MONI)

The LV8774 is provided with the EMO pin which notifies the CPU if the protection circuit detects an unusual condition of the IC. This pin is of the open-drain output type and when an unusual condition is detected, the EMO output is placed in the ON (EMO = Low) state.
In the DC motor driver mode (DM = High), the MONI pin also functions as a warning output pin.
The functions of the EMO pin and MONI pin change function as shown below depending on the state of the DM pin.

When the DM is low (STM mode) :
EMO : Unusual condition warning output pin
MONI : Excitation initial position detection monitoring

When the DM is high (DCM) mode) :
EMO : Channel 1 warning output pin
MONI : Channel 2 warning output pin

The EMO (MONI) pin is also placed in the ON state when one of the following conditions occurs.

1. Shorting-to-power, shorting-to-ground, or shorting-to-load occurs at the output pin and the output short-circuit protection circuit is activated.
2. The IC junction temperature rises and the thermal protection circuit is activated.

Unusual condition	DM = L (STM mode)		DM = H (DCM mode)	
	EMO	MONI	EMO	MONI
Channel 1 short-circuit detected	ON	-	ON	-
Channel 2 short-circuit detected	ON	-	-	ON
Overheating condition detected	ON	-	ON	ON

4-5) Timer latch time (Tcem)

The time taken for the output to be set to OFF when the output has been short-circuited can be set using capacitor Ccem, connected between the CEM pin and GND. The value of capacitor Ccem is determined by the formula given below.

Timer latch : Tcem   Tcem ≈ Ccem × Vtcem/Icem [sec]
Vtcem : Comparator threshold voltage, typ 1V
Icem : CEM pin charge current, typ 10μA

5. Thermal shutdown function

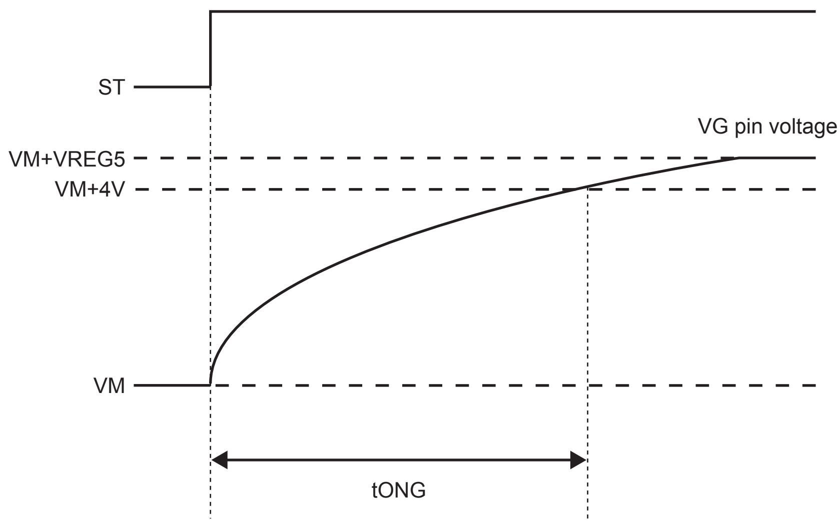
The thermal shutdown circuit is included, and the output is turned off when junction temperature Tj exceeds 180°C and the abnormal state warning output is turned on at the same time.
When the temperature falls below the hysteresis level, output is driven again (automatic restoration)
The thermal shutdown circuit doesn’t guarantee protection of the set and the destruction prevention of IC, as it operates at a temperature that is higher than the rating (Tjmax=150°C) of the junction temperature

TTSD = 180°C (typ)
ΔTSD = 40°C (typ)

6. Charge Pump Circuit

When the ST pin is set High, the charge pump circuit operates and the VG pin voltage is boosted from the VM voltage to the VM + VREG5 voltage.

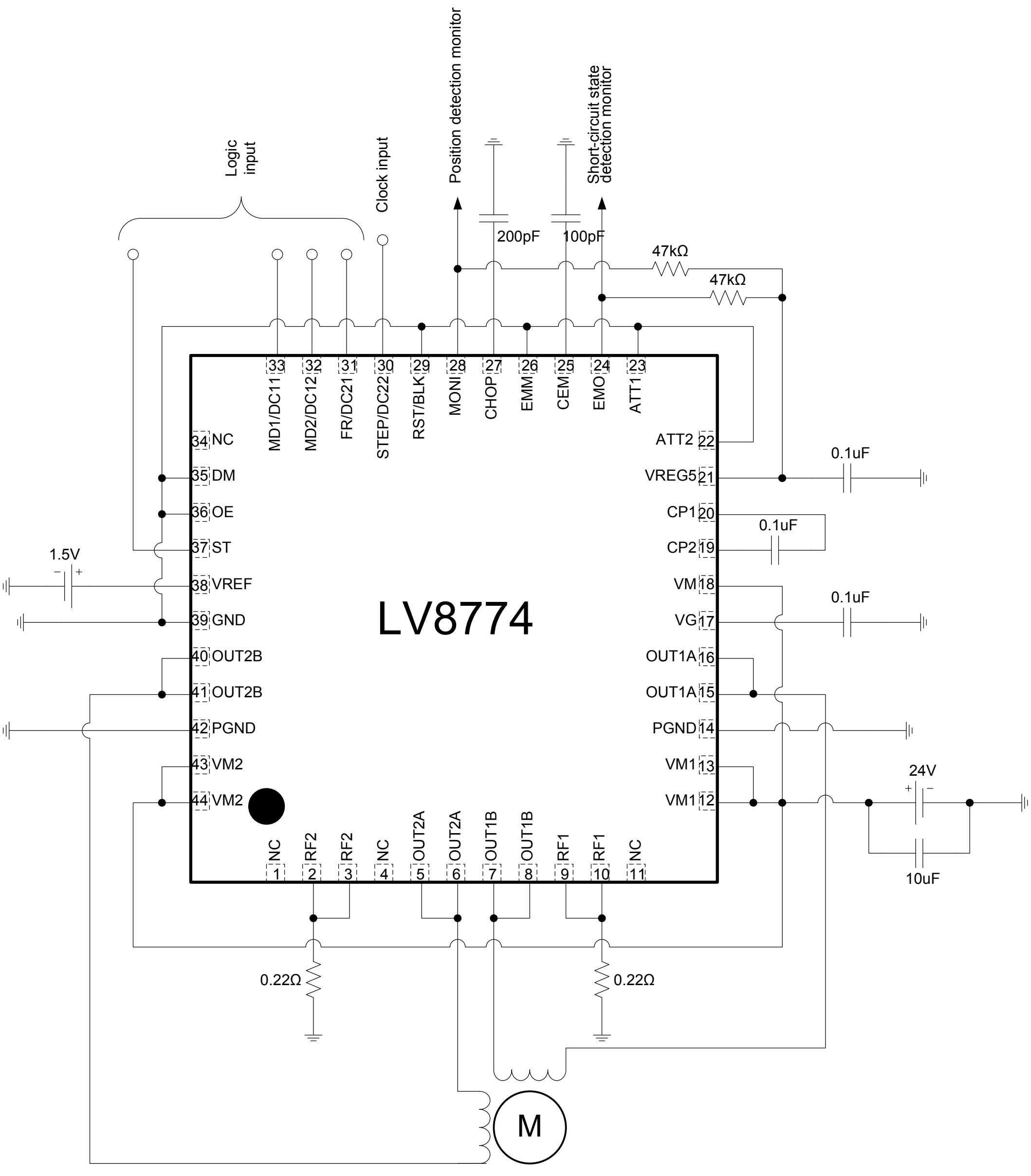
If the VG pin voltage is not boosted to VM+4V or more, the output pin cannot be turned on. Therefore it is recommended that the drive of motor is started after the time has passed tONG or more.



VG Pin Voltage Schematic View

Application Circuit Example

• Stepper motor driver circuit (DM = Low)



The formulae for setting the constants in the example of the application circuit above are as follows :

Constant current (100%) setting

When VREF = 1.5V

I_{OUT} = VREF/5/RF resistance

= 1.5V/5/0.22Ω = 1.36A

Chopping frequency setting

Fchop = Ichop/ (Cchop × Vtchop × 2)

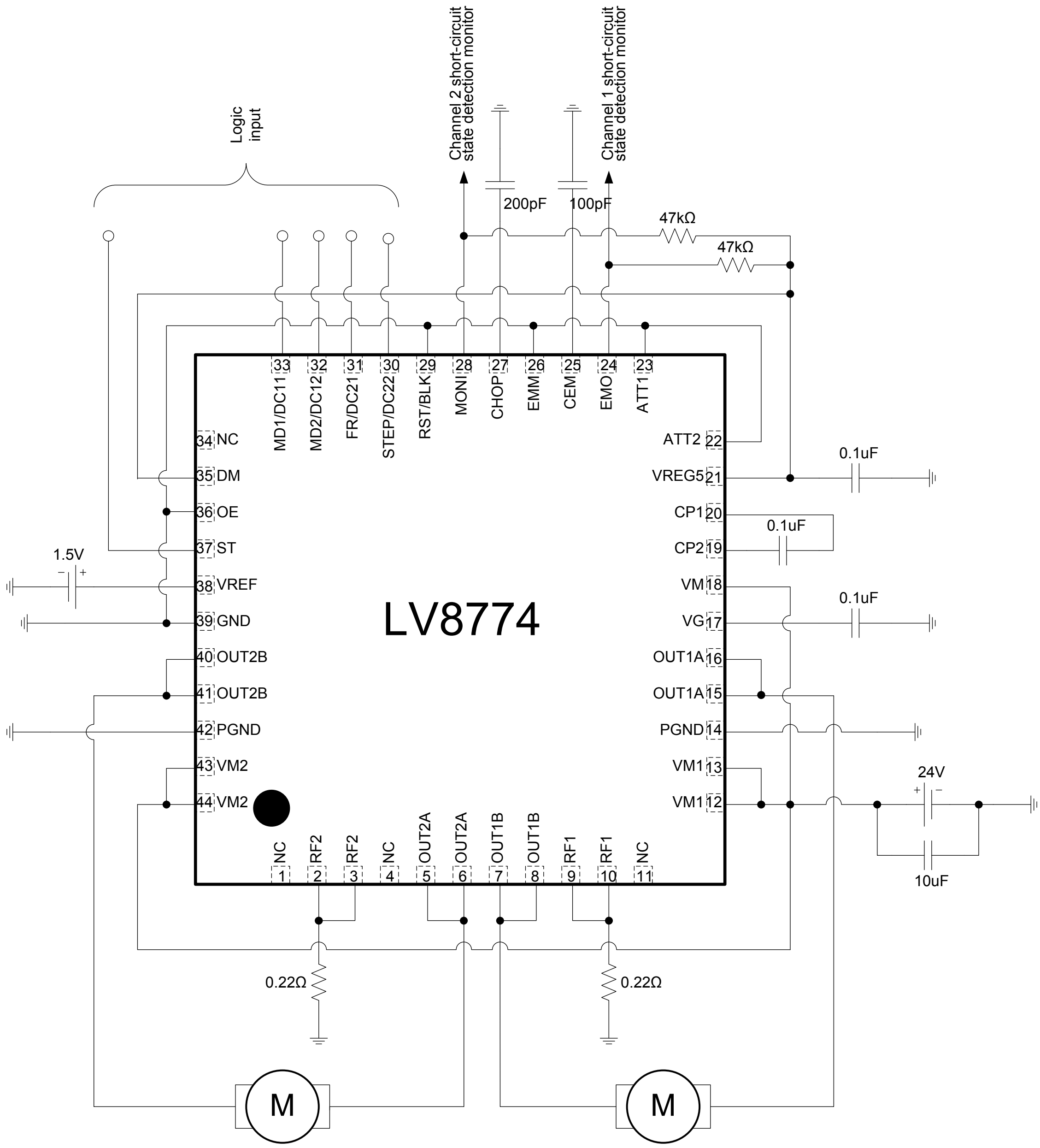
= 10μA/ (200pF × 0.5V × 2) = 50kHz

Timer latch time when the output is short-circuited

Tcem = Ccem × Vtcem/Icem

= 100pF × 1V/10μA = 10μs

• DC motor driver circuit (DM = High, and the current limit function is in use.)



The formulae for setting the constants in the example of the application circuit above are as follows :

Constant current limit (100%) setting

When VREF = 1.5V

Ilimit = VREF/5/RF resistance

= 1.5V/5/0.22Ω = 1.36A

Chopping frequency setting

Fchop = Ichop/ (Cchop × Vtchop × 2)

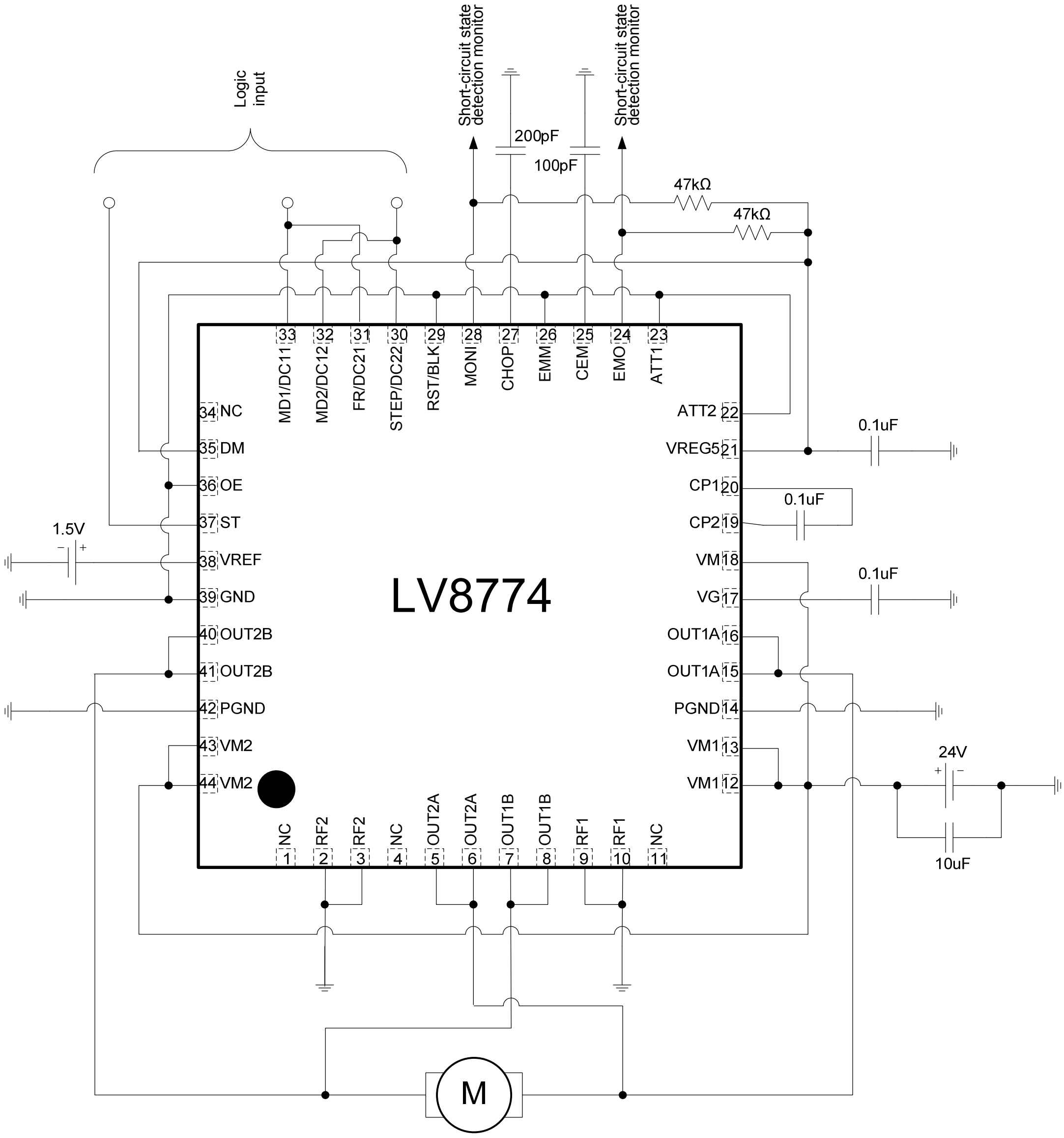
= 10µA/ (200pF × 0.5V × 2) = 50kHz

Timer latch time when the output is short-circuited

Tcem = Ccem × Vtcem/Icem

= 100pF × 1V/10µA = 10µs

• High current DC motor driver circuit (DM = High, and the current limit function cannot be used.)



LV8774Q can drive a large current DC motor by connecting two H-bridges to parallel.

Iomax = 4A
Iopeak = 5A (tw ≤ 10ms, duty 20%)

When it connects two H-bridges to parallel, LV8774Q cannot use the internal PWM constant current control function. Please connect the RF1 pin and RF2 pin to GND.

ORDERING INFORMATION

Device	Package	Shipping (Qty / Packing)
LV8774Q-AH	VQFN44L (6mm × 6mm) (Pb-Free / Halogen Free)	1000 / Tape & Reel

† For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D. http://www.onsemi.com/pub_link/Collateral/BRD8011-D.PDF