

Crimzon<sup>™</sup> ZLR16300

# Z8 Low Voltage ROM MCUs with Infrared Timers

### **Product Specification**

PS021410-0605

ZiLOG Worldwide Headquarters • 532 Race Street • San Jose, CA 95126-3432 Telephone: 408.558.8500 • Fax: 408.558.8300 • <u>www.ZiLOG.com</u>



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ZiLOG Worldwide Headquarters

532 Race Street San Jose, CA 95126-3432 Telephone: 408.558.8500 Fax: 408.558.8300 www.zilog.com

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### **Revision History**

Each instance in Table 1 reflects a change to this document from its previous revision. To see more detail, click the appropriate link in the table.

Date	Revision Level	Description	Page#
December 2004	07	Changed low power consumption and current usage for STOP and HALT modes, removed mask option note, and added characterization data to Table 7.	1, 2, 8
		Removed Preliminary designation	All
January 2005	08	Changed low power consumption value to 5mW. Changed STOP and HALT mode current values to $1.3\mu$ A and $0.5$ mA respectively. Changed V <sub>CC</sub> Low Voltage Protection typical rating to 1.8V.	1, 12
April 2005	09	Clarified Port 1 reserved address status by removing Port 1 in Figure 1 and adding a note in Figure 12. Reference CR5843.	3, 21
June 2005	10	Added 1K and 2K parts.	All

### Table 1. Revision History of this Document

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### **Features**

Table 1 lists the features of ZiLOG<sup>®</sup>'s Crimzon<sup>TM</sup> ZLR16300 family members.

### Table 1. Features

Device	ROM (KB)	RAM* (Bytes)	I/O Lines	Voltage Range
Crimzon <sup>TM</sup> ZLR16300	1, 2, 4, 8, 16	237	24, 16	2.0V-3.6V
* General purpose				

- Low power consumption–5mW (typical)
- Three standby modes:
  - STOP—1.3μA (typical)
  - HALT—0.5mA (typical)
  - Low voltage reset
- Special architecture to automate both generation and reception of complex pulses or signals:
  - One programmable 8-bit counter/timer with two capture registers and two load registers
  - One programmable 16-bit counter/timer with one 16-bit capture register pair and one 16-bit load register pair
  - Programmable input glitch filter for pulse reception
- Six priority interrupts
  - Three external
  - Two assigned to counter/timers
  - One low-voltage detection interrupt
- Low voltage detection and high voltage detection flags
- Programmable Watch-Dog Timer (WDT)
- Power-On Reset (POR)
- Two independent comparators with programmable interrupt polarity
- Selectable pull-up transistors on ports 0, 2, 3

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- Mask options
  - Port 0: 0–3 pull-ups
  - Port 0: 4-7 pull-ups
  - Port 2: 0-7 pull-ups
  - Port 3: 0–3 pull-ups
  - Watch-Dog Timer at Power On Reset

### **General Description**

The Crimzon<sup>TM</sup> ZLR16300 is a ROM-based member of the MCU family of general purpose microcontrollers. With 1KB to 16KB of program memory and 237B of general purpose RAM, ZiLOG<sup>®</sup>'s CMOS microcontrollers offer fast-executing, efficient use of memory, sophisticated interrupts, input/output bit manipulation capabilities, automated pulse generation/reception, and internal key-scan pull-up transistors.

The Crimzon<sup>TM</sup> ZLR16300 architecture (Figures 1 and 2) is based on ZiLOG<sup>®</sup>'s 8bit microcontroller core with an Expanded Register File allowing access to register-mapped peripherals, input/output (I/O) circuits, and powerful counter/timer circuitry. The Z8<sup>®</sup> core offers a flexible I/O scheme, an efficient register and address space structure, and a number of ancillary features that are useful in many consumer, automotive, computer peripheral, and battery-operated hand-held applications.

There are three basic address spaces available to support a wide range of configurations: Program Memory, Register File and Expanded Register File. The register file is composed of 256B of RAM. It includes three I/O port registers, 16 control and status registers, and 237 general-purpose registers. The Expanded Register File consists of two additional register groups (F and D).

To unburden the program from coping with such real-time problems as generating complex waveforms or receiving and demodulating complex waveform/pulses, the Crimzon<sup>TM</sup> ZLR16300 offers a new intelligent counter/timer architecture with 8-bit and 16-bit counter/timers (see Figure 2). Also included are a large number of user-selectable modes and two on-board comparators to process analog signals with separate reference voltages.

Power connections use the conventional descriptions listed in Table 2.

Connection	Circuit	Device	
Power	V <sub>CC</sub>	V <sub>DD</sub>	
Ground	GND	V <sub>SS</sub>	

### Table 2. Power Connections





Note: Refer to the specific package for available pins.

Figure 1. Functional Block Diagram





Figure 2. Counter/Timers Diagram



### **Pin Description**

The pin configuration for the 20-pin DIP/SOIC/SSOP is illustrated in Figure 3 and described in Table 3. The pin configuration for the 28-pin DIP/SOIC/SSOP are depicted in Figure 4 and described in Table 4.

Figure 3.	20-Pin DIP/SOIC/SSOP Pin Config	juration
-----------	---------------------------------	----------

Pin #	Symbol	Function	Direction
1–3	P25–P27	Port 2, Bits 5,6,7	Input/Output
4	P07	Port 0, Bit 7	Input/Output
5	V <sub>DD</sub>	Power Supply	
6	XTAL2	Crystal Oscillator Clock	Output
7	XTAL1	Crystal Oscillator Clock	Input
8–10	P31–P33	Port 3, Bits 1,2,3	Input
11,12	P34, P36	Port 3, Bits 4,6	Output
13	P00/Pref1/P30	Port 0, Bit 0/Analog reference input Port 3, Bit 0	Input/Output for P00 Input for Pref1/P30
14	P01	Port 0, Bit 1	Input/Output
15	V <sub>SS</sub>	Ground	
16–20	P20–P24	Port 2, Bits 0,1,2,3,4	Input/Output

#### Table 3. 20-Pin DIP/SOIC/SSOP Pin Identification





				т
P25 □	1	$\bigcirc$	28	□ P24
P26 □	2		27	□ P23
P27 🗖	3		26	🗆 P22
P04 🗖	4		25	🗆 P21
P05 🗖	5		24	🗆 P20
P06 🗖	6	28-Pin	23	🗖 P03
P07 🗖	7	PDIP	22	⊐v <sub>ss</sub>
V <sub>DD</sub> ⊏	8	SOIC SSOP	21	□ P02
XTAL2	9	550P	20	<b>P</b> 01
XTAL1 □	10		19	🗆 P00
P31 🗖	11		18	Pref1/P30
P32 🗖	12		17	🗆 P36
P33 🗖	13		16	🖵 P37
P34 🗖	14		15	□ P35
				4

Figure 4. 28-Pin DIP/SOIC/SSOP Pin Configuration

Pin	Symbol	Direction	Description
1-3	P25-P27	Input/Output	Port 2, Bits 5,6,7
4-7	P04-P07	Input/Output	Port 0, Bits 4,5,6,7
8	V <sub>DD</sub>		Power supply
9	XTAL2	Output	Crystal, oscillator clock
10	XTAL1	Input	Crystal, oscillator clock
11–13	P31-P33	Input	Port 3, Bits 1,2,3
14	P34	Output	Port 3, Bit 4
15	P35	Output	Port 3, Bit 5
16	P37	Output	Port 3, Bit 7
17	P36	Output	Port 3, Bit 6
18	Pref1	Input	Analog ref input; connect to V <sub>CC</sub> if not used
			Port 3 Bit 0
19-21	P00-P02	Input/Output	Port 0, Bits 0,1,2
22	V <sub>SS</sub>		Ground
23	P03	Input/Output	Port 0, Bit 3
24-28	P20-P24	Input/Output	Port 2, Bits 0-4

#### Table 4. 28-Pin DIP/SOIC/SSOP Pin Identification

### **Absolute Maximum Ratings**

Stresses greater than those listed in Table 5 might cause permanent damage to the device. This rating is a stress rating only. Functional operation of the device at



any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period might affect device reliability.

### Table 5. Absolute Maximum Ratings

Parameter	Minimum	Maximum	Units	Notes
Ambient temperature under bias	0	+70	С	
Storage temperature	-65	+150	С	
Voltage on any pin with respect to $V_{SS}$	-0.3	+4.0	V	1
Voltage on $V_{DD}$ pin with respect to $V_{SS}$	-0.3	+3.6	V	
Maximum current on input and/or inactive output pin	-5	+5	mA	
Maximum output current from active output pin	-25	+25	mA	
Maximum current into V <sub>DD</sub> or out of V <sub>SS</sub>		75	mA	
Note:				

1. This voltage applies to all pins except the following: V<sub>DD</sub>.

### **Standard Test Conditions**

The characteristics listed in this product specification apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 5).



Figure 5. Test Load Diagram





### Capacitance

Table 6 lists the capacitances.

### Table 6. Capacitance

Parameter	Maximum		
Input capacitance	12pF		
Output capacitance	12pF		
I/O capacitance	12pF		
Note: $T_A = 25^{\circ}C$ , $V_{CC} = GND = 0 V$ , f = 1.0 MHz, unmeasured pins returned to GND			

### **DC Characteristics**

			T <sub>A</sub> = 0°C t	o +70°C	;			
Symbol	Parameter	V <sub>cc</sub>	Min	Typ(7)	Мах	Units	Conditions	Notes
V <sub>CC</sub>	Supply Voltage		2.0 V		3.6	V	See Note 5	
V <sub>CH</sub>	Clock Input High Voltage	2.0-3.6V	0.8 V <sub>CC</sub>		V <sub>CC</sub> +0.3	V	Driven by External Clock Generator	
V <sub>CL</sub>	Clock Input Low Voltage	2.0-3.6V	V <sub>SS</sub> -0.3		0.5	V	Driven by External Clock Generator	
V <sub>IH</sub>	Input High Voltage	2.0-3.6V	0.7 V <sub>CC</sub>		V <sub>CC</sub> +0.3	V		
V <sub>IL</sub>	Input Low Voltage	2.0-3.6V	V <sub>SS</sub> -0.3		0.2 V <sub>CC</sub>	V		
V <sub>OH1</sub>	Output High Voltage	2.0-3.6V	V <sub>CC</sub> -0.4			V	I <sub>OH</sub> = –0.5mA	
V <sub>OH2</sub>	Output High Voltage (P36, P37, P00, P01)	2.0-3.6V	V <sub>CC</sub> -0.8			V	I <sub>OH</sub> = -7mA	
V <sub>OL1</sub>	Output Low Voltage	2.0-3.6V			0.4	V	I <sub>OL</sub> = 4.0mA	
V <sub>OL2</sub>	Output Low Voltage (P00, P01, P36, P37)	2.0-3.6V			0.8	V	I <sub>OL</sub> = 10mA	
V <sub>OFFSET</sub>	Comparator Input Offset Voltage	2.0-3.6V			25	mV		
V <sub>REF</sub>	Comparator Reference Voltage	2.0-3.6V	0		V <sub>DD</sub> -1.75	V		
IIL	Input Leakage	2.0-3.6V	-1		1	μΑ	V <sub>IN</sub> = 0V, V <sub>CC</sub> Pull-ups disabled	
R <sub>PU</sub>	Pull-up Resistance	2.0V	225		675	KΩ	V <sub>IN</sub> = 0V; Pullups selectedby mask	
		3.6V	75		275	KΩ	option	
IOL	Output Leakage	2.0-3.6V	–1		1	μΑ	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
ICC	Supply Current	2.0 V 3.6 V		1.2 2.1	3 5	mA mA	at 8.0MHz at 8.0MHz	1, 2 1, 2

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T <sub>A</sub> = 0°C to +70°C								
Symbol	Parameter	V <sub>cc</sub>	Min	Typ(7)	Max	Units	Conditions	Notes
I <sub>CC1</sub>	Standby Current	2.0 V		0.5	1.6	mA	V <sub>IN</sub> = 0V, Clock at 8.0MHz	1, 2, 6
001	(HALT Mode)	3.6 V		0.8	2.0	mA	Same as above	1, 2, 6
I <sub>CC2</sub>	Standby Current	2.0 V		1.2	8	μΑ	V <sub>IN</sub> = 0 V, V <sub>CC</sub> WDT is not Runnin	g 3
	(STOP Mode)	3.6 V		1.4	10	μA	Same as above	3
		2.0 V		3.5	20	μA	V <sub>IN</sub> = 0 V, V <sub>CC</sub> WDT is Running	3
		3.6 V		6.5	30	μA	Same as above	3
I <sub>LV</sub>	Standby Current (Low Voltage)			0.8	6	μA	Measured at 1.3V	4
V <sub>BO</sub>	V <sub>CC</sub> Low Voltage			1.8	2.0	V	8MHz maximum	
20	Protection						Ext. CLK Freq.	
V <sub>LVD</sub>	Vcc Low Voltage			2.4		V		
210	Detection							
V <sub>HVD</sub>	Vcc High Voltage			2.7		V		
	Detection							

#### Table 7. DC Characteristics (Continued)

#### Notes:

1. All outputs unloaded, inputs at rail.

2. CL1 = CL2 = 100 pF.

3. Oscillator stopped.

4. Oscillator stops when  $V_{CC}$  falls below  $V_{BO}$  limit. 5. It is strongly recommended to add a filter capacitor (minimum 0.1  $\mu$ F), physically close to VDD and  $V_{SS}$  pins if operating voltage fluctuations are anticiipated, such as those resulting from driving an IR LED.

6. Comparators and Timers are on. Interrupt disabled.

7. Typical vales shown are at 25 degrees C.



### **AC Characteristics**

Figure 6 and Table 8 describe the Alternating Current (AC) characteristics.



Figure 6. AC Timing Diagram



			Т <sub>А</sub> =0°С to +70°С 8.0MHz					
No	Symbol	Parameter	V <sub>cc</sub>	Minimum	Maximum	Units	Notes	<sup>–</sup> Register (D1, D0)
1	ТрС	Input Clock Period	2.0–3.6	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–3.6		25	ns	1	
3	TwC	Input Clock Width	2.0–3.6	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 3.6	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–3.6	3ТрС			1	
6	TpTin	Timer Input Period	2.0–3.6	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–3.6		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 3.6	100 70		ns	1, 2	
9	TwIH	Interrupt Request Input High Time	2.0–3.6	10TpC			1, 2	
10	Twsm	Stop-Mode Recovery Width	2.0–3.6	12		ns	3	
		Spec		10TpC			4	
11	Tost	Oscillator Start-Up Time	2.0–3.6		5TpC		4	
12	Twdt	Watch-Dog Timer Delay Time	2.0–3.6 2.0–3.6 2.0–3.6 2.0–3.6	10 20 40 160		ms ms ms ms		0, 0 0, 1 1, 0 1, 1
13	T <sub>POR</sub>	Power-On Reset	2.0–3.6	2.5	10	ms		
Not	es:							

#### Table 8. AC Characteristics

1. Timing Reference uses 0.9  $V_{CC}$  for a logic 1 and 0.1  $V_{CC}$  for a logic 0. 2. Interrupt request through Port 3 (P33–P31).

3. SMR – D5 = 1.

4. SMR – D5 = 0.

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### **Pin Functions**

### XTAL1 Crystal 1 (Time-Based Input)

This pin connects a parallel-resonant crystal or ceramic resonator to the on-chip oscillator input. Additionally, an external single-phase clock can be connected to the on-chip oscillator input.

### XTAL2 Crystal 2 (Time-Based Output)

This pin connects a parallel-resonant crystal or ceramic resonant to the on-chip oscillator output.

### Port 0 (P07-P00)

Port 0 is an 8-bit, bidirectional, CMOS-compatible port. These eight I/O lines are configured under software control as a nibble I/O port. The output drivers are push-pull or open-drain controlled by bit D2 in the PCON register.

If one or both nibbles are needed for I/O operation, they must be configured by writing to the Port 0 mode register. After a hardware reset, Port 0 is configured (Figure 7) as an input port.

An optional pull-up transistor is available as a mask option on all Port 0 bits with nibble select.

Notes: Internal pull-ups are disabled on any given pin or group of port pins when programmed into Output mode.

The Port 0 direction is reset to be input following an SMR.





Figure 7. Port 0 Configuration

### Port 2 (P27–P20)

Port 2 is an 8-bit, bidirectional, CMOS-compatible I/O port (see Figure 8). These eight I/O lines can be independently configured under software control as inputs or outputs. Port 2 is always available for I/O operation. A mask option is available to connect eight pull-up transistors on this port. Bits programmed as outputs are globally programmed as either push-pull or open-drain. The POR resets with the eight bits of Port 2 configured as inputs.

Port 2 also has an 8-bit input OR and AND gate, which can be used to wake up the part. P20 can be programmed to access the edge-detection circuitry in Demodulation mode.





Figure 8. Port 2 Configuration

### Port 3 (P37-P30)

Port 3 is an 8-bit, CMOS-compatible fixed I/O port (see Figure 9). Port 3 consists of four fixed input (P33–P30) and four fixed output (P37–P34), which can be configured under software control for interrupt and as output from the counter/timers. P30, P31, P32, and P33 are standard CMOS inputs; P34, P35, P36, and P37 are push-pull outputs.





### Figure 9. Port 3 Configuration

Two on-board comparators process analog signals on P31 and P32, with reference to the voltage on Pref1 and P33. The analog function is enabled by programming the Port 3 Mode Register (bit 1). P31 and P32 are programmable as rising, falling, or both edge triggered interrupts (IRQ register bits 6 and 7). Pref1 and P33 are the comparator reference voltage inputs. Access to the Counter Timer edgedetection circuit is through P31 or P20 (see "T8 and T16 Common Functions—"T8



and T16 Common Functions—CTR1(0D)01h" on page 28). Other edge detect and IRQ modes are described in Table 9.

**Note:** Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery (SMR) source, these inputs must be placed into Digital mode.

Pin	I/O	Counter/Timers	Comparator	Interrupt
Pref1/P30	IN		RF1	
P31	IN	IN	AN1	IRQ2
P32	IN		AN2	IRQ0
P33	IN		RF2	IRQ1
P34	OUT	Т8	AO1	
P35	OUT	T16		
P36	OUT	T8/16		
P37	OUT		AO2	
P20	I/O	IN		

Table 9. Port 3 Pin Function Summary

>

Port 3 also provides output for each of the counter/timers and the AND/OR Logic (see Figure 10). Control is performed by programming bits D5–D4 of CTR1, bit 0 of CTR0, and bit 0 of CTR2.





Figure 10. Port 3 Counter/Timer Output Configuration



### **Comparator Inputs**

In ANALOG mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 9 on page 15. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.



**Note:** Comparators are powered down by entering STOP mode. For P31–P33 to be used in a STOP Mode Recovery source, these inputs must be placed into Digital mode.

### **Comparator Outputs**

These channels can be programmed to be output on P34 and P37 through the PCON register.

### **Functional Description**

These devices incorporate special functions to enhance the Z8<sup>®</sup>'s functionality in consumer and battery-operated applications.

### **Program Memory**

These devices address from 1KB to16KB of program memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts. See Figure 11.

### RAM

The ZLR16300 product family features 237 Bytes of RAM.

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Maximum ROM Size		Not Accessible
Location of first Byte of	C	On-Chip ROM
instruction —— executed	12	Reset Start Address
after RESET	11	IRQ5
	10	IRQ5
	9	IRQ4
	8	IRQ4
	7	IRQ3
Interrupt Vector (Lower Byte)	6	IRQ3
	5	► IRQ2
Interrupt Vector	4	→ IRQ2
(Upper Byte)	3	IRQ1
	2	IRQ1
	1	IRQ0
	0	IRQ0

Figure 11. Program Memory Map



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### **Expanded Register File**

The register file has been expanded to allow for additional system control registers and for mapping of additional peripheral devices into the register address area. The  $Z8^{(\!8\!)}$  register address space (0 through15 (OFh) has been implemented as 16 banks, with 16 registers per bank. These register banks are known as the ERF (Expanded Register File). Bits 7–4 of register RP select the working register group. Bits 3–0 of register RP select the expanded register file bank.



**Note:** An expanded register bank is also referred to as an expanded register group (see Figure 12).

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Z8 <sup>®</sup> Standard Co	ontrol Registers	Reset Condition
	Register**	D7 D6 D5 D4 D3 D2 D1 D0
	FF SPL	
	FE SPH	
De sister Deister	FD RP	
Register Pointer	FC FLAGS	
7 6 5 4 3 2 1 0	FB IMR	
	FA IRQ	
Working RegisterExpanded RegisterGroup PointerBank Pointer	F9 IPR	
	F8 P01M	
	* F7 P3M	
	F6 P2M	
	* F5 Reserved	
	F4 Reserved	
	F3 Reserved	
Register File (Bank 0)**	F2 Reserved	
	F1 Reserved	
FF F0	F0 Reserved	
	Expanded Reg. Bank F/Group 0**	
	(F) 0F WDTMR	UU001101
	(F) 0E Reserved	
	* (F) 0D SMR2	0 0 0 0 0 0 0 0
	(F) 0C Reserved	
7F	↑ (F) 0B SMR	U 0 1 0 0 0 U 0
	(F) 0A Reserved	
	(F) 09 Reserved	$\left  \left  \left$
	(F) 08 Reserved	
	(F) 07 Reserved (F) 06 Reserved	
	(F) 05 Reserved	
	(F) 04 Reserved	╢┝┼┼┼┼┼┼┼┤
	(F) 03 Reserved	╽┝╶┽╶┽╶┽╶┽╶┽╶┥╴
	(F) 02 Reserved	
	(F) 01 Reserved	
Expanded Bog, Bank 0/Croup (0)	(F) 00 PCON	
Expanded Reg. Bank 0/Group (0)           (0) 03 P3         0         U	Expanded Reg. Bank D/Group 0	
(0) 02 P2 U	(D) 0C LVD	
NOTE Reserved	* (D) 0B HI8	00000000
(0) 00 P0 U	* (D) 0A LO8	0 0 0 0 0 0 0 0
	* (D) 09 HI16	000000000
NOTE: A write has no effect. Will always read back FF.	* (D) 08 LO16	0 0 0 0 0 0 0 0
U = Unknown	* (D) 07 TC16H	0 0 0 0 0 0 0 0
* Is not reset with a Stop-Mode Recovery	* (D) 06 TC16L	0 0 0 0 0 0 0 0
** All addresses are in hexadecimal	* (D) 05 TC8H	0 0 0 0 0 0 0 0
$\uparrow$ Is not reset with a Stop-Mode Recovery, except Bit 0	* (D) 04 TC8L	0 0 0 0 0 0 0
↑↑ Bit 5 is not reset with a Stop-Mode Recovery	↑↑ (D) 03 CTR3	0 0 0 1 1 1 1 1
↑↑↑ Bits 5,4,3,2 not reset with a Stop-Mode Recovery	↑↑↓ (D) 02 CTR2	000000000
↑↑↑↑ Bits 5 and 4 not reset with a Stop-Mode Recovery	<sup>↑↑↑↑</sup> \ (D) 01 CTR1	00000000
$\uparrow\uparrow\uparrow\uparrow\uparrow$ Bits 5,4,3,2,1 not reset with a Stop-Mode Recovery	↑↑↑↑↑\ (D) 00 CTR0	0 0 0 0 0 0 0 0

Figure 12. Expanded Register File Architecture



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The upper nibble of the register pointer (see Figure 13) selects which working register group, of 16 bytes in the register file, is accessed out of the possible 256. The lower nibble selects the expanded register file bank and in the case of the Crimzon<sup>TM</sup> ZLR16300 family, banks 0, F, and D are implemented. A 0h in the lower nibble allows the normal register file (bank 0) to be addressed. Any other value from 1h to Fh exchanges the lower 16 registers to the selected expanded register bank.

#### R253 RP





#### Figure 13. Register Pointer

### Example: (See Figure 12 on page 21)

R253 RP = 00h R0 = Port 0 R2 = Port 2 R3 = Port 3

But if:

R253 RP = 0Dh R0 = CTR0 R1 = CTR1 R2 = CTR2 R3 = CTR3



# The counter/timers are mapped into ERF group D. Access is easily performed using the following:

LD	RP, #0Dh	;Select ERF D for access to bank D ;(working register
group 0)		
LD	R0,#xx	;load CTR0
LD	1, #xx	;load CTR1
LD	R1, 2	;CTR2→CTR1
LD	RP, #0Dh	;Select ERF D for access to bank D ; (working register
group 0)		
LD	RP, #7Dh	;Select expanded
register bank D and working bank 0 for access.		;register group 7 of
LD	71h, 2	;CTRL2→register 71h
LD	R1, 2	;CTRL2 $\rightarrow$ register 71h

### **Register File**

The register file (bank 0) consists of 3 I/O port registers, 237 general-purpose registers, 16 control and status registers (R0, R2, R3, R4–R239, and R240–R255, respectively), and two expanded register Banks D (see Table 10) and F. Instructions can access registers directly or indirectly through an 8-bit address field, thereby allowing a short, 4-bit register address to use the Register Pointer (Figure 14). In the 4-bit mode, the register file is divided into 16 working register groups, each occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working register group.

**Note:** Register address E0h–EFh can only be accessed through working registers and indirect addressing modes.

## Crimzon<sup>TM</sup>ZLR16300 Product Specification





\* RP = 00: Selects Register Bank 0, Working Register Group 0

Figure 14. Register Pointer—Detail

### Stack

The internal register file is used for the stack. An 8-bit Stack Pointer SPL (R255) is used for the internal stack that resides in the general-purpose registers (R4–R239). SPH (R254) can be used as a general-purpose register.



### **Timers**

### T8\_Capture\_HI—HI8(0D)0Bh

This register holds the captured data from the output of the 8-bit Counter/Timer0. Typically, this register holds the number of counts when the input signal is 1.

Field	Bit Position		Description
T8_Capture_HI	[7:0]	R/W	Captured Data - No Effect

### T8\_Capture\_LO—L08(0D)0Ah

This register holds the captured data from the output of the 8-bit Counter/Timer0. Typically, this register holds the number of counts when the input signal is 0.

Field	Bit Position		Description	
T8_Capture_L0	[7:0]	R/W	Captured Data - No Effect	

### T16\_Capture\_HI—HI16(0D)09h

This register holds the captured data from the output of the 16-bit Counter/ Timer16. This register holds the MS-Byte of the data.

Field Bit Positio			Description
T16_Capture_HI	[7:0]	R/W	Captured Data - No Effect

### T16\_Capture\_LO—L016(0D)08h

This register holds the captured data from the output of the 16-bit Counter/ Timer16. This register holds the LS-Byte of the data.

Field	Bit Position	Description
T16_Capture_LO	[7:0]	R/W Captured Data - No Effect

### Counter/Timer2 MS-Byte Hold Register—TC16H(0D)07h

Field	Bit Position		Description
T16_Data_HI	[7:0]	R/W	Data





### Counter/Timer2 LS-Byte Hold Register—TC16L(0D)06h

Field Bit Position			Description
T16_Data_LO	[7:0]	R/W	Data

### Counter/Timer8 High Hold Register—TC8H0(D)05h

Field	Bit Position		Description
T8_Level_HI	[7:0]	R/W	Data

### Counter/Timer8 Low Hold Register—TC8L(0D)04h

Field	Bit Position		Description
T8_Level_LO	[7:0]	R/W	Data

### CTR0 Counter/Timer8 Control Register—CTR0(0D)00h

Table 10 lists and briefly describes the fields for this register.

Table 10. CTR0(0D)00h Counter/Timer8 Control Register

Field	<b>Bit Position</b>		Value	Description
T8_Enable	7	R/W	0*	Counter Disabled
_			1	Counter Enabled
			0	Stop Counter
			1	Enable Counter
Single/Modulo-N	-6	R/W	0*	Modulo-N
-			1	Single Pass
Time_Out	5	R/W	0**	No Counter Time-Out
_			1	Counter Time-Out Occurred
			0	No Effect
			1	Reset Flag to 0
T8 _Clock	43	R/W	0 0**	SCLK
_			0 1	SCLK/2
			10	SCLK/4
			11	SCLK/8
Capture_INT_Mask	2	R/W	0**	Disable Data Capture Interrupt
			1	Enable Data Capture Interrupt

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#### Table 10.CTR0(0D)00h Counter/Timer8 Control Register (Continued)

Field	Bit Position		Value	Description
Counter_INT_Mask	1-	R/W	0** 1	Disable Time-Out Interrupt Enable Time-Out Interrupt
P34_Out	0	R/W	0* 1	P34 as Port Output T8 Output on P34

#### Note:

\*Indicates the value at Power-On Reset.

\*\* Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

### **T8 Enable**

This field enables T8 when set (written) to 1.

### Single/Modulo-N

When set to 0 (Modulo-N), the counter reloads the initial value when the terminal count is reached. When set to 1 (Single-Pass), the counter stops when the terminal count is reached.

### Timeout

This bit is set when T8 times out (terminal count reached). To reset this bit, write a 1 to its location.



**Caution:** Writing a 1 is the only way to reset the Terminal Count status condition. Reset this bit before using/enabling the counter/timers.

The first clock of T8 might not have complete clock width and can occur any time when enabled.

**Note:** Take care when using the OR or AND commands to manipulate CTR0, bit 5 and CTR1, bits 0 and 1 (Demodulation Mode). These instructions use a Read-Modify-Write sequence in which the current status from the CTR0 and CTR1 registers is ORed or ANDed with the designated value and then written back into the registers.

### **T8 Clock**

These bits define the frequency of the input signal to T8.



### Capture\_INT\_Mask

Set this bit to allow an interrupt when data is captured into either LO8 or HI8 upon a positive or negative edge detection in Capture Mode.

### Counter\_INT\_Mask

Set this bit to allow an interrupt when T8 has a timeout.

### P34\_Out

This bit defines whether P34 is used as a normal output pin or the T8 output.

### T8 and T16 Common Functions—CTR1(0D)01h

This register controls the functions in common with the T8 and T16.

Table 11 lists and briefly describes the fields for this register.

### Table 11. CTR1(0D)01h T8 and T16 Common Functions

Field	Bit Position		Value	Description
Mode	7	R/W	0*	Transmit Mode
			1	Demodulation Mode
P36_Out/	-6	R/W		Transmit Mode
Capture_Input			0*	Port Output
			1	T8/T16 Output
				Demodulation Mode
			0*	P31
			1	P20
T8/T16_Logic/	54	R/W		Transmit Mode
Edge _Detect			00**	AND
			01	OR
			10	NOR
			11	NAND
				Demodulation Mode
			00**	Falling Edge
			01	Rising Edge
			10	Both Edges
			11	Reserved



Field	Bit Position		Value	Description
Transmit_Submode/	32	R/W		Transmit Mode
Glitch_Filter			00	Normal Operation
			01	Ping-Pong Mode
			10	T16_Out = 0
			11	T16_Out = 1
				Demodulation Mode
			00	No Filter
			01	4 SCLK Cycle
			10	8 SCLK Cycle
			11	Reserved
Initial_T8_Out/	1-			Transmit Mode
Rising Edge		R/W	0	T8_OUT is 0 Initially
			1	T8_OUT is 1 Initially
				Demodulation Mode
		R	0	No Rising Edge
			1	Rising Edge Detected
		W	0	No Effect
			1	Reset Flag to 0
Initial_T16_Out/	0			Transmit Mode
Falling_Edge		R/W	0	T16_OUT is 0 Initially
			1	T16_OUT is 1 Initially
				Demodulation Mode
		R	0	No Falling Edge
			1	Falling Edge Detected
		W	0	No Effect
			1	Reset Flag to 0

### Table 11. CTR1(0D)01h T8 and T16 Common Functions (Continued)

#### Note:

\*Default at Power-On Reset.

\*\* Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

### Mode

If the result is 0, the counter/timers are in Transmit mode; otherwise, they are in Demodulation Mode.

### P36\_Out/Demodulator\_Input

In Transmit Mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In Demodulation Mode, this bit defines whether the input signal to the Counter/ Timers is from P20 or P31.
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If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

# T8/T16\_Logic/Edge\_Detect

In Transmit Mode, this field defines how the outputs of T8 and T16 are combined (AND, OR, NOR, NAND).

In Demodulation Mode, this field defines which edge should be detected by the edge detector.

## Transmit\_Submode/Glitch Filter

In Transmit Mode, this field defines whether T8 and T16 are in the Ping-Pong mode or in independent normal operation mode. Setting this field to "Normal Operation Mode" terminates the "Ping-Pong Mode" operation. When set to 10, T16 is immediately forced to a 0; a setting of 11 forces T16 to output a 1.

In Demodulation Mode, this field defines the width of the glitch that must be filtered out.

# Initial\_T8\_Out/Rising\_Edge

In Transmit Mode, if 0, the output of T8 is set to 0 when it starts to count. If 1, the output of T8 is set to 1 when it starts to count. When the counter is not enabled and this bit is set to 1 or 0, T8\_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D1.

In Demodulation Mode, this bit is set to 1 when a rising edge is detected in the input signal. In order to reset the mode, a 1 should be written to this location.

#### Initial\_T16 Out/Falling \_Edge

In Transmit Mode, if it is 0, the output of T16 is set to 0 when it starts to count. If it is 1, the output of T16 is set to 1 when it starts to count. This bit is effective only in Normal or Ping-Pong Mode (CTR1, D3; D2). When the counter is not enabled and this bit is set, T16\_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D0.

In Demodulation Mode, this bit is set to 1 when a falling edge is detected in the input signal. In order to reset it, a 1 should be written to this location.



**Note:** Modifying CTR1 (D1 or D0) while the counters are enabled causes unpredictable output from T8/16\_OUT.

#### CTR2 Counter/Timer 16 Control Register—CTR2(0D)02h

Table 12 lists and briefly describes the fields for this register.



Field	Bit Position		Value	Description
T16_Enable	7	R	0*	Counter Disabled
			1	Counter Enabled
		W	0	Stop Counter
			1	Enable Counter
Single/Modulo-N	-6	R/W		Transmit Mode
			0	Modulo-N
			1	Single Pass
				Demodulation Mode
			0	T16 Recognizes Edge
			1	T16 Does Not Recognize
				Edge
Time_Out	5	R	0**	No Counter Timeout
			1	Counter Timeout
				Occurred
		W	0	No Effect
			1	Reset Flag to 0
T16 _Clock	43	R/W	00**	SCLK
			01	SCLK/2
			10	SCLK/4
			11	SCLK/8
Capture_INT_Mask	2	R/W	0**	Disable Data Capture Int.
			1	Enable Data Capture Int.
Counter_INT_Mask	1-	R/W	0*	Disable Timeout Int.
				Enable Timeout Int.
P35_Out	0	R/W	0*	P35 as Port Output
			1	T16 Output on P35

#### Table 12. CTR2(0D)02h: Counter/Timer16 Control Register

#### Note:

\*Indicates the value upon Power-On Reset.

\*\* Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

# T16\_Enable

This field enables T16 when set to 1.

#### Single/Modulo-N

In Transmit Mode, when set to 0, the counter reloads the initial value when it reaches the terminal count. When set to 1, the counter stops when the terminal count is reached.

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In Demodulation Mode, when set to 0, T16 captures and reloads on detection of all the edges. When set to 1, T16 captures and detects on the first edge but ignores the subsequent edges. For details, see the description of T16 Demodulation Mode on page 40.

# Time\_Out

This bit is set when T16 times out (terminal count reached). To reset the bit, write a 1 to this location.

# T16\_Clock

This bit defines the frequency of the input signal to Counter/Timer16.

# Capture\_INT\_Mask

This bit is set to allow an interrupt when data is captured into LO16 and HI16.

# Counter\_INT\_Mask

Set this bit to allow an interrupt when T16 times out.

# P35\_Out

This bit defines whether P35 is used as a normal output pin or T16 output.

# CTR3 T8/T16 Control Register—CTR3(0D)03h

Table 13 lists and briefly describes the fields for this register. This register allow the T8 and T16 counters to be synchronized.

#### Table 13. CTR3(0D)03h T8/T16 Control Register

T16_Enable	7	R	0*	Counter Disabled
		R	1	Counter Enabled
		W	0	Stop Counter
		W	1	Enable Counter
T8 Enable	-6	R/W	0**	Counter Disabled
			1	Counter Enabled
			0	Stop Counter
			1	Enable Counter
Sync Mode	5	R/W	0*	Disable Sync Mode
			1	Enable Sync Mode
Reserved	43210	R/W	1	Always reads 11111
			x	No Effect

\* Indicates the value upon Power-On Reset.

\*\*\* Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.



# **Counter/Timer Functional Blocks**

# Input Circuit

The edge detector monitors the input signal on P31 or P20. Based on CTR1 D5– D4, a pulse is generated at the Pos Edge or Neg Edge line when an edge is detected. Glitches in the input signal that have a width less than specified (CTR1 D3, D2) are filtered out (see Figure 15).



#### Figure 15. Glitch Filter Circuitry

# T8 Transmit Mode

Before T8 is enabled, the output of T8 depends on CTR1, D1. If it is 0, T8\_OUT is 1; if it is 1, T8\_OUT is 0. See Figure 16.





Figure 16. Transmit Mode Flowchart



When T8 is enabled, the output T8\_OUT switches to the initial value (CTR1, D1). If the initial value (CTR1, D1) is 0, TC8L is loaded; otherwise, TC8H is loaded into the counter. In Single-Pass Mode (CTR0, D6), T8 counts down to 0 and stops, T8\_OUT toggles, the timeout status bit (CTR0, D5) is set, and a timeout interrupt can be generated if it is enabled (CTR0, D1). In Modulo-N Mode, upon reaching terminal count, T8\_OUT is toggled, but no interrupt is generated. From that point, T8 loads a new count (if the T8\_OUT level now is 0), TC8L is loaded; if it is 1, TC8H is loaded. T8 counts down to 0, toggles T8\_OUT, and sets the timeout status bit (CTR0, D5), thereby generating an interrupt if enabled (CTR0, D1). One cycle is complete. T8 then loads from TC8H or TC8L according to the T8\_OUT level and repeats the cycle. See Figure 17.



Figure 17. 8-Bit Counter/Timer Circuits

The values in TC8H or TC8L can be modified at any time. The new values take effect when they are loaded.

Ca

Caution: To ensure known operation do not write these registers at the time the values are to be loaded into the counter/timer. An initial count of 1 is not allowed (a non-function occurs). An initial count of 0 causes TC8 to count from 0 to FFh to FEh.



**Note:** The letter h denotes hexadecimal values.

Transition from 0 to FFh is not a timeout condition.

 $\triangle$ 

**Caution:** Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur. See Figure 18 and Figure 19.



Figure 18. T8\_OUT in Single-Pass Mode



#### Figure 19. T8\_OUT in Modulo-N Mode

# **T8 Demodulation Mode**

The user must program TC8L and TC8H to FFh. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put into LO8; if it is a negative edge, data is put into HI8. From that point, one of the



edge detect status bits (CTR1, D1; D0) is set, and an interrupt can be generated if enabled (CTR0, D2). Meanwhile, T8 is loaded with FFh and starts counting again. If T8 reaches 0, the timeout status bit (CTR0, D5) is set, and an interrupt can be generated if enabled (CTR0, D1). T8 then continues counting from FFh (see Figure 21 and Figure 21).



Figure 20. Demodulation Mode Count Capture Flowchart







Figure 21. Demodulation Mode Flowchart



## **T16 Transmit Mode**

In Normal or Ping-Pong mode, the output of T16 when not enabled, is dependent on CTR1, D0. If it is a 0, T16\_OUT is a 1; if it is a 1, T16\_OUT is 0. You can force the output of T16 to either a 0 or 1 whether it is enabled or not by programming CTR1 D3; D2 to a 10 or 11.

When T16 is enabled, TC16H \* 256 + TC16L is loaded, and T16\_OUT is switched to its initial value (CTR1, D0). When T16 counts down to 0, T16\_OUT is toggled (in NORMAL or PING-PONG mode), an interrupt (CTR2, D1) is generated (if enabled), and a status bit (CTR2, D5) is set. See Figure 22.



Figure 22. 16-Bit Counter/Timer Circuits

**Note:** Global interrupts override this function as described in "Interrupts" on page 43.

If T16 is in Single-Pass mode, it is stopped at this point (see Figure 23). If it is in Modulo-N Mode, it is loaded with TC16H \* 256 + TC16L, and the counting continues (see Figure 24).

The values in TC16H and TC16L can be modified at any time. The new values take effect when they are loaded.

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Caution: Do not load these registers at the time the values are to be loaded into the counter/timer to ensure known operation. An initial count of 1 is not allowed. An initial count of 0 causes T16 to count from 0 to FFFFh to FFFFh. Transition from 0 to FFFFh is not a timeout condition.







Figure 24. T16\_OUT in Modulo-N Mode

# **T16 Demodulation Mode**

The user must program TC16L and TC16H to FFh. After T16 is enabled, and the first edge (rising, falling, or both depending on CTR1 D5; D4) is detected, T16 captures HI16 and LO16, reloads, and begins counting.

# If D6 of CTR2 Is 0

When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current count in T16 is complemented and put into HI16 and LO16. When data is captured, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt is generated if enabled (CTR2, D2). T16 is loaded with FFFFh and starts again.

This T16 mode is generally used to measure space time, the length of time between bursts of carrier signal (marks).



# If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from FFFFh. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

# **Ping-Pong Mode**

This operation mode is only valid in Transmit Mode. T8 and T16 must be programmed in Single-Pass mode (CTR0, D6; CTR2, D6), and Ping-Pong mode must be programmed in CTR1, D3; D2. The user can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8\_OUT is set to this initial value (CTR1, D1). According to T8\_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16\_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the ping-pong operation, write 00 to bits D3 and D2 of CTR1. See Figure 25.

**Note:** Enabling ping-pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status flags before instituting this operation.





Figure 25. Ping-Pong Mode Diagram

# **Initiating Ping-Pong Mode**

First, make sure both counter/timers are not running. Set T8 into Single-Pass mode (CTR0, D6), set T16 into Single-Pass mode (CTR2, D6), and set the Ping-Pong mode (CTR1, D2; D3). These instructions can be in random order. Finally, start Ping-Pong mode by enabling either T8 (CTR0, D7) or T16 (CTR2, D7). See Figure 25.





The initial value of T8 or T16 must not be 1. If you stop the timer and restart the timer, reload the initial value to avoid an unknown previous value.



# **During Ping-Pong Mode**

The enable bits of T8 and T16 (CTR0, D7; CTR2, D7) are set and cleared alternately by hardware. The timeout bits (CTR0, D5; CTR2, D5) are set every time the counter/timers reach the terminal count.

## **Timer Output**

The output logic for the timers is illustrated in Figure 26. P34 is used to output T8-OUT when D0 of CTR0 is set. P35 is used to output the value of T16-OUT when D0 of CRTR2 is set. When D6 of CTR1 is et, P36 outputs the logic combination of T8-OUT and T16-OUT determined by D5 and D4 of CTR1.

## Interrupts

The Crimzon<sup>TM</sup> ZLR16300 features six different interrupts (Table 14). The interrupts are maskable and prioritized (Figure 27). The six sources are divided as follows: three sources are claimed by Port 3 lines P33–P31, two by the counter/ timers (Table 14) and one for low voltage detection. The Interrupt Mask Register (globally or individually) enables or disables the six interrupt requests.

The source for IRQ is determined by bit 1 of the Port 3 mode register (P3M). When in digital mode, Pin P33 is the source. When in analog mode the output of the Stop Mode Recovery source logic is used as the source for the interrupt. See Figure 32, Stop Mode Recovery Source, on page 52.





Figure 27. Interrupt Block Diagram



Name	Source	Vector Location	Comments
IRQ0	P32	0,1	External (P32), Rising, Falling Edge Triggered
IRQ1	P33	2,3	External (P33), Falling Edge Triggered
IRQ2	P31, T <sub>IN</sub>	4,5	External (P31), Rising, Falling Edge Triggered
IRQ3	T16	6,7	Internal
IRQ4	Т8	8,9	Internal
IRQ5	LVD	10,11	Internal

#### Table 14. Interrupt Types, Sources, and Vectors

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder controlled by the Interrupt Priority Register. An interrupt machine cycle activates when an interrupt request is granted. As a result, all subsequent interrupts are disabled, and the Program Counter and Status Flags are saved. The cycle then branches to the program memory vector location reserved for that interrupt. All Crimzon<sup>TM</sup> ZLR16300 interrupts are vectored through locations in the program memory. This memory location and the next byte contain the 16-bit address of the interrupt service routine for that particular interrupt request. To accommodate polled interrupt systems, interrupt inputs are masked, and the Interrupt Request register is polled to determine which of the interrupt requests require service.

An interrupt resulting from AN1 is mapped into IRQ2, and an interrupt from AN2 is mapped into IRQ0. Interrupts IRQ2 and IRQ0 can be rising, falling, or both edge triggered. These interrupts are programmable by the user. The software can poll to identify the state of the pin.

Programming bits for the Interrupt Edge Select are located in the IRQ Register (R250), bits D7 and D6. The configuration is indicated in Table 15.

IRQ		Interrupt Edge			
D7	D6	IRQ2 (P31)	IRQ0 (P32)		
0	0	F	F		
0	1	F	R		
1	0	R	F		
1	1	R/F	R/F		

#### Table 15. IRQ Register



#### Clock

The device's on-chip oscillator has a high-gain, parallel-resonant amplifier, for connection to a crystal, ceramic resonator, or any suitable external clock source (XTAL1 = Input, XTAL2 = Output). The crystal must be AT cut, 1 MHz to 8 MHz maximum, with a series resistance (RS) less than or equal to 100  $\Omega$ . The on-chip oscillator can be driven with a suitable external clock source.

The crystal must be connected across XTAL1 and XTAL2 using the recommended capacitors (capacitance greater than or equal to 22 pF) from each pin to ground.



\* Preliminary value including pin parasitics



XTAL2

#### Figure 28. Oscillator Configuration

#### **Power-On Reset**

A timer circuit clocked by a dedicated on-board RC-oscillator is used for the Power-On Reset (POR) timer function. The POR time allows V<sub>DD</sub> and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- Power Fail to Power OK status, including Waking up from V<sub>BO</sub> Standby
- Stop-Mode Recovery (if D5 of SMR = 1)
- WDT Timeout



The POR timer is 2.5 ms minimum. Bit 5 of the Stop-Mode Register determines whether the POR timer is bypassed after Stop-Mode Recovery (typical for external clock).

## Halt Mode

This instruction turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2, IRQ3, IRQ4, and IRQ5 remain active. The devices are recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit Halt Mode. After the interrupt service routine, the program continues from the instruction after the Halt.

## Stop Mode

This instruction turns off the internal clock and external crystal oscillation, reducing the standby current to 10  $\mu$ A or less. Stop Mode is terminated only by a reset, such as WDT timeout, POR or SMR. This condition causes the processor to restart the application program at address 000Ch. In order to enter Stop (or Halt) mode, first flush the instruction pipeline to avoid suspending execution in midinstruction. Execute an NOP instruction (Opcode = FFh) immediately before the appropriate sleep instruction, as follows:



FF	NOP	; clear the pipeline
6F	STOP	; enter Stop Mode
or		
FF	NOP	; clear the pipeline
7F	HALT	; enter Halt Mode
15	TALI	, enter mait Mode

## **Port Configuration Register**

The Port Configuration (PCON) register (Figure 29) configures the comparator output on Port 3. It is located in the expanded register file at Bank F, location 00.

#### PCON (0F) 00H



\* Default setting after reset

#### Figure 29. Port Configuration Register (PCON) (Write Only)

# Comparator Output Port 3 (D0)

Bit 0 controls the comparator used in Port 3. A 1 in this location brings the comparator outputs to P34 and P37, and a 0 releases the Port to its standard I/O configuration.

#### Port 0 Output Mode (D2)

Bit 2 controls the output mode of port 0. A 1 in this location sets the output to push-pull, and a 0 sets the output to open-drain.



## Stop-Mode Recovery Register (SMR)

This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 30). All bits are write only except bit 7, which is read only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level at the XORgate input (Figure 32 on page 52) is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits D2, D3, and D4 of the SMR register specify the source of the Stop-Mode Recovery signal. Bits D0 determines if SCLK/ TCLK are divided by 16 or not. The SMR is located in Bank F of the Expanded Register File at address 0Bh.







\* Default after Power On Reset or Watch-Dog Reset

\* \* Default setting after Reset and Stop Mode Recovery

\* \* \* At the XOR gate input

\* \* \* \* Default setting after reset. Must be 1 if using a crystal or resonator clock source.

#### Figure 30. Stop Mode Recovery Register

#### SCLK/TCLK Divide-by-16 Select (D0)

D0 of the SMR controls a divide-by-16 prescaler of SCLK/TCLK (Figure 31). This control selectively reduces device power consumption during normal processor execution (SCLK control) and/or Halt Mode (where TCLK sources interrupt logic). After Stop-Mode Recovery, this bit is set to 0.





Figure 31. SCLK Circuit

## Stop-Mode Recovery Register 2—SMR2(0F)0DH

Table 16 lists and describes the fields for this register.

Field	<b>Bit Position</b>		Value	Description
Reserved	7		0	Reserved (Must be 0)
Recovery Level	-6	W	0†	Low
-			1	High
Reserved	5		0	Reserved (Must be 0)
Source	432	W	000†	A. POR Only
			001	B. NAND of P23–P20
			010	C. NAND of P27–P20
			011	D. NOR of P33–P31
			100	E. NAND of P33–P31
			101	F. NOR of P33–P31, P00, P07
			110	G. NAND of P33–P31, P00, P07
			111	H. NAND of P33–P31, P22–P20
Reserved	10		00	Reserved (Must be 0)
<b>N</b> <i>i</i>				

#### Table 16. SMR2(F)0DH:Stop Mode Recovery Register 2\*

#### Notes:

\* Port pins configured as outputs are ignored as an SMR recovery source.

<sup>†</sup> Indicates the value at Power-On Reset

## Stop-Mode Recovery Source (D2, D3, and D4)

These three bits of the SMR specify the wake-up source of the Stop recovery (Figure 32 and Table 17).

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Figure 32. Stop Mode Recovery Source

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#### Table 17. Stop Mode Recovery Source

SMR:432			Operation		
D4	D3	D2	Description of Action		
0	0	0	POR and/or external reset recovery		
0	0	1	Reserved		
0	1	0	P31 transition		
0	1	1	P32 transition		
1	0	0	P33 transition		
1	0	1	P27 transition		
1	1	0	Logical NOR of P20 through P23		
1	1	1	Logical NOR of P20 through P27		

**Note:** Any Port 2 bit defined as an output drives the corresponding input to the default state. This condition allows the remaining inputs to control the AND/OR function. Refer to SMR2 register on page 54 for other recover sources.

#### Stop Mode Recovery Delay Select (D5)

This bit, if Low, disables the  $T_{POR}$  delay after Stop Mode Recovery. The default configuration of this bit is 1. If the "fast" wake up is selected, the Stop Mode Recovery source must be kept active for at least 10 TpC.

**Note:** This bit must be set to 1 if using a crystal or resonator clock source. The T<sub>POR</sub> delay allows the clock source to stabilize before executing instructions.

#### Stop Mode Recovery Edge Select (D6)

A 1 in this bit position indicates that a High level on any one of the recovery sources wakes the Crimzon<sup>TM</sup> ZLR16300 from Stop Mode. A 0 indicates Low level recovery. The default is 0 on POR.

#### Cold or Warm Start (D7)

This bit is read only. It is set to 1 when the device is recovered from Stop Mode. The bit is set to 0 when the device reset is other than Stop Mode Recovery (SMR).

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# Stop Mode Recovery Register 2 (SMR2)

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 33).

SMR2 (0F) DH

D7	D6	D5	D4	D3	D2	D1	D0	
								<ul> <li>Reserved (Must be 0)</li> <li>Reserved (Must be 0)</li> <li>Stop-Mode Recovery Source 2 000 POR Only * 001 NAND P20, P21, P22, P23 010 NAND P20, P21, P22, P23, P24, P25, P26, P27 011 NOR P31, P32, P33 100 NAND P31, P32, P33, P00, P07 110 NAND P31, P32, P33, P00, P07 111 NAND P31, P32, P33, P20, P21, P22</li> <li>Reserved (Must be 0)</li> <li>Recovery Level * * 0 Low * 1 High</li> </ul>
								1 High ——Reserved (Must be 0)

Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

\* Default setting after reset \* \* At the XOR gate input

Figure 33. Stop Mode Recovery Register 2 ((0F) DH:D2–D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.



**Note:** Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.





# Watch-Dog Timer Mode Register (WDTMR)

The Watch-Dog Timer (WDT) is a retriggerable one-shot timer that resets the  $Z8^{(i)}$  if it reaches its terminal count. The WDT must initially be enabled by executing the WDT instruction. On subsequent executions of the WDT instruction, the WDT is refreshed. The WDT circuit is driven by an on-board RC-oscillator. The WDT instruction affects the Zero (Z), Sign (S), and Overflow (V) flags.

The POR clock source the internal RC-oscillator. Bits 0 and 1 of the WDT register control a tap circuit that determines the minimum timeout period. Bit 2 determines whether the WDT is active during HALT, and Bit 3 determines WDT activity during STOP. Bits 4 through 7 are reserved (Figure 34). This register is accessible only during the first 60 processor cycles (120 XTAL clocks) from the execution of the first instruction after Power-On-Reset, Watch-Dog Reset, or a Stop-Mode Recovery (Figure 33). After this point, the register cannot be modified by any means (intentional or otherwise). The WDTMR cannot be read. The register is located in Bank F of the Expanded Register File at address location 0Fh. It is organized as illustrated in Figure 34.

WDTMR (0F) 0FH



\* Default setting after reset

#### Figure 34. Watch-Dog Timer Mode Register (Write Only)

# WDT Time Select (D0, D1)

This bit selects the WDT time period. It is configured as indicated in Table 18.





#### Table 18. Watch-Dog Timer Time Select

D1	D0	Timeout of Internal RC-Oscillator
0	0	10 ms min.
0	1	20 ms min.
1	0	40 ms min.
1	1	160 ms min.

# WDTMR During Halt (D2)

This bit determines whether or not the WDT is active during Halt Mode. A 1 indicates active during Halt. The default is 1. See Figure 35.



\* CLR1 and CLR2 enable the WDT/POR and 18 Clock Reset timers respectively upon a Low-to-High input translation.

#### Figure 35. Resets and WDT



# WDTMR During Stop (D3)

This bit determines whether or not the WDT is active during Stop Mode. A 1 indicates active during Stop. The default is 1.

## **ROM Selectable Options**

There are five ROM Selectable Options to choose from based on ROM code requirements. These options are listed in Table 19.

#### Table 19. ROM Selectable Options

Port 00–03 Pull-Ups	On/Off
Port 04–07 Pull-Ups	On/Off
Port 20–27 Pull-Up Port 3 Pull-Ups	On/Off
Port 3 Pull-Ups	On/Off
Watch-Dog Timer at Power-On Reset	On/Off

## Voltage Brown-Out/Standby

An on-chip Voltage Comparator checks that the V<sub>DD</sub> is at the required level for correct operation of the device. Reset is globally driven when V<sub>DD</sub> falls below V<sub>BO</sub>. A small drop in V<sub>DD</sub> causes the XTAL1 and XTAL2 circuitry to stop the crystal or resonator clock. If the V<sub>DD</sub> is allowed to stay above V<sub>RAM</sub>, the RAM content is preserved. When the power level is returned to above V<sub>BO</sub>, the device performs a POR and functions normally.

#### Low-Voltage Detection Register—LVD(0D)0CH

**Note:** Voltage detection does not work at Stop mode. It must be disabled during Stop mode in order to reduce current.

Field	Bit Position			Description
LVD	765432			Reserved
	2	R	1 0*	HVD flag set HVD flag reset
	1-	R	1 0*	LVD flag set LVD flag reset
	0	R/W	1 0*	Enable VD Disable VD
*Default	after POR			





**Note:** Do not modify register P01M while checking a low-voltage condition. Switching noise of both ports 0 and 1 together might trigger the LVD flag.

# **Voltage Detection and Flags**

The Voltage Detection register (LVD, register 0Ch at the expanded register bank 0Dh) offers an option of monitoring the V<sub>CC</sub> voltage. The Voltage Detection is enabled when bit 0 of LVD register is set. When Voltage Detection is enabled, the the V<sub>CC</sub> level is monitored in real time. The flags in the LVD register valid 20uS after Voltage Detection is enabled. The HVD flag (bit 2 of the LVD register) is set only if V<sub>CC</sub> is lower than the V<sub>HVD</sub>. When Voltage Detection is enabled, the LVD flag also triggers IRQ5. The IRQ bit 5 latches the low voltage condition until it is cleared by instructions or reset. The IRQ5 interrupt is served if it is enabled in the IMR register. Otherwise, bit 5 of IRQ register is latched as a flag only.



**Note:** If it is necessary to receive an LVD interrupt upon power-up at an operating voltage lower than the low battery detect threshold, enable interrupts using the Enable Interrupt instruction (EI) prior to enabling the voltage detection.

# **Expanded Register File Control Registers (0D)**

The expanded register file control registers (0D) are depicted in Figure 36 through Figure 40.





#### CTR0 (0D) 00H D4 D7 D6 D5 D3 D2 D1 D0 0 P34 as Port Output \* 1 Timer8 Output 0 Disable T8 Timeout Interrupt\*\* 1 Enable T8 Timeout Interrupt 0 Disable T8 Data Capture Interrupt\*\* 1 Enable T8 Data Capture Interrupt 00 SCLK on T8\*\* 01 SCLK/2 on T8 10 SCLK/4 on T8 11 SCLK/8 on T8 R 0 No T8 Counter Timeout\*\* R 1 T8 Counter Timeout Occurred W 0 No Effect W 1 Reset Flag to 0 0 Modulo-N\* 1 Single Pass R 0 T8 Disabled \* R 1 T8 Enabled W 0 Stop T8 W 1 Enable T8

\* Default setting after reset.

\*\* Default setting after Reset. Not reset with a Stop Mode recovery

#### Figure 36. TC8 Control Register ((0D) 00H: Read/Write Except Where Noted)

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D7 D6 D5 D4 D3 D2 D1 D0	
	Transmit Mode* R/W 0 T16_OUT is 0 initially* 1 T16_OUT is 1 initially Capture Mode R 0 No Falling Edge Detection R 1 Falling Edge Detection W 0 No Effect W 1 Reset Flag to 0
	Transmit Mode* R/W 0 T8_OUT is 0 initially* 1 T8_OUT is 1 initially Capture Mode R 0 No Rising Edge Detection R 1 Rising Edge Detection W 0 No Effect W 1 Reset Flag to 0 Transmit Mode* 0 0 Normal Operation* 0 1 Ping-Pong Mode 1 0 T16_OUT = 0
	1 1 T16_OUT = 1 Capture Mode 0 0 No Filter 0 1 4 SCLK Cycle Filter 1 0 8 SCLK Cycle Filter 1 1 Reserved
	Transmit Mode/T8/T16 Logic 0 0 AND** 0 1 OR 1 0 NOR 1 1 NAND
	Capture Mode 0 0 Falling Edge Detection 0 1 Rising Edge Detection 1 0 Both Edge Detection 1 1 Reserved
	Transmit Mode 0 P36 as Port Output * 1 P36 as T8/T16_OUT Capture Mode
	0 P31 as Demodulator Input 1 P20 as Demodulator Input Transmit/Capture Mode
<ul> <li>* Default setting after reset.</li> <li>** Default setting after Reset. Not reset with a Stop Mode recovery.</li> </ul>	0 Transmit Mode * 1 Capture Mode

Figure 37. T8 and T16 Common Control Functions ((0D) 01H: Read/Write)





**Notes:** Take care in differentiating the Transmit Mode from Capture Mode. Depending on which of these two modes is operating, the CTR1 bit has different functions.

Changing from one mode to another cannot be performed without disabling the counter/timers.

CTR2 (0D) 02H

D7	D6	D5	D4	D3	D2	D1	D0	
								<ul> <li>0 P35 is Port Output *</li> <li>1 P35 is TC16 Output</li> <li>0 Disable T16 Timeout Interrupt*</li> <li>1 Enable T16 Timeout Interrupt</li> <li>0 Disable T16 Data Capture Interrupt**</li> <li>1 Enable T16 Data Capture Interrupt</li> <li>0 0 SCLK on T16 Timeout **</li> <li>0 No T16 Timeout **</li> <li>R 1 T16 Timeout Occurs</li> <li>W 0 No Effect</li> <li>W 1 Reset Flag to 0</li> </ul>
								Transmit Mode — 0 Modulo-N for T16* 1 Single Pass for T16 Capture Mode 0 T16 Recognizes Edge 1 T16 Does Not Recognize Edge
<ul> <li>* Default setting after reset.</li> <li>** Default setting after Reset. Not reset with a Stop Mode recovery.</li> </ul>						R 0 T16 Disabled * R 1 T16 Enabled W 0 Stop T16 W 1 Enable T16		



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# CTR3 (0D) 03H



#### Figure 39. T8/T16 control Register (0D) 03H: Read/Write (Except Where Noted)

**Note:** If Sync Mode is enabled, the first pulse of T8 (carrier) is always synchronized with T16 (demodulated signal). It can always provide a full carrier pulse.



#### LVD (0D) 0CH D3 D2 D7 D6 D5 D4 D1 D0 Voltage Detection 0: Disable \* 1: Enable LVD Flag (Read only) 0: LVD flag reset \* 1: LVD flag set HVD Flag (Read only) 0: HVD flag reset \* 1: HVD flag set Reserved (Must be 0) \* Default setting after reset.



# **Expanded Register File Control Registers (0F)**

The expanded register file control registers (0F) are depicted in Figures 41 through Figure 54.



# PCON (0F) 00H



\* Default setting after reset







# SMR (0F) 0BH



- \* Default setting after Reset
- \* \* Set after STOP Mode Recovery
- \* \* \* At the XOR gate input
- \* \* \* \* Default setting after reset. Must be 1 if using a crystal or resonator clock source. Not reset with a Stop Mode recovery.
- \* \* \* \* \* Default setting after Power On Reset

# Figure 42. Stop Mode Recovery Register ((0F) 0BH: D6–D0=Write Only, D7=Read Only)




Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

\* Default setting after reset. Not reset with a Stop Mode recovery.

\* \* At the XOR gate input

#### Figure 43. Stop Mode Recovery Register 2 ((0F) 0DH: D2–D4, D6 Write Only)



#### WDTMR (0F) 0FH D7 D6 D5 D4 D3 D2 D1 D0 WDT TAP INT RC OSC 00 10 ms min. 01 20 ms min.\* 10 40 ms min. 11 80 ms min. WDT During Halt 0 OFF 1 ON \* WDT During Stop 0 OFF 1 ON \* Reserved (Must be 0)

\* Default setting after reset. Not reset with a Stop Mode recovery.

Figure 44. Watch-Dog Timer Register ((0F) 0FH: Write Only)

## **Standard Control Registers**

#### R246 P2M (F6H)



\* Default setting after reset. Not reset with a Stop Mode recovery.

Figure 45. Port 2 Mode Register (F6H: Write Only)



# R247 P3M (F7H) D7 D6 D5 D4 D3 D2 D1 D0 O: Port 2 Open Drain \* 1: Port 2 Push-Pull 0= P31, P32 Digital Mode\* 1= P31, P32 Analog Mode Reserved (Must be 0)

\* Default setting after reset. Not reset with a Stop Mode recovery.

Figure 46. Port 3 Mode Register (F7H: Write Only)

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\* Default setting after reset; only P00, P01 and P07 are available on 20-pin configurations.

Figure 47. Port 0 Register (F8H: Write Only)





#### R249 IPR (F9H)



Figure 48. Interrupt Priority Register (F9H: Write Only)



#### R250 IRQ (FAH)





#### Figure 49. Interrupt Request Register (FAH: Read/Write)





\* Default setting after reset

\*\* Only by using EI, DI instruction; DI is required before changing the IMR register

Figure 50. Interrupt Mask Register (FBH: Read/Write)





Figure 51. Flag Register (FCH: Read/Write)



Default setting after reset = 0000 0000

Figure 52. Register Pointer (FDH: Read/Write)



D7	D6	D5	D4	D3	D2	D1	D0	
								General-Purpose Register

Figure 53. Stack Pointer High (FEH: Read/Write)

R255 SPL (FFH)

D7	D6	D5	D4	D3	D2	D1	D0

Stack Pointer Low Byte (SP7–SP0)

Figure 54. Stack Pointer Low (FFH: Read/Write)

## **Package Information**

Package information for all device versions of ZGR16300 is depicted in Figures 55 through Figure 60.







SYMBOL	MILLIN	IETER	INCH		
STMDUL	MIN	MAX	MIN	MAX	
A1	0.38	0.81	.015	.032	
A2	3.25	3.68	.128	.145	
В	0.41	0.51	.016	.020	
B1	1.47	1.57	.058	.062	
С	0.20	0.30	.008	.012	
D	25.65	26.16	1.010	1.030	
E	7.49	8.26	.295	.325	
E1	6.10	6.65	.240	.262	
e	2.54	BSC	.100	BSC	
eA	7.87	9.14	.310	.360	
L	3.18	3.43	.125	.135	
Q1	1.42	1.65	.056	.065	
S	1.52	1.65	.060	.065	



Figure 55. 20-Pin DIP Package Diagram



CONTROLLING DIMENSIONS : INCH



SYMBOL	MILLIN	METER	INCH		
STMBUL	MIN	MAX	MIN	MAX	
A	2.40	2.65	.094	.104	
A1	0.10	0.30	.004	.012	
A2	2.24	2.44	.088	.096	
В	0.36	0.46	.014	.018	
С	0.23	0.30	.009	.012	
D	12.60	12.95	.496	.510	
E	7.40	7.60	.291	.299	
e	1.27	1.27 BSC		BSC	
н	10.00	10.65	.394	.419	
h	0.30	0.40	.012	.016	
L	0.60	1.00	.024	.039	
Q1	0.97	1.07	.038	.042	

CONTROLLING DIMENSIONS : MM LEADS ARE COPLANAR WITHIN .004 INCH.







0141001		MILLIMETER			INCH	
SYMBOL	MIN	NOM	MAX	MIN	NOM	MAX
A	1.73	1.85	1.98	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.83	0.066	0.068	0.072
В	0.25	0.30	0.38	0.010	0.012	0.015
С	0.13	0.15	0.22	0.005	0.006	0.009
D	7.07	7.20	7.33	0.278	0.283	0.289
E	5.20	5.30	5.38	0.205	0.209	0.212
e		0.65 BSC		0.0256 BSC		
Н	7.65	7.80	7.90	0.301	0.307	0.311
L	0.56	0.75	0.94	0.022	0.030	0.037
Q1	0.74	0.78	0.82	0.029	0.031	0.032



CONTROLLING DIMENSIONS : MM LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 57. 20-Pin SSOP Package Diagram

0-8

DETAIL A

Н







Figure 58. 28-Pin SOIC Package Diagram





SYMBOL	OPT #	MILLIN	ETER	INCH		
OTMOOL	5	MIN	MAX	MIN	MAX	
A1		0.38	1.02	.015	.040	
A2		3.18	4.19	.125	.165	
В		0.38	0.53	.015	.021	
B1	01	1.40	1.65	.055	.065	
51	02	1.14	1.40	.045	.055	
С		0.23	0.38	.009	.015	
D	01	36.58	37.34	1.440	1.470	
5	02	35.31	35.94	1.390	1.415	
Е		15.24	15.75	.600	.620	
E1	01	13.59	14.10	.535	.555	
<b>L</b> 1	02	12.83	13.08	.505	.515	
e		2.54	TYP	.100	BSC	
eA		15.49	16.76	.610	.660	
L		3.05	3.81	.120	.150	
Q1	01	1.40	1.91	.055	.075	
- 121	02	1.40	1.78	.055	.070	
•	01	1.52	2.29	.060	.090	
S	02	1.02	1.52	.040	.060	



Note: ZILOG supplies both options for production. Component layout PCB design should cover bigger option 01.

Figure 59. 28-Pin DIP Package Diagram







		MILLIMETER	R		INCH	
SYMBOL	MIN	NOM	MAX	MIN	NOM	MAX
А	1.73	1.86	1.99	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.78	0.066	0.068	0.070
В	0.25		0.38	0.010		0.015
С	0.09	-	0.20	0.004	0.006	0.008
D	10.07	10.20	10.33	0.397	0.402	0.407
E	5.20	5.30	5.38	0.205	0.209	0.212
е		0.65 TYP			0.0256 TYF	>
Н	7.65	7.80	7.90	0.301	0.307	0.311
L	0.63	0.75	0.95	0.025	0.030	0.037

CONTROLLING DIMENSIONS: MM LEADS ARE COPLANAR WITHIN .004 INCHES.

DETAIL 'A'

#### Figure 60. 28-Pin SSOP Package Diagram

**Note:** Please check with ZiLOG<sup>®</sup> on the actual bonding diagram and coordinate for chip-on-board assembly.

## **Ordering Information**

>

The following table provides ordering information for the ZLR16300 16K, 8K, 4K, 2K, and 1K parts.



Memory Size	Part No.	Description
16K	ZLR16300H2816C	28-pin SSOP 16K ROM
	ZLR16300P2816C	28-pin PDIP 16K ROM
	ZLR16300S2816C	28-pin SOIC 16K ROM
	ZLR16300H2016C	20-pin SSOP 16K ROM
	ZLR16300P2016C	20-pin PDIP 16K ROM
	ZLR16300S2016C	20-pin SOIC 16K ROM
8K	ZLR16300H2808C	28-pin SSOP 8K ROM
	ZLR16300P2808C	28-pin PDIP 8K ROM
	ZLR16300S2808C	28-pin SOIC 8K ROM
	ZLR16300H2008C	20-pin SSOP 8K ROM
	ZLR16300P2008C	20-pin PDIP 8K ROM
	ZLR16300S2008C	20-pin SOIC 8K ROM
4K	ZLR16300H2804C	28-pin SSOP 4K ROM
	ZLR16300P2804C	28-pin PDIP 4K ROM
	ZLR16300S2804C	28-pin SOIC 4K ROM
	ZLR16300H2004C	20-pin SSOP 4K ROM
	ZLR16300P2004C	20-pin PDIP 4K ROM
	ZLR16300S2004C	20-pin SOIC 4K ROM
2K	ZLR16300H2802C	28-pin SSOP 2K ROM
	ZLR16300P2802C	28-pin PDIP 2K ROM
	ZLR16300S2802C	28-pin SOIC 2K ROM
	ZLR16300H2002C	20-pin SSOP 2K ROM
	ZLR16300P2002C	20-pin PDIP 2K ROM
	ZLR16300S2002C	20-pin SOIC 2K ROM
1K	ZLR16300H2801C	28-pin SSOP 1K ROM
	ZLR16300P2801C	28-pin PDIP 1K ROM
	ZLR16300S2801C	28-pin SOIC 1K ROM
	ZLR16300H2001C	20-pin SSOP 1K ROM
	ZLR16300P2001C	20-pin PDIP 1K ROM
	ZLR16300S2001C	20-pin SOIC 1K ROM
	ZLP32300100KIT	Development System

#### Note:

Replace C with G for Lead-Free Packaging.
 Contact <u>www.zilog.com</u> for the die form.

ZLP323ICE01ZEM

Emulator



For fast results, contact your local ZiLOG sales office for assistance in ordering the part desired.

#### Codes

ZL = ZiLOG Low Voltage Family

R = ROM

16300 = Family Designation

- P = Package Type:
- H = SSOP
- P = Plastic DIP
- S = SOIC
- ## = Number of Pins
- CC = Memory Size

X = Molding Compound

#### Example





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