Monolithic Digital IC PWM Current Control Stepping Motor Driver



Overview

The LB11946 is a stepping motor driver IC that implements PWM current control bipolar drive with a fixed off time. This IC features 15 current setting levels using a fixed VREF voltage and support for micro-stepping drive from 1-2 phase excitation drive to 4W1-2 phase excitation drive. This device is optimal for driving stepping motors such as those used for carriage drive and paper feed in printers.

Features

- PWM current control (with a fixed off time)
- Logic input serial-parallel converter (allows 1-2, W1-2, 2W1-2, and 4W1-2 phase excitation drive)
- Current attenuation switching function (with slow decay, fast decay, and mixed decay modes)
- Built-in upper and lower side diodes
- Simultaneous on state prevention function (through current prevention)
- Noise canceller function
- Thermal shutdown circuit
- Shutoff on low logic system voltage circuit
- Low-power mode control pin

Specifications

Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	V _{BB}		50	V
Peak output current	I _O peak	$tw \le 20\mu S$	1.2	А
Continuous output current	I _O max		1.0	А
Logic system supply voltage	V _{CC}		7.0	V
Logic input voltage range	VIN		-0.3 to V _{CC}	V
Emitter output voltage	VE	V _{CC} = 5V specifications	1.0	V
		V _{CC} = 3.3V specifications	0.5	V
Allowable power dissipation	Pd max	Independent IC	3.0	W
Operating temperature	Topr		-25 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Recommended Operating Conditions at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	V _{BB}		10 to 45	V
Logic system supply voltage	VCC	V _{CC} = 5V specifications	4.5 to 5.5	V
		V _{CC} = 3.3V specifications	3.0 to 3.6	V
Reference voltage	VREF	V _{CC} = 5V specifications	0.0 to 3.0	V
		V _{CC} = 3.3V specifications	0.0 to 1.0	V

Electrical Characteristics at $Ta = 25^{\circ}C$, $V_{CC} = 5V$, $V_{BB} = 42V$, VREF = 1.52V

Parameter	Symbol	Conditions		Ratings		Unit
i didiliotor			min	typ	max	Olin
Output Block						1
Output stage supply current	I _{BB} ON		0.9	1.3	1.7	mA
	IBB OFF		0.52	0.7	1.05	mA
Output saturation voltage	V _O (sat) 1	I _O = +0.5A (sink)		1.1	1.4	V
	V _O (sat) 2	I _O = +1.0A (sink)		1.4	1.7	V
	V _O (sat) 3	I _O = -0.5A (source)		1.9	2.2	V
	V _O (sat) 4	I _O = -1.0A (source)		2.2	2.5	V
Output leakage current	I _O 1 (leak)	$V_{O} = V_{BB}$ (sink)			50	μΑ
	I _O 2 (leak)	V _O = 0V (source)	-50			μA
Output sustain voltage	V _{SUS}	L = 15mH, I_O = 1.0A, Design guarantee *	45			V
Logic Block						
Logic system supply current	I _{CC} ON	D0 = 1, D1 = 1, D2 = 1, D3 = 1 When these data values are set	24	35	46	mA
	ICC OFF1	D0 = 0, D1 = 0, D2 = 0, D3 = 0	22	32	42	mA
	I _{CC} OFF2	ST = LOW		0.05	0.1	mA
Input voltage	VIH		2			V
	VIL				0.8	V
Input current	Iн	V _{IH} = 2 V			35	μΑ
	۱ _{IL}	V _{IL} = 0.8 V	6			μΑ
Sense voltages	VE	D0 = 1, $D1 = 1$, $D2 = 1$, $D3 = 1$ When these data values are set	0.470	0.50	0.525	V
		D0 = 1, D1 = 1, D2 = 1, D3 = 0	0.445	0.48	0.505	V
		D0 = 1, D1 = 1, D2 = 0, D3 = 1	0.425	0.46	0.485	V
		D0 = 1, D1 = 1, D2 = 0, D3 = 0	0.410	0.43	0.465	V
		D0 = 1, D1 = 0, D2 = 1, D3 = 1	0.385	0.41	0.435	V
		D0 = 1, D1 = 0, D2 = 1, D3 = 0	0.365	0.39	0.415	V
		D0 = 1, D1 = 0, D2 = 0, D3 = 1	0.345	0.37	0.385	V
		D0 = 1, D1 = 0, D2 = 0, D3 = 0	0.325	0.35	0.365	V
		D0 = 0, D1 = 1, D2 = 1, D3 = 1	0.280	0.30	0.325	V
		D0 = 0, D1 = 1, D2 = 1, D3 = 0	0.240	0.26	0.285	V
		D0 = 0, D1 = 1, D2 = 0, D3 = 1	0.195	0.22	0.235	V
		D0 = 0, D1 = 1, D2 = 0, D3 = 0	0.155	0.17	0.190	V
		D0 = 0, D1 = 0, D2 = 1, D3 = 1	0.115	0.13	0.145	V
		D0 = 0, D1 = 0, D2 = 1, D3 = 0	0.075	0.09	0.100	V
Reference current	IREF	VREF = 1.5V	-0.5			μA
CR pin current	ICR	CR = 1.0V	-1.6	-1.2	-0.8	mA
MD pin current	IMD	MD = 1.0V, CR = 4.0V	-5.0			μA
Logic system on voltage	V _{LSD} ON		2.6	2.8	3.0	V
Logic system off voltage	V _{LSD} OFF		2.45	2.65	2.85	V
LVSD hysteresis	VLHIS		0.03	0.15	0.35	V
Thermal shutdown temperature	Ts	Design guarantee *		170		°C

*Design guarantee: Design guarantee value, Do not measurement.

AC Electrical Characteristics at $V_{CC} = 5V$

Doromotor	Cumbol	Conditions	Ratings			Unit
Parameter	Symbol Conditions		min	typ	max	Unit
Clock frequency	Fclk			200	550	kHz
Data setup time	TDS		0.9	2.5		μS
Data hold time	TDH		0.9	2.5		μS
Minimum clock high-level pulse width	TSCH		0.9	2.5		μS
Minimum clock low-level pulse width	TSCL		0.9	2.5		μS
SET pin stipulated time	Tlat		0.9	2.5		μS
SET pin signal pulse width	Tlatw		1.9	5.0		μS



Electrical Characteristics at Ta = 25°C, V_{CC} = 3.3V, V_{BB} = 42V, V_{REF} = 1.0V

(When measuring	the sense voltage:	VREF = 1.03V)

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Descurator	Symbol Conditions			Ratings		1.1 14
Parameter			min	typ	max	Unit
Output Block				·		
Output stage supply current	I _{BB} ON		0.9	1.3	1.7	mA
	I _{BB} OFF		0.52	0.7	1.05	mA
Output saturation voltage	V _O (sat) 1	I _O = +0.5A (sink)		1.2	1.5	V
	V _O (sat) 2	$I_{O} = +1.0A \text{ (sink)}$		1.5	1.8	V
	V _O (sat) 3	I _O = -0.5A (source)		2.0	2.3	V
	V _O (sat) 4	I _O = -1.0A (source)		2.3	2.6	V
Output leakage current	I _O 1 (leak)	$V_{O} = V_{BB}$ (sink)			50	μA
	I _O 2 (leak)	V _O = 0V (source)	-50			μA
Output sustain voltage	V _{SUS}	L = 15mH I _O -1.5A, Design guarantee *	45			V
Logic Block	1		1 1			
Logic system supply current	I _{CC} ON	D0 = 1, D1 = 1, D2 = 1, D3 = 1	21	30	39	mA
		When these data values are set	40	00	00 F	
	I _{CC} OFF1	D0 = 0, D1 = 0, D2 = 0, D3 = 0	19	28	36.5	mA
1	I _{CC} OFF2	ST = 0.8V		0.03	0.1	mA
Input voltage	VIH		2		0.0	V
	V _{IL}				0.8	V
Input current	IIH	V _{IH} = 2V			35	μA
	<u>IIL</u>	V _{IL} = 0.8V	6			μA
Sense voltages	VE	D0 = 1, D1 = 1, D2 = 1, D3 = 1 VREF = 1.03V	0.303	0.330	0.356	V
		D0 = 1, D1 = 1, D2 = 1, D3 = 0 VREF = 1.03V	0.290	0.315	0.341	V
		D0 = 1, D1 = 1, D2 = 0, D3 = 1 VREF = 1.03V	0.276	0.300	0.324	V
		D0 = 1, D1 = 1, D2 = 0, D3 = 0 VREF = 1.03V	0.263	0.286	0.309	V
		D0 = 1, D1 = 0, D2 = 1, D3 = 1 VREF = 1.03V	0.250	0.272	0.294	V
		D0 = 1, D1 = 0, D2 = 1, D3 = 0 VREF = 1.03V	0.236	0.257	0.278	V
		D0 = 1, D1 = 0, D2 = 0, D3 = 1 VREF = 1.03V	0.223	0.243	0.263	V
		D0 = 1, D1 = 0, D2 = 0, D3 = 0 VREF = 1.03V	0.209	0.228	0.247	V
		D0 = 0, D1 = 1, D2 = 1, D3 = 1 VREF = 1.03V	0.183	0.200	0.217	V
		D0 = 0, D1 = 1, D2 = 1, D3 = 0 VREF = 1.03V	0.155	0.170	0.185	V
		D0 = 0, D1 = 1, D2 = 0, D3 = 1 VREF = 1.03V	0.128	0.143	0.158	V
		D0 = 0, D1 = 1, D2 = 0, D3 = 0 VREF = 1.03V	0.102	0.114	0.126	V
		D0 = 0, D1 = 0, D2 = 1, D3 = 1 VREF = 1.03V	0.074	0.085	0.096	V
		D0 = 0, D1 = 0, D2 = 1, D3 = 0 VREF = 1.03V	0.047	0.057	0.067	V
Reference current	IREF	VREF = 1.0V	-0.5			μA
CR pin current	ICR	CR = 1.0V	-0.91	-0.7	-0.49	mA
MD pin current	IMD	MD = 1.0V, CR = 4.0V	-5.0			μΑ
LVSD voltage	V _{LSD} ON		2.6	2.8	3.0	V
Logic system off voltage	V _{LSD} OFF		2.45	2.65	2.85	V
LVSD hysteresis	VLHIS		0.03	0.15	0.35	V
Thermal shutdown temperature	Ts	Design guarantee *	1 1	170		°C

*Design guarantee: Design guarantee value, Do not measurement.

AC Electrical Characteristics at $V_{CC} = 3.3V$

Doromotor	Sumbol	Conditions	Ratings			Unit
Parameter	Symbol Conditions		min	typ	max	Unit
Clock frequency	Fclk			200	550	kHz
Data setup time	TDS		0.9	2.5		μS
Data hold time	TDH		0.9	2.5		μS
Minimum clock high-level pulse width	TSCH		0.9	2.5		μS
Minimum clock low-level pulse width	TSCL		0.9	2.5		μS
SET pin stipulated time	Tlat		0.9	2.5		μS
SET pin signal pulse width	Tlatw		1.9	5.0		μS



Package Dimensions

unit : mm (typ) 3147C

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11 BONDB-D Note: The D-GNDA and D-GNDB pins are the anode sides of the lower side diodes

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Timing Chart



Serially Transferred Data Definition

	IA4	IA3	IA2	IA1	DE1	PH1	IB4	IB3	IB2	IB1	DE2	PH2		Output	t mode		I/O	DEC
No.	D0	D1	D2	D3	D4	D5	D6	D7	D8	D9	D10	D11	OUTA	OUTA	OUTB	$OUT\overline{B}$	ratio	MODE
0	1	1	1	1	1	1	1	1	1	1	1	1	Н	L	Н	L	100%	SLOW
1	1	1	1	0	1	1	1	1	1	0	1	1	Н	L	Н	L	96	SLOW
2	1	1	0	1	1	1	1	1	0	1	1	1	Н	L	Н	L	91	SLOW
3	1	1	0	0	1	1	1	1	0	0	1	1	Н	L	Н	L	87	SLOW
4	1	0	1	1	1	1	1	0	1	1	1	1	Н	L	Н	L	83	SLOW
5	1	0	1	0	1	1	1	0	1	0	1	1	Н	L	Н	L	78	SLOW
6	1	0	0	1	1	1	1	0	0	1	1	1	Н	L	Н	L	74	SLOW
7	1	0	0	0	1	1	1	0	0	0	1	1	Н	L	Н	L	70	SLOW
8	0	1	1	1	1	1	0	1	1	1	1	1	Н	L	Н	L	61	SLOW
9	0	1	1	0	1	1	0	1	1	0	1	1	Н	L	Н	L	52	SLOW
10	0	1	0	1	1	1	0	1	0	1	1	1	Н	L	Н	L	44	SLOW
11	0	1	0	0	1	1	0	1	0	0	1	1	Н	L	Н	L	35	SLOW
12	0	0	1	1	1	1	0	0	1	1	1	1	Н	L	Н	L	26	SLOW
13	0	0	1	0	1	1	0	0	1	0	1	1	Н	L	Н	L	17	SLOW
14	1	1	1	1	0	0	1	1	1	1	0	0	L	Н	L	Н	100	FAST
15	1	1	1	0	0	0	1	1	1	0	0	0	L	Н	L	Н	96	FAST
16	1	1	0	1	0	0	1	1	0	1	0	0	L	Н	L	Н	91	FAST
17	1	1	0	0	0	0	1	1	0	0	0	0	L	Н	L	Н	87	FAST
18	1	0	1	1	0	0	1	0	1	1	0	0	L	Н	L	Н	83	FAST
19	1	0	1	0	0	0	1	0	1	0	0	0	L	Н	L	Н	78	FAST
20	1	0	0	1	0	0	1	0	0	1	0	0	L	Н	L	Н	74	FAST
21	1	0	0	0	0	0	1	0	0	0	0	0	L	Н	L	Н	70	FAST
22	0	1	1	1	0	0	0	1	1	1	0	0	L	Н	L	Н	61	FAST
23	0	1	1	0	0	0	0	1	1	0	0	0	L	Н	L	Н	52	FAST
24	0	1	0	1	0	0	0	1	0	1	0	0	L	Н	L	Н	44	FAST
25	0	1	0	0	0	0	0	1	0	0	0	0	L	Н	L	Н	35	FAST
26	0	0	1	1	0	0	0	0	1	1	0	0	L	Н	L	Н	26	FAST
27	0	0	1	0	0	0	0	0	1	0	0	0	L	Н	L	Н	17	FAST
28	0	0	0	0	*	*	0	0	0	0	*	*	OFF	OFF	OFF	OFF	0	-

Note *: Either 0 or 1.

Note *1: In mixed decay mode, set D4 and D10 to 0 and set the MD pin to a level in the range 1.5 to 4.0V.

Current Settings Truth Table * Iter	ns in parentheses ar	re defined by the serial data.
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IA4	IA3	IA2	IA1	Set current lout	Current ratio (%)
(D0)	(D1)	(D2)	(D3)		
1	1	1	1	11.5/11.5 × VREF/3.04RE = lout	100
1	1	1	0	11.0/11.5 × VREF/3.04RE = lout	95.65
1	1	0	1	10.5/11.5 × VREF/3.04RE = lout	91.30
1	1	0	0	10.0/11.5 × VREF/3.04RE = lout	86.95
1	0	1	1	9.5/11.5 × VREF/3.04RE = lout	82.61
1	0	1	0	9.0/11.5 × VREF/3.04RE = lout	78.26
1	0	0	1	8.5/11.5 × VREF/3.04RE = lout	73.91
1	0	0	0	8.0/11.5 × VREF/3.04RE = lout	69.56
0	1	1	1	7.0/11.5 × VREF/3.04RE = lout	60.87
0	1	1	0	6.0/11.5 × VREF/3.04RE = lout	52.17
0	1	0	1	5.0/11.5 × VREF/3.04RE = lout	43.48
0	1	0	0	4.0/11.5 × VREF/3.04RE = lout	34.78
0	0	1	1	3.0/11.5 × VREF/3.04RE = lout	26.08
0	0	1	0	2.0/11.5 × Vref/3.04RE = lout	17.39

Note: The current ratios shown are calculated values.

Block Diagram



Sample Application Circuit at $V_{CC} = 5V$



Sample Application Circuit at $V_{CC} = 3.3V$



SLOW DECAY Current Path

The reregenerative current at upper-side transistor switching operates



Fig.1

FAST DECAY Current Path



Fig.2

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3.04







The following operation by comparison between CR voltage and MD pin voltage in turning off time. CR voltage > MD pin voltage: both sides chopping CR voltage < MD pin voltage: upper side chopping

Attached Documents

1. Switching Off Time and Noise Canceller Time Calculations Notes on the CR Pin Setting (switching off time and noise canceller time)

The noise canceller time (Tn) and the switching off time (Toff) are set using the following formulas. (1) When V_{CC} is 5 V

Noise canceller time (Tn) Tn \approx C \times R \times ln {(1.5 - RI) / (4.0 - RI)}[s]

Switching off time (Toff) Toff $\approx -C \times R \times \ln (1.5/4.8)[s]$ CR pin charge current: 1.25mA

Component value ranges R: $5.6k\Omega$ to $100k\Omega$ C: 470pF to 2000pF

(2) When V_{CC} is 3.3 V Noise canceller time (Tn) $Tn \approx C \times R \times ln \{(1.06 - RI) / (2.66 - RI)\}[s]$

CR pin charge current: 0.7 mA

Switching off time (Toff) Toff $\approx -C \times R \times \ln (1.06 / 3.1)[s]$

CR Pin Internal Circuit Structure



2. Notes on the MD Pin

- (1) If slow decay mode is set up by setting the D4 and D10 bits in the input serial data to 1, the MD pin must be shorted to ground.
- (2) If fast decay mode is set up by setting the D4 and D10 bits in the input serial data to 0, mixed decay mode can be set with the MD pin.

When the $V_{CC} = 5V$ specifications are used the setting voltage range for mixed decay mode is 1.6 to 3.9V.

When the $V_{CC} = 3.3V$ specifications are used the setting voltage range for mixed decay mode is 1.2 to 2.5V.

If mixed decay mode will not be used with the fast decay mode setting, either:

(a) Short the MD pin to ground to select fast decay mode, or

(b) Short the MD pin to V_{CC} to select slow decay mode.

Usage Notes

(1) Notes on the VREF pin

Since the VREF pin inputs the reference voltage used to set the current, applications must be designed so that noise does not occur at this pin.

(2) Notes on the ground pins

Since this IC switches large currents, care is required with respect to the ground pins.

The PCB pattern in sections where large currents flow must be designed with low impedances and must be kept separate from the small-signal system.

In particular, the ground terminals of the E1 and E2 pin sense resistors (Re) and the external Schottky barrier diode ground terminals must be located as close as possible to the IC ground. The capacitors between V_{CC} and ground and between V_{BB} and ground must be as close as possible to the corresponding V_{CC} and V_{BB} pin in the pattern.

(3) Power on sequence

When turning the power systems on $V_{CC} \rightarrow$ logic level inputs (CLK, DATA, SET, and ST) \rightarrow VREF \rightarrow V_{BB}

When turning the power systems off

 $V_{BB} \rightarrow VREF$ logic level inputs (CLK, DATA, SET, and ST) $\rightarrow V_{CC}$

Note that if the power supply for the logic level inputs is on when the V_{CC} power supply is off, a bias with an unstable state will be applied due to the protection diodes at the V_{CC} pins, and this can cause incorrect operation.

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